ORIENTAL MOTOR

NEW Motorized Sliders/Cylinders

*Introducing **EZ limo**, the New Linear-Motion System That's Much Easier to Use*

EZ limo
easy linear motion

EZ limo
easy linear motion

EZ limo

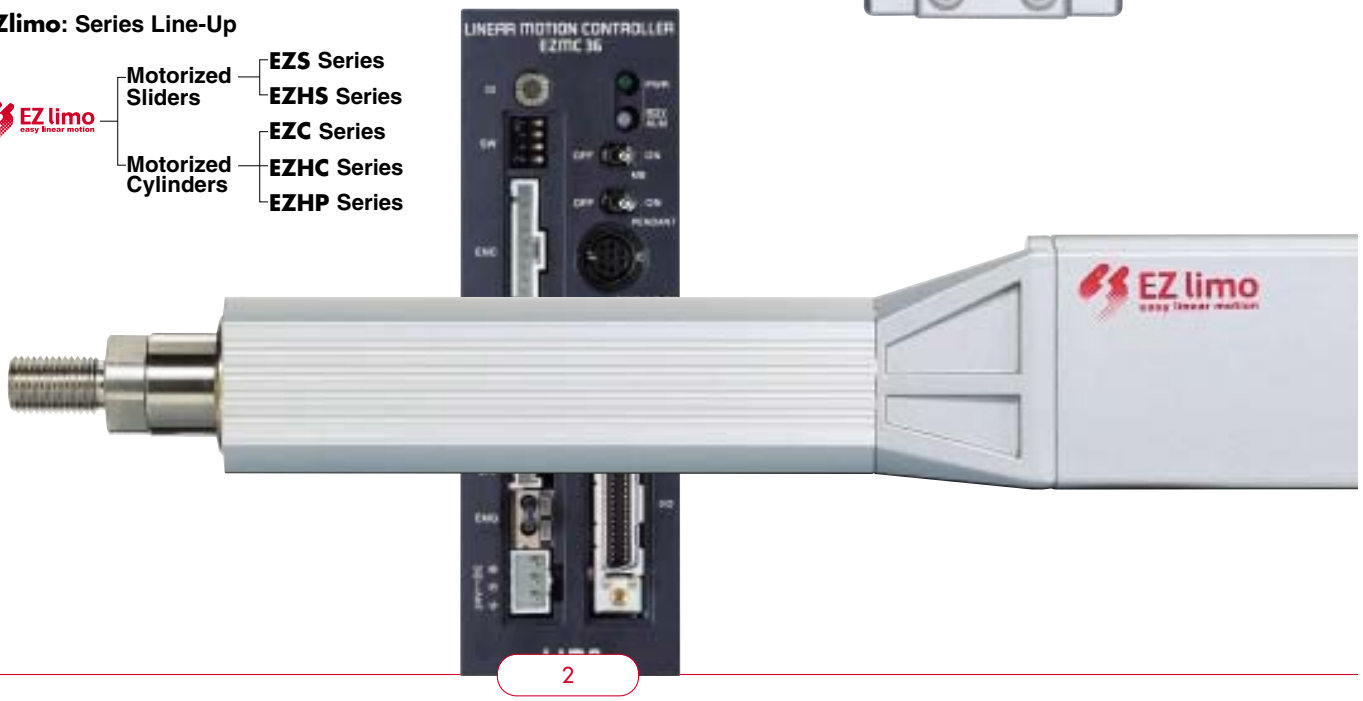
Easy to use linear motion

*Oriental Motor began by thinking from the user's point of view and a commitment to do whatever it takes to achieve what our users have requested. Oriental Motor then combined a number of advanced functions needed to obtain the high level of easy to use functionality that the **EZ limo** series includes today. Oriental Motor also worked to create a visual design that has never been seen in a factory automation environment. Based on the principles of making a product that was both easy to use and pleasing to look at, Oriental Motor is pleased to introduce the **EZ limo** series of linear motion products.*

Easy to Use

EZlimo: Series Line-Up

- EZ limo
  - Motorized Sliders
    - **EZS** Series
    - **EZHS** Series
  - Motorized Cylinders
    - **EZC** Series
    - **EZHC** Series
    - **EZHP** Series



Index

LIMO

Features	4~5
Functions	6~9
Selection	10~11
Line-Up • Conformance with EC Directives	12~15
System Configuration	16~19
Motorized Sliders	20~35
Motorized Cylinders	36~51
Controller	52~55
Connection Diagrams	56~61
Installation	62~64
Optional Parts	65~73
Linear Motion Products	74~75

Employing Ideals that are Distinctive to Oriental Motor

EZ limo is a linear-motion system that combines Oriental Motor's pledge of "ultimate user-friendliness", "utilization of the latest motor technology", "pursuit of mechanical design excellence" and "consideration for safety and the environment".

Motorized Sliders

EZS Series
EZHS Series Fastest

Motorized Cylinders

EZC Series
EZHC Series Fastest
EZHP Series Highest Thrust

Useful

Ultimate User-Friendliness

●Offering a Wide Range of Utilities

Up to 63 motion profiles can be set. The system provides a full range of utilities such as a teaching function, push function, area output function, selection of home detection modes and absolute feedback type. **EZ limo** also supports external pulse input, which means you can combine your existing controller with the **EZ limo** system.

●Pleasant, User-Friendly Operation

An optional teaching pendant facilitates data setting and operation. The LCD monitor is easy to see, and the user-friendly controls ensure pleasant, trouble-free operation.

You can set or edit various data on your personal computer using optional data editing software.

Technical

Incorporating Proprietary Technologies from Oriental Motor, an Industry Leader

●New Closed-Loop Control

The motor part houses a stepping motor only on **EZ** series change to "with a position feedback device". When a condition presenting the possibility of a misstep is detected, the motor performs closed-loop control, thereby ensuring stable operation.

●Prevention of Hunting at Standstill

Unlike other conventional servomotors, the motor used in the **EZ limo** system is free from hunting.

●Low Vibration/Low Noise Even During Low-Speed Operation

The new **EZHS**/**EZHC**/**EZHP** series adopts a software-based smooth drive control to suppress vibration and noise even during low-speed operation, such as the return-to-home operation.

Mechanical

Pursuit of Mechanical Design Excellence

●Easy Combination of Multiple Axes

If necessary, such as when palletizing the work, two axes can be combined using an optional dual axis mounting bracket. X-Y configuration (4 patterns) and X-Z configuration (4 patterns) can be implemented with ease.

Installation example:
X-Y configuration

Installation example:
X-Z configuration

●Maintenance-Free for Long-Term Performance

The drive mechanism uses THK's ball screw, while the guide mechanism adopts THK's LM Guide®.
The ball screw employs the QZ™ lubrication system, while the LM Guide® uses the Ball Retainer® to retain the coupled rolling elements. These mechanisms give the system a considerable duration of maintenance-free performance.

∗QZ™ lubrication system (THK): High-density fiber net supplies appropriate amounts of oil, thereby preventing oil wastage and reducing environmental burden.
∗Ball Retainer®(THK): Individual balls are retained in a manner allowing smooth rotation while preventing contact with adjacent balls. Use of the Ball Retainer® provides long-term, maintenance-free operating conditions and other benefits.
* Ball Retainer and LM Guide are registered trademarks of THK Co., Ltd.

●Thin, Compact Slider

The slider is only 31.5 mm high (**EZS4**·**EZHS4**). The ultra thin body helps save space at the installation site.

Safety

Consideration for Safety and the Environment

●Environmentally Friendly

The **EZ limo** system is constructed from carefully selected parts that exert a minimum burden on the environment.

●CE Marking

All **EZ limo** products bear the CE mark to indicate their conformance with the Low-Voltage and EMC directives.

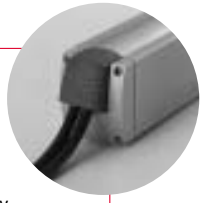
* See “Conformance with EC Directives” on p.13 & p.15 for details.

EZ limo : The Ultimate Combination of User-Friendliness, High Reliability and High Functionality

Common

Space-Saving Cable Outlet Orientation

The cable outlet is facing downward, which contributes to the overall space savings by reducing the space needed to wire the cables.



EZS EZHS

Positioning Pinholes on the Table

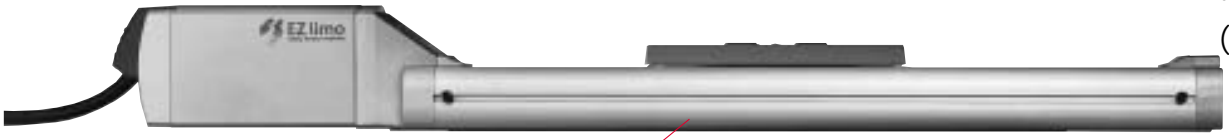
These holes help maintain positional repeatability when the work must be removed and then installed again for the purpose of maintenance, etc.

EZS EZHS

Stainless Sheet

The mechanical parts of the slider are covered with a stainless sheet to keep out foreign particles.

(The stainless sheet is also available as a spare part.)



Slider height
31.5 mm
(EZS4
EZHS4)

Common

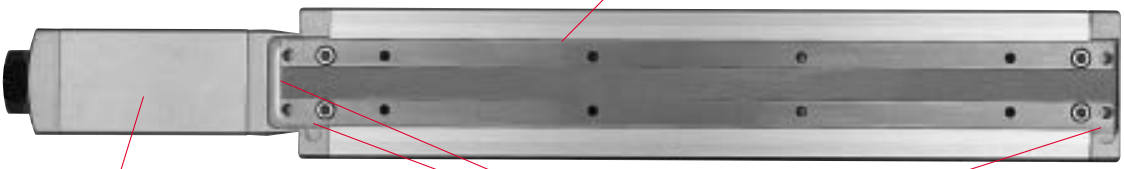
Drive method : THK's ball screw

(The QZ™ lubrication system provides a considerable duration of maintenance-free performance.)

EZS EZHS

Guide mechanism: THK's LM Guide®

(Ball Retainer® provides long-term, maintenance-free operating conditions.)



Common

Easy Connection

A connector provides a simple, one-touch connection to the controller.

A power cable is also supplied for ease of connection.

EZS EZHS

Mounting Reference Surface

These surfaces help maintain positional repeatability when the slider must be removed and then installed again for the purpose of maintenance, etc.

Common

Easy Installation

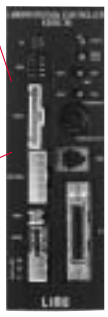
Both the mechanical parts and controller can be installed easily.

Slider: The slider body can be affixed directly from the top and bottom with screws. (**EZS3** and **EZHS3** can be affixed only from the bottom.)

Cylinder: The cylinder can be installed through the dedicated mounting holes, or via a flange connection using an optional mounting bracket.

Controller: The **EZS**/**EZC** series controllers can be installed with mounting screws or using a DIN rail. The **EZHS**/**EZHC**/**EZHP** series controllers come with dedicated mounting brackets.

* See p.62 to p.64 for details on the installation.



Common

Real-Time Monitoring

Information such as set data, current position and I/O status can be monitored in real time using an optional teaching pendant (sold separately).

■ Choice of Incremental Type or Absolute Type Feedback

Common

As long as power is supplied, the **EZ limo** system can proceed to the next operation without executing home detection, even given the occurrence of an overload or emergency stop error.

Choose the incremental type if you want to execute home detection each time the power is turned on. The absolute type would be your choice if you want to start operation from the current position rather than the home position, when the power is turned on.

Absolute Type

The absolute type allows the movement of the table or rod to be followed and backed up, even when the power is cut off.

●EZS/EZC Series

Two types of backup modes are available. Select the mode that best suits your application.

Standard backup — **Provides a longer backup period**
Optional backup — **Provides better speed-follow-up capability**

●EZHS/EZHC/EZHP Series

These models provide a long backup period of around 15 days (approx. 360 hours).

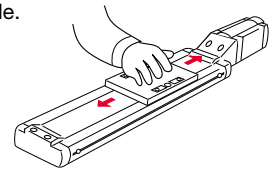
■ Teaching Function

Common

You can move the table to a desired position manually or by using the teaching pendant and store that position.

●Direct Teaching:

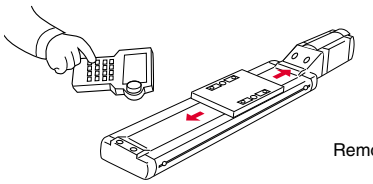
Turn off the excitation of the motor and move the table or rod manually to the target position, then store the data of that position in the motion profile.



Direct teaching

●Remote Teaching:

Use the keys on the teaching pendant to move the table or rod to the target position, then store the data of that position in the motion profile.



Remote teaching

■ Choice of Home Detection Methods

Common

You can choose the sensorless mode if you want to simplify the mechanical layout, or the sensor mode if you want to use sensors to detect home.

●Sensorless Home Detection

Home detection is performed without the use of a home sensor. The home position can be adjusted. For the sliders, the direction of home detection can also be changed.

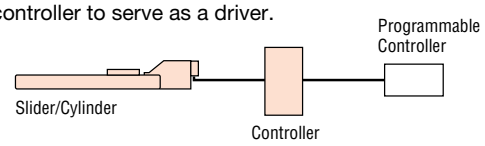
●Home Detection Using Sensors

Home detection is performed using home sensors. The sensors are available as options.
(See p. 68 for the sensor set.)

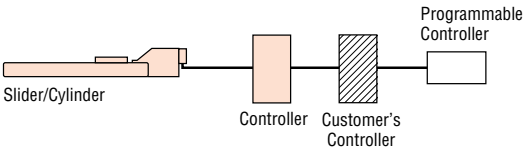
■ Operation Using External Pulse Input

Common

The **EZ limo** can be combined with your existing controller to serve as a driver.



Normal System Configuration [Controller Mode]



When Combined with the Customer's Controller [Driver Mode]

	Controller Mode	Driver Mode
Push Function	●	×
Teaching Function	●	×
Monitoring Function	●	×
Pause Function *1	●	×
Area Output Function	●	×
Absolute Type	●	●*2
Sensorless Home Detection	●	×

●=Available ×=Not available

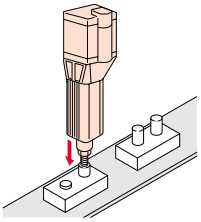
Notes:
●Certain functions cannot be used in the driver mode.
●Provide HOME, +LS and –LS sensors (optional) and connect them to the controller you want to use.

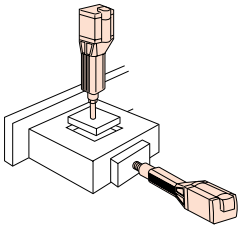
*1 Only for **EZS** and **EZC** Series
*2 Only for **EZHS** , **EZHC** and **EZHP** Series

■ Push Function

EZC EZHC EZHP

The rod can be held in a state of being pushed against the work or similar object, as with an air cylinder.
The force used to push the work (push force) can be changed. The **EZHC/EZHP** series handles up to 63 push width/force profiles.

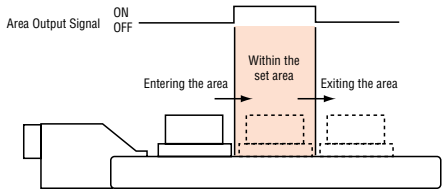


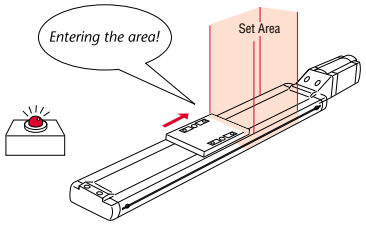


■ Area Output Function

Common

A signal is output when the slider table or cylinder rod enters a set range during operation.

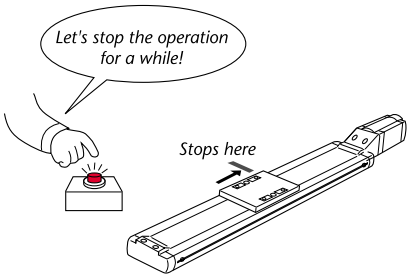




■ Pause Function

EZS EZC

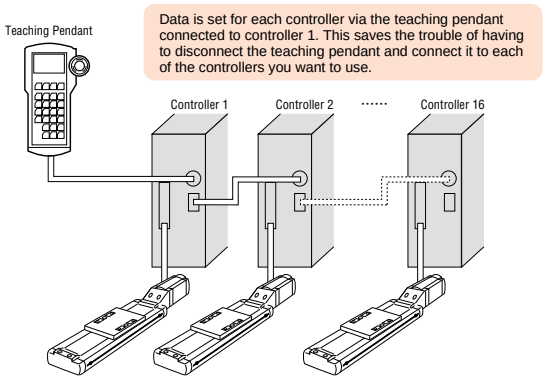
The slider/cylinder can be stopped temporarily during operation, using an external signal.
When the pause input signal (PAUSE) is turned ON, the slider/cylinder decelerates to a stop. When the START signal is turned ON again after the (PAUSE) signal is turned OFF, the slider/cylinder resumes operation from the position at which it had stopped.



■ Connection of Multiple Axes

Common

A maximum of 16 controllers can be connected, with data set separately for each of the controllers. There is no need to connect the teaching pendant to each of the controllers.

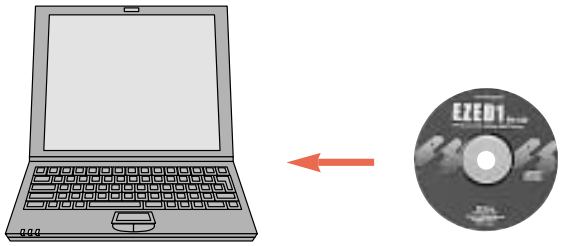

Teaching Pendant
Data is set for each controller via the teaching pendant connected to controller 1. This saves the trouble of having to disconnect the teaching pendant and connect it to each of the controllers you want to use.
Controller 1
Controller 2
Controller 16

■ Easy Data Editing

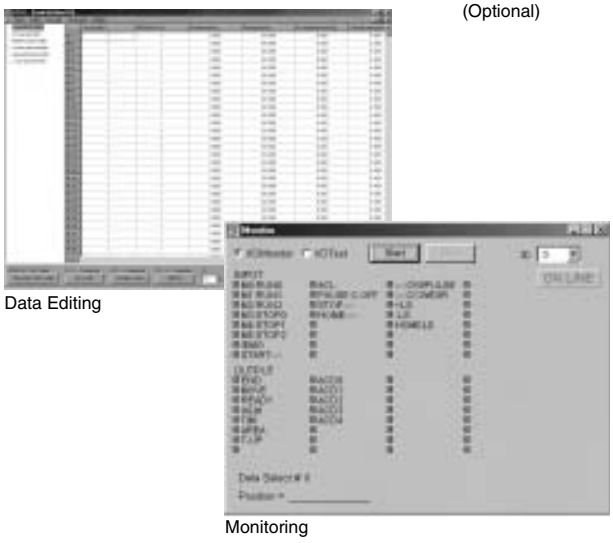
EZS EZC

You can set and edit various data on a personal computer (PC) using the optional data editing software. The software comes with a PC interface cable (five meters in length) used to connect the controller and PC. The software also provides various monitoring functions.

✻ See p.16 and p.65 for details.



Data Editing Software (Optional)



Data Editing

Monitoring

■ Multifunction Controller (Stored-Data Type)

●A Maximum of 63 Motion Profiles

Common

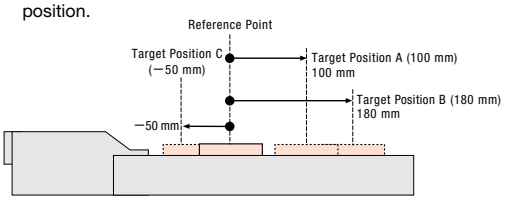
Up to 63 motion profiles can be set by the controller.

●Two Motion Profiles Setting Modes: Absolute Mode and Incremental Mode

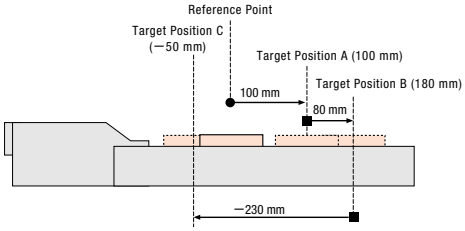
Common

You can set motion profile in the absolute mode or incremental mode, depending on your preferred movement of the equipment.

Absolute Mode (Absolute-Position Specification) :
Each position is set as the absolute position with respect to the reference point. This is suitable when you want to move the work directly from an arbitrary position to the specified position.



Incremental Mode (Relative-Position Specification) :
Each position is relative, being set as an amount of travel from the current position or another target position for the work. This is suitable in a regular feed or other operation where the same pattern is used repeatedly.



●Simple Unit Setting Common

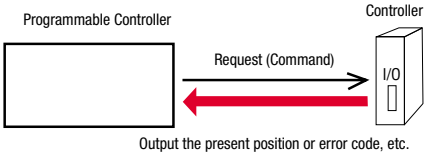
Travel amount, operating speed and acceleration/deceleration can be set directly as mm, mm/s and m/s² values, respectively. There is no need for pulse conversion, which allows for more efficient operation of a linear-motion product.

●Continuous Operation via External Signal EZHS EZHC EZHP

Continuous operation can be performed while an external signal (FWD, RVS) is ON. This mode is ideal when you want to move the work via external control without using the teaching pendant.

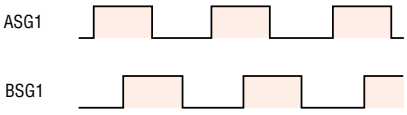
●Output of Current Position and Error Code EZHS EZHC EZHP

The current position, error code and certain other data can be output to an external device.



●Table/Rod Position Monitor EZHS EZHC EZHP

A counter or similar device can be connected to monitor the position of the slider table or cylinder rod using phase-A/B pulse signal outputs.

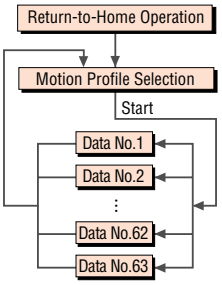


(When the slider table or cylinder rod is moving to the counter-motor side)

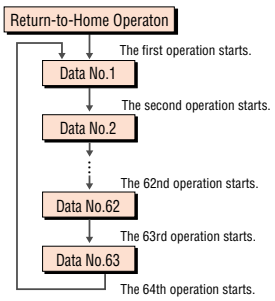
Notes:
- The phase difference between A and B is 90° electrical.
- The pulse output accuracy is within ±0.01 mm.
- Pulse output is subject to a maximum delay of 1 ms with respect to the actual movement of the slider table or cylinder rod. Use this function to check the stop position.
- Pulse output is possible at up to the maximum operating speed of each series. When counting the number of pulses, use a frequency counter that can count frequencies of at least twice the frequency level of the applicable maximum speed.
  Maximum speed and frequency
  EZHS Series : 800 mm/s (80 kHz)
  EZHC Series : 600 mm/s (60 kHz)
  EZHP Series : 300 mm/s (60 kHz)
- When a line-driver output is used, connect a 150 Ω terminal resistor between the line-receiver inputs.
- When an open-collector output is used, keep the cable length to 2 m or shorter. With an open-collector output, the output waveform changes depending on the load condition. Check the operation of the connected equipment.

●Two Data Execution Modes: Selective Positioning and Sequential Positioning Common

Selective positioning mode:
The set data can be selected at random.



Sequential positioning mode:
Positioning operations are performed sequentially from the desired data.

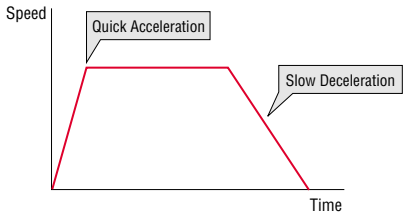


●Separate Acceleration and Deceleration Settings Common

Acceleration and deceleration can be set separately for each motion profile. This feature is useful in a quick acceleration/slow deceleration operation where the motor rises quickly and then decelerates slowly to a stop. [The opposite pattern (slow acceleration/quick deceleration) is also supported.]

EZS/EZC Series: Each motion profile has its own acceleration and deceleration settings.

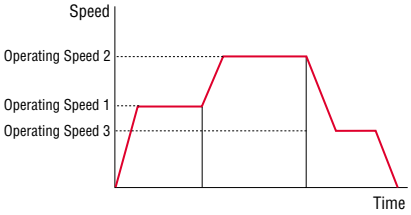
EZHS/EZHC/EZHP Series: One common acceleration and deceleration setting for all motion profiles



●Linked Operation Common

Up to 63 motion profiles (for **EZS/EZC** Series) or 4 motion profiles (for **EZHS/EZHC/EZHP** Series) can be linked, thereby allowing the motor to change speeds without stopping.

Note: The motion profiles must create a motion in the same direction in order to be linked.

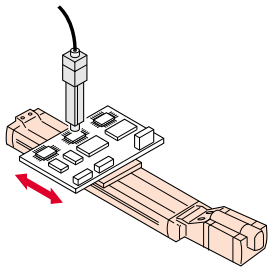


Selection

To select an **EZ limo** product that best suits your application, check the required specifications using the following procedure:

[1] Check the required operation.

Conveyance of work, etc.



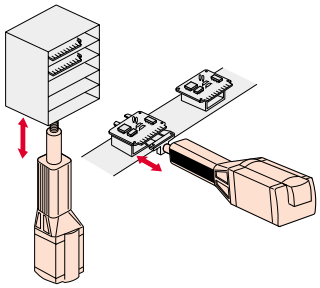
The motorized sliders are your best choice.

[2] Check the direction of installation.

- Horizontal installation → **A model without an electromagnetic brake is recommended.**
- Vertical installation → **Use a model equipped with an electromagnetic brake.**

Use the correlation diagrams shown at the right to select a specific model that meets your required specifications.

Pushing/pulling work, pushing for press fit, etc.

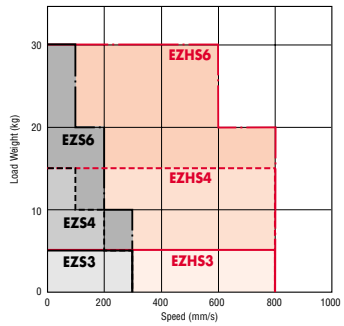


The motorized cylinders are your best choice.

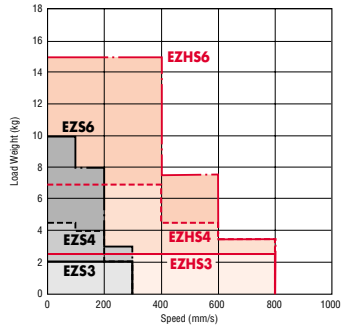
- Horizontal installation → **A model without an electromagnetic brake is recommended.**
- Vertical installation → **Use a model equipped with an electromagnetic brake.**

Use the correlation diagrams shown at the right to select a specific model that meets your required specifications.

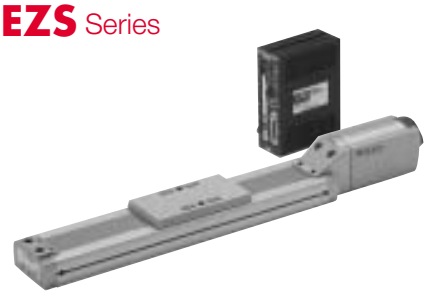
Correlation of Speed and Load Weight
for Slider Horizontal Direction



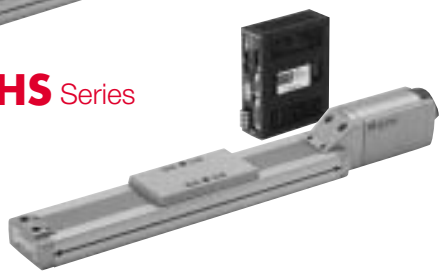
Correlation of Speed and Load Weight
for Slider Vertical Direction



Motorized Sliders
EZS Series



EZHS Series



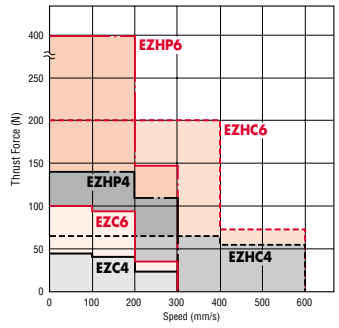
Line-Up ····· Page 12〜15

EZS Series Specifications & Characteristics ····· Page 24〜29

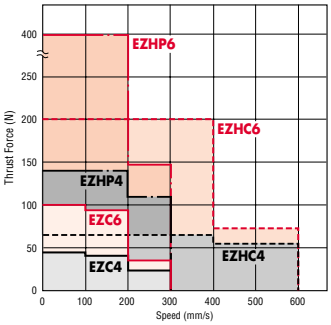
EZHS Series Specifications & Characteristics ··· Page 30〜35

Note: If the object to be installed to the slider has a large overhang from the center of the table, consider the length of overhang.
(See the allowable overhang lengths specified on p. 24 to p. 34.)

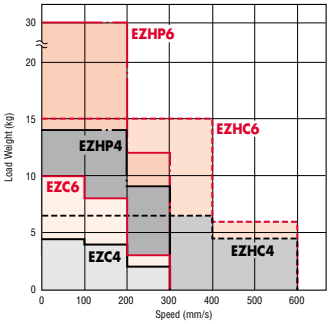
Correlation of Speed and Thrust Force
for Cylinder Horizontal Direction



Correlation of Speed and Thrust Force
for Cylinder Vertical Direction

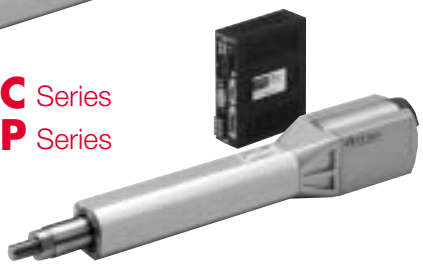


Correlation of Speed and Load Weight
for Cylinder Vertical Direction



Motorized Cylinders
EZC Series

EZHC Series
EZHP Series



Line-Up ····· Page 12〜15

EZC Series Specifications & Characteristics ····· Page 40〜43

EZHC Series Specifications & Characteristics ··· Page 44〜47

EZHP Series Specifications & Characteristics ··· Page 48〜51

Line-Up·Conformance with EC Directives

Motorized Sliders
EZS Series

Model	Power Supply	Electromagnetic Brake	Type	Stroke mm	Maximum Speed mm/s	Max. Transportable Mass kg		Max. Thrust Force N	CE Marking	Page
						Horizontal Direction	Vertical Direction			
EZS3-□CI	24 VDC	Not equipped	Incremental	50 100 150 200 250 300 400 500	300	5	—	23	○	24
EZS3-□CA			Absolute							
EZS3-□MCI		Equipped	Incremental		300	5	2	23		
EZS3-□MCA			Absolute							
EZS4-□CI		Not equipped	Incremental		100 200 300	15 10 5	— — —	45 40 23		26
EZS4-□CA			Absolute							
EZS4-□MCI		Equipped	Incremental		100 200 300	15 10 5	4.5 4 2	45 40 23		
EZS4-□MCA			Absolute							
EZS6-□CI		Not equipped	Incremental	100 150 200 250 300 400 500	100 200 300	30 20 10	— — —	100 94 35		28
EZS6-□CA			Absolute							
EZS6-□MCI		Equipped	Incremental		100 200 300	30 20 10	10 8 3	100 94 35		
EZS6-□MCA			Absolute							

*The box in the model name represents the code for stroke length.

Motorized Cylinders
EZC Series

Model	Power Supply	Electromagnetic Brake	Type	Stroke mm	Maximum Speed mm/s	Max. Transportable Mass kg		Max. Thrust Force N	CE Marking	Page
						Horizontal Direction	Vertical Direction			
EZC4-□CI	24 VDC	Not equipped	Incremental	50 100 200 300	100 200 300	— — —	— — —	45 40 23	○	40
EZC4-□CA			Absolute							
EZC4-□MCI		Equipped	Incremental		100 200 300	— — —	4.5 4 2	45 40 23		
EZC4-□MCA			Absolute							
EZC6-□CI		Not equipped	Incremental		100 200 300	— — —	— — —	100 94 35		42
EZC6-□CA			Absolute							
EZC6-□MCI		Equipped	Incremental		100 200 300	— — —	10 8 3	100 94 35		
EZC6-□MCA			Absolute							

*The box in the model name represents the code for stroke length.

■ Conformance with EC Directives (EZS and EZC series)

The sliders, cylinders, controllers and teaching pendant bear the CE mark to indicate their conformance with the EMC directives.

●Compliance Conditions

- Incorporation in equipment
- Overvoltage Category: Ⅰ
- Pollution Degree: Class 2
- Class Ⅲ equipment

●EMC Directives (89/336/EEC, 92/31/EEC)

See the instructions in the "**EZS**/**EZC** Series Controller User Manual" for the installation and wiring methods.

◇Applicable Standards

• EMI	Emission Tests:	EN50081-2
	Radiated Emission Test:	EN55011
• EMS	Immunity Tests:	EN61000-6-2
	Radiation Field Immunity Test:	IEC61000-4-3
	Electrostatic Discharge Immunity Test:	IEC61000-4-2
	Fast Transient/Burst Immunity Test:	IEC61000-4-4
	Conductive Noise Immunity Test:	IEC61000-4-6

●Emergency Stop

The emergency stop function cuts off the motor current, leaving the motor in a free state.

◇Emergency Stop Function

The stop action actuated by the emergency stop switch or EMG input conforms to "Stop Category 0 (non-controlled stop)" under EN60204-1.

◇Emergency Stop Circuit

The safety parts in the emergency stop circuit are selected in accordance with the requirements of EN954-1, category 1.

Line-Up·Conformance with EC Directives

Motorized Sliders **EZHS** Series

Model	Power Supply Single-Phase	Electromagnetic Brake	Type	Stroke mm	Maximum Speed mm/s	Max. Transportable Mass kg		Max. Thrust Force N	CE Marking	Page
						Horizontal Direction	Vertical Direction			
EZHS3A-□I	100-115V	Not equipped	Incremental	50 100 150 200 250 300 400 500	800	5	—	30	×	30
EZHS3A-□A			Absolute							
EZHS3A-□MI		Equipped	Incremental		800	5	2.5	30		
EZHS3A-□MA			Absolute							
EZHS4A-□I		Not equipped	Incremental		400 600 800	15 15 15	— — —	70 55 43		32
EZHS4A-□A			Absolute							
EZHS4A-□MI		Equipped	Incremental		400 600 800	15 15 15	7 4.5 3.5	70 55 43		
EZHS4A-□MA			Absolute							
EZHS6A-□I	100-115V	Not equipped	Incremental	100 150 200 250 300 400 500	400 600 800	30 30 20	— — —	184 92 50	○	34
EZHS6C-□I	200-230V									
EZHS6A-□A	100-115V		Absolute							
EZHS6C-□A	200-230V									
EZHS6A-□MI	100-115V	Equipped	Incremental		400 600 800	30 30 20	15 7.5 3.5	184 92 50		
EZHS6C-□MI	200-230V									
EZHS6A-□MA	100-115V		Absolute							
EZHS6C-□MA	200-230V									

*The box in the model name represents the code for stroke length.

Motorized Cylinders **EZHC** Series

Model	Power Supply Single-Phase	Electromagnetic Brake	Type	Stroke mm	Maximum Speed mm/s	Max. Transportable Mass kg		Max. Thrust Force N	CE Marking	Page
						Horizontal Direction	Vertical Direction			
EZHC4A-□I	100-115V	Not equipped	Incremental	50 100 200 300	400 600	— —	— —	65 55	×	44
EZHC4A-□A			Absolute							
EZHC4A-□MI		Equipped	Incremental		400 600	— —	6.5 4.5	65 55		
EZHC4A-□MA			Absolute							
EZHC6A-□I	100-115V	Not equipped	Incremental		400 600	— —	— —	200 73	○	46
EZHC6C-□I	200-230V									
EZHC6A-□A	100-115V		Absolute							
EZHC6C-□A	200-230V									
EZHC6A-□MI	100-115V	Equipped	Incremental		400 600	— —	15 6	200 73		
EZHC6C-□MI	200-230V									
EZHC6A-□MA	100-115V		Absolute							
EZHC6C-□MA	200-230V									

*The box in the model name represents the code for stroke length.

Motorized Cylinders **EZHP** Series

Model	Power Supply Single-Phase	Electromagnetic Brake	Type	Stroke mm	Maximum Speed mm/s	Max. Transportable Mass kg		Max. Thrust Force N	CE Marking	Page
						Horizontal Direction	Vertical Direction			
EZHP4A-□I	100-115V	Not equipped	Incremental	50 100 200 300	200 300	— —	— —	140 110	×	48
EZHP4A-□A			Absolute							
EZHP4A-□MI		Equipped	Incremental		200 300	— —	14 9	140 110		
EZHP4A-□MA			Absolute							
EZHP6A-□I	100-115V	Not equipped	Incremental		200 300	— —	— —	400 147	○	50
EZHP6C-□I	200-230V									
EZHP6A-□A	100-115V		Absolute							
EZHP6C-□A	200-230V									
EZHP6A-□MI	100-115V	Equipped	Incremental		200 300	— —	30 12	400 147		
EZHP6C-□MI	200-230V									
EZHP6A-□MA	100-115V		Absolute							
EZHP6C-□MA	200-230V									

*The box in the model name represents the code for stroke length.

■ Conformance with EC Directives (EZHS, EZHC and EZHP series)

The **EZHS6** sliders, **EZHC6** and **EZHP6** cylinders, controllers and teaching pendant bear the CE mark to indicate their conformance with the Low-Voltage and EMC directives.

●Low Voltage Directive

	Applicable Standards	Install Condition
Slider Cylinder	EN60950 EN60034-1 EN60034-5 IEC60664-1	Incorporation in equipment Overvoltage Category: II Pollution Degree: Class 2 Class I equipment
Controller	EN50178	Incorporation in equipment Overvoltage Category: II Pollution Degree: Class 2 Class I equipment
Teaching Pendant	EN60950 EN60204-1	Overvoltage Category: II Pollution Degree: Class 2 Class II equipment

●EMC Directives (89/336/EEC, 92/31/EEC)

See the instructions in the "**EZHS**/**EZHC**/**EZHP** Series Controller User Manual" for the installation and wiring methods.

◇Applicable Standards

• EMI	Emission Tests:	EN50081-2
	Radiated Emission Test:	EN55011
	Conducted Emission Test:	EN55011
• EMS	Immunity Tests:	EN61000-6-2
	Radiation Field Immunity Test:	IEC61000-4-3
	Electrostatic Discharge Immunity Test:	IEC61000-4-2
	Fast Transient/Burst Immunity Test:	IEC61000-4-4
	Conductive Noise Immunity Test:	IEC61000-4-6
	Surge Immunity Test:	IEC61000-4-5
	Voltage Dip Immunity Test:	IEC61000-4-11
	Voltage Interruption Immunity Test:	IEC61000-4-11

●Machinery Directive (98/37/EC)

The **EZHS6** sliders, **EZHC6**/**EZHP6** cylinders, controllers and teaching pendants are designed and manufactured for use in general industrial equipment as an internal component, and therefore need not comply with the Machinery Directive. However, each product has been evaluated under the following standards to ensure proper operation:

EN292-1, EN292-2, EN1050, EN954-1, EN418, EN60204-1

◇Emergency Stop Function

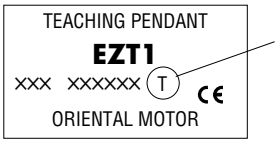
The emergency stop button of the teaching pendant uses an EN-certified product. See page 58 for a connection example that conforms to Stop Category 0 (non-controlled stop) under EN60204-1.

◇Emergency Stop Circuit

The safety parts in the emergency stop circuit are selected in accordance with the requirements of EN954-1.

■ If you already have a teaching pendant;

Please check its conformance to EC Directives on the nameplate attached on the back of the teaching pendant.



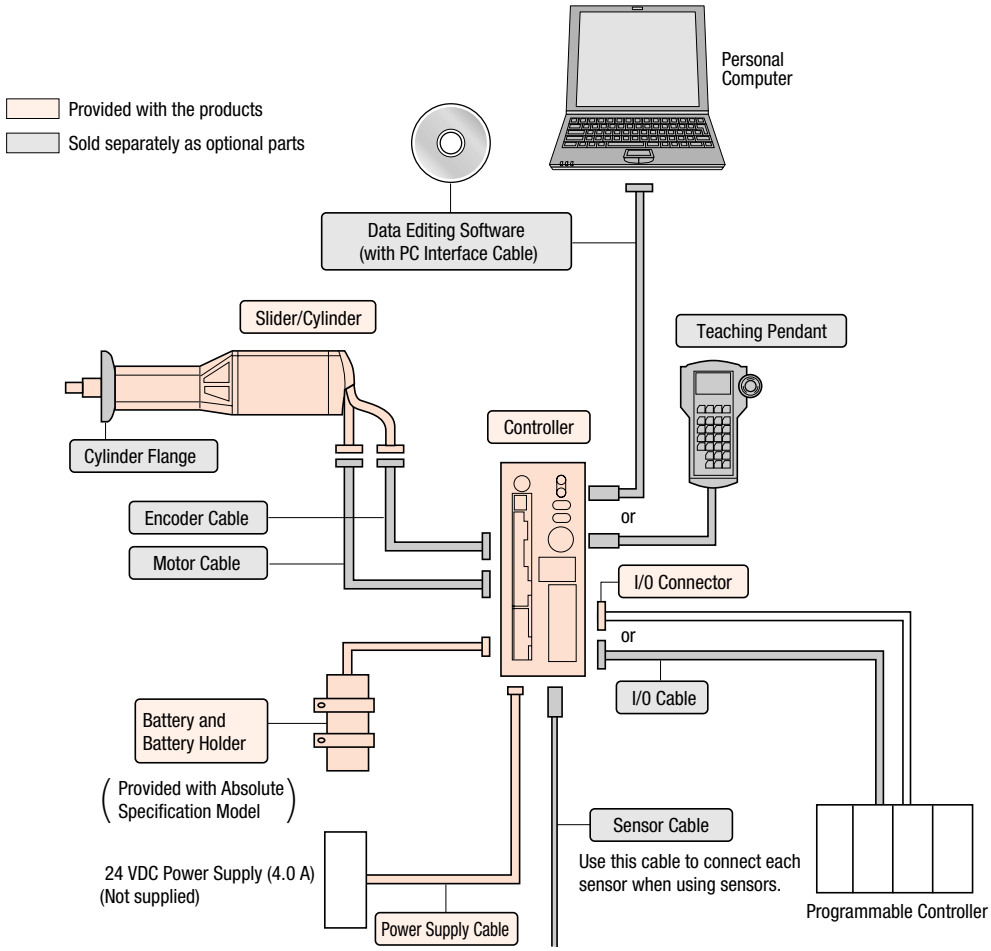
T : Conforming to the Low-Voltage and EMC Directives

J : Conforming to only the EMC Directives

If the nameplate on your teaching pendant shows "J" and your application requires conformance to the Low-Voltage Directives, purchase a new teaching pendant that ensures the required conformance.

System Configuration

■ EZS Series • EZC Series



■ Optional Parts (sold separately)

EZS For use with the **EZS** series
EZC For use with the **EZC** series

●Teaching Pendant —— EZS EZC —— P.65

The teaching pendant allows you to set and execute motion profiles already stored, as well as to monitor the set data, current position and I/O status in real time.

●Data Editing Software —— EZS EZC —— P.65

With this software you can set and edit various data on a PC. It comes with a PC interface cable for connecting the controller and PC. The software also provides various monitoring functions.

●Cable Set — EZS EZC — P.66

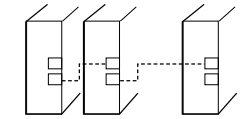
A set of dedicated cables is used to connect the **EZ limo** slider/cylinder with the controller. The cable set consists of a motor cable and an encoder cable. The cable length can be selected from 2 m, 5 m and 10 m. Each of the cables can be purchased individually.

Motor cable

Encoder cable

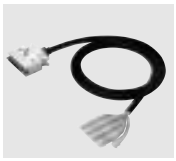
●Controller Link Cable — EZS EZC — P.67

Use this dedicated cable to link the **EZ limo** controllers. A maximum of 16 controllers can be connected, with data set separately for each of the controllers.



●I/O Cable — EZS EZC — P.67

This cable is used exclusively for connection between the **EZ limo** controller and the host controller. A half-pitch connector allowing one-touch connection to the controller is attached at one end of the flat cable.



●Sensor Cable — EZS EZC — P.67

Use this cable to connect each sensor used in the controller mode to the controller.

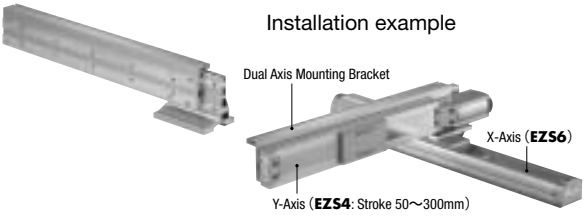
●Sensor Set — EZS EZC — P.68

These sensors can be used in the controller mode or driver mode. The sensor set comes with the necessary mounting hardware.

●Dual Axis Mounting Bracket — EZS — P.69

This dual axis mounting bracket allows easy installation of a pair of axes (**EZS6**/**EZS4** sliders). Various types of brackets are available to support combinations of X-Y and X-Z axes.

Installation example



●Cable Holder — EZS — P.73

This low-noise cable holder protects and guides cables in multi-axis configurations. It can be easily installed on a dual axis mounting bracket using the supplied brackets.

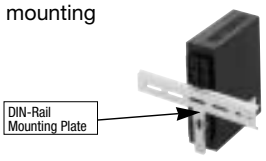
Installation example

●Cylinder Flange — EZC — P.73

This special mounting bracket is used to install the cylinder from the body side. The flange comes with the mounting screws for affixing the cylinder to the flange. (The customer must provide the mounting screws for affixing the flange to the equipment.)

●DIN Rail Mounting Plate — EZS EZC — P.73

This plate is used to install the **EZ limo** controller to a DIN rail. The plate comes with the mounting screws.



The following spare parts are also available:

●**Stainless Sheet** (for slider)
— EZS — P.73

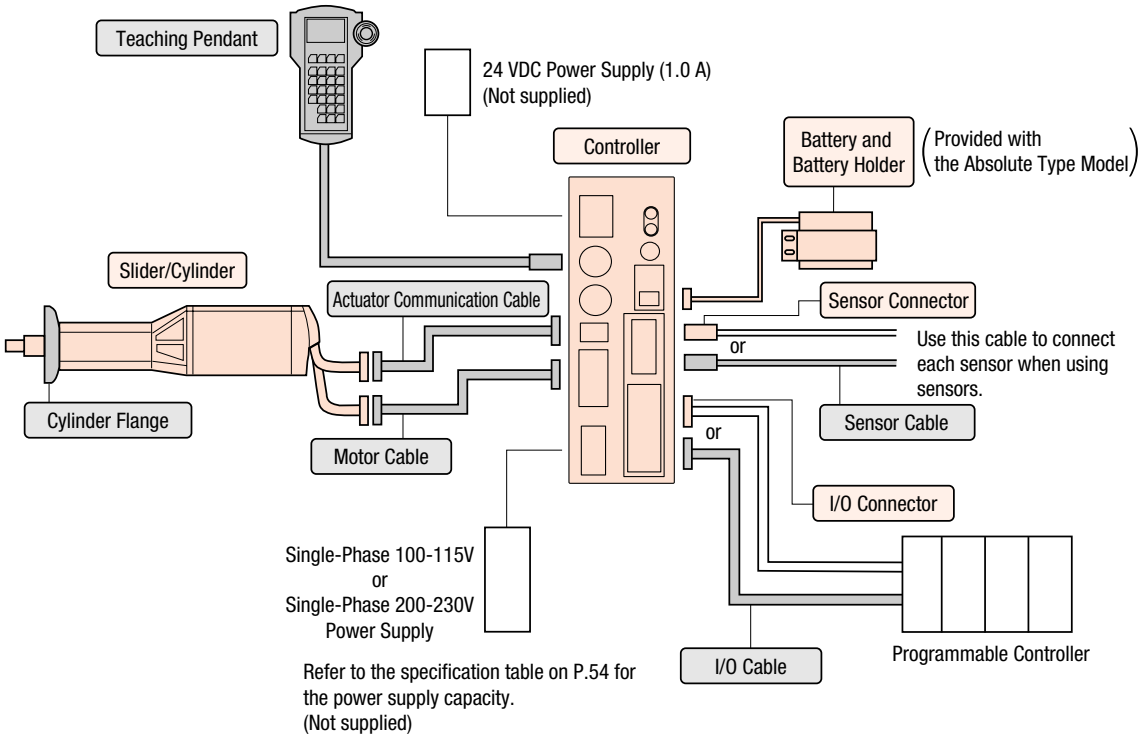
●**Battery** (for absolute type)
— EZS EZC — P.73

*Battery holder not supplied with a spare battery

System Configuration

■ EZHS Series・EZHC Series・EZHP Series

Provided with the products
Sold separately as optional parts



Refer to the specification table on P.54 for the power supply capacity.
(Not supplied)

■ Optional Parts (sold separately)

EZHS For use with the **EZHS** series
EZHC For use with the **EZHC** series
EZHP For use with the **EZHP** series

●Teaching Pendant —— EZHS EZHC EZHP —— P.65

The teaching pendant allows you to set and execute motion profiles already stored, as well as to monitor the set data, current position and I/O status in real time.

●Cable Set —— EZHS EZHC EZHP —— P.66

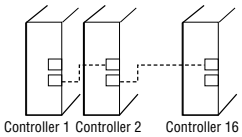
A set of dedicated cables is used to connect the **EZ limo** slider/cylinder with the controller. The cable set consists of a motor cable and an actuator communication cable. The cable length can be selected from 2 m, 5 m and 10 m. Each of the cables can be purchased individually.
Flexible cables are also available.

Motor cable

Actuator communication cable

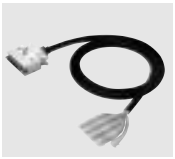
●Controller Link Cable — EZHS EZHC EZHP —P.67

Use this dedicated cable to link the **EZ limo** controllers. A maximum of 16 controllers can be connected, with data set separately for each of the controllers.



●I/O Cable — EZHS EZHC EZHP —P.67

This cable is used exclusively for connection between the **EZ limo** controller and the host controller. A half-pitch connector allowing one-touch connection to the controller is attached at one end of the flat cable.

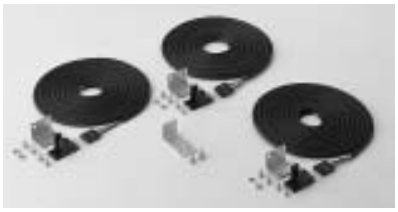


●Sensor Cable — EZHS EZHC EZHP —P.67

Use this cable to connect each sensor used in the controller mode to the controller.

●Sensor Set — EZHS EZHC EZHP —P.68

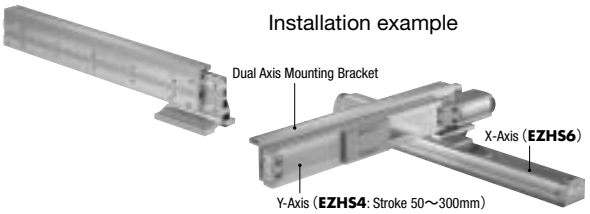
These sensors can be used in the controller mode or driver mode. The sensor set comes with the necessary mounting hardware.



●Dual Axis Mounting Bracket — EZHS —P.69

This dual axis mounting bracket allows easy installation of a pair of axes (**EZHS6**/**EZHS4** sliders). Various types of brackets are available to support combinations of X-Y and X-Z axes.

Installation example



●Cable Holder — EZHS —P.73

This low-noise cable holder protects and guides cables in multi-axis configurations. It can be easily installed on a dual axis mounting bracket using the supplied brackets.

Installation example

●Cylinder Flange — EZHC EZHP —P.73

This special mounting bracket is used to install the cylinder from the body side. The flange comes with the mounting screws for affixing the cylinder to the flange. (The customer must provide the mounting screws for affixing the flange to the equipment.)

The following spare parts are also available:

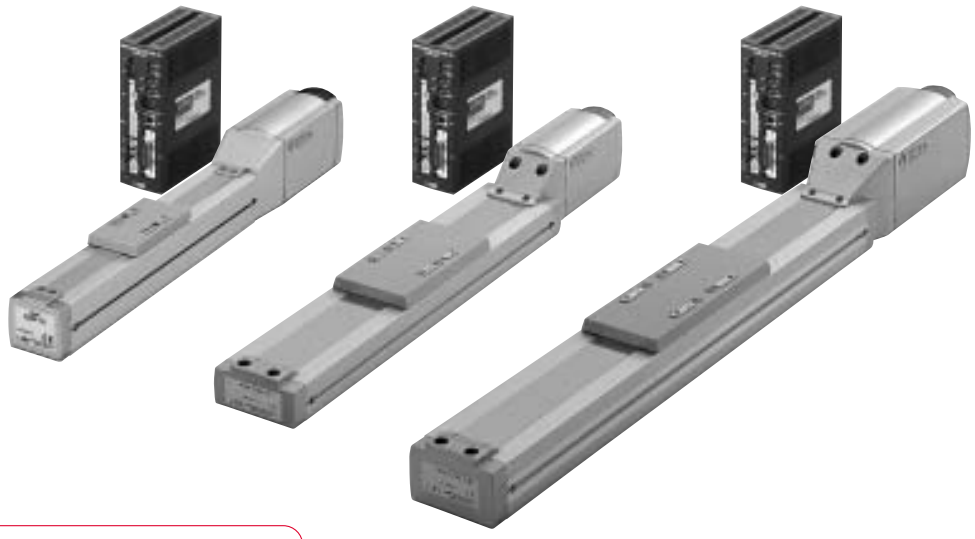
●**Stainless Sheet** (for slider) — EZHS —P.73

●**Battery** (for absolute type) — EZHS EZHC EZHP —P.73

*Battery holder not supplied with a spare battery

EZS Series
EZHS Series

EZS Series



Names and Functions of the Slider

Cable

The cable outlet is facing downward, which contributes to the overall space savings by reducing the space needed to wire the cables.

Stainless Sheet

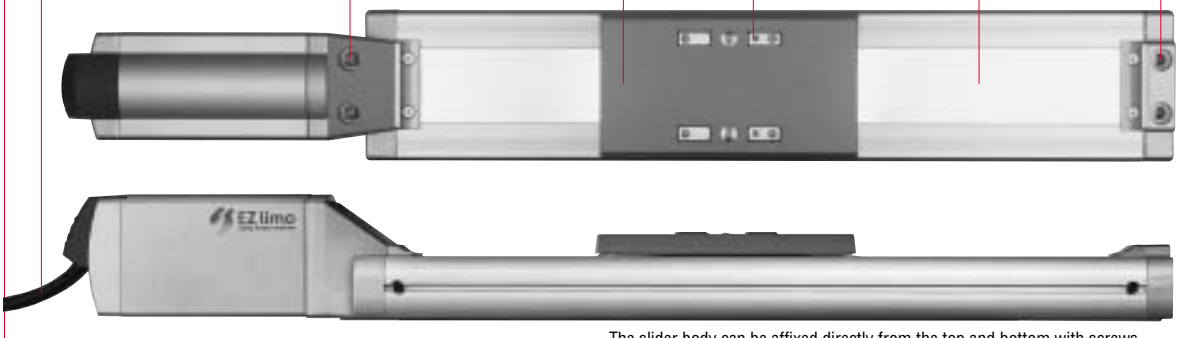
The mechanical parts of the slider are covered with stainless sheet to keep out foreign particles.

Mounting Hole (Except for EZS3 and EZHS3)

Table

Positioning Pinhole

Mounting Hole (Except for EZS3 and EZHS3)



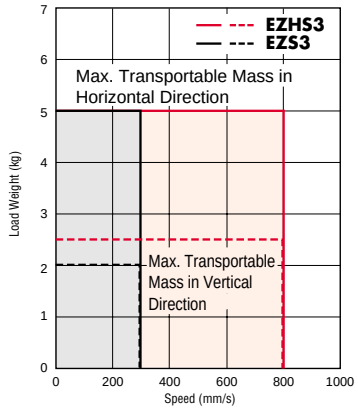
The slider body can be affixed directly from the top and bottom with screws. (**EZS3** and **EZHS3** can be affixed only from the bottom.)

Mounting Reference Surface

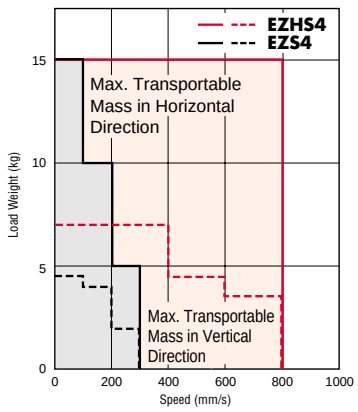
EZHS Series

■ Motorized Slider Speed – Load Weight Characteristics

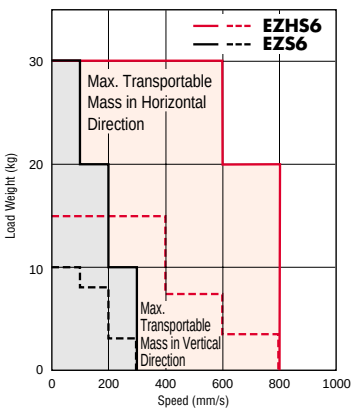
EZS3/EZHS3



EZS4/EZHS4



EZS6/EZHS6



■ Models

●EZS Series

◇Incremental Type

Without Electromagnetic Brake 24 VDC Input

Stroke	Model		
50mm	**EZS3-05CI**	**EZS4-05CI**	—
100mm	**EZS3-10CI**	**EZS4-10CI**	**EZS6-10CI**
150mm	**EZS3-15CI**	**EZS4-15CI**	**EZS6-15CI**
200mm	**EZS3-20CI**	**EZS4-20CI**	**EZS6-20CI**
250mm	**EZS3-25CI**	**EZS4-25CI**	**EZS6-25CI**
300mm	**EZS3-30CI**	**EZS4-30CI**	**EZS6-30CI**
400mm	**EZS3-40CI**	**EZS4-40CI**	**EZS6-40CI**
500mm	**EZS3-50CI**	**EZS4-50CI**	**EZS6-50CI**

With Electromagnetic Brake 24 VDC Input

Stroke	Model		
50mm	**EZS3-05MCI**	**EZS4-05MCI**	—
100mm	**EZS3-10MCI**	**EZS4-10MCI**	**EZS6-10MCI**
150mm	**EZS3-15MCI**	**EZS4-15MCI**	**EZS6-15MCI**
200mm	**EZS3-20MCI**	**EZS4-20MCI**	**EZS6-20MCI**
250mm	**EZS3-25MCI**	**EZS4-25MCI**	**EZS6-25MCI**
300mm	**EZS3-30MCI**	**EZS4-30MCI**	**EZS6-30MCI**
400mm	**EZS3-40MCI**	**EZS4-40MCI**	**EZS6-40MCI**
500mm	**EZS3-50MCI**	**EZS4-50MCI**	**EZS6-50MCI**

◇ Absolute Type

Without Electromagnetic Brake 24 VDC Input

Stroke	Model		
50mm	**EZS3-05CA**	**EZS4-05CA**	—
100mm	**EZS3-10CA**	**EZS4-10CA**	**EZS6-10CA**
150mm	**EZS3-15CA**	**EZS4-15CA**	**EZS6-15CA**
200mm	**EZS3-20CA**	**EZS4-20CA**	**EZS6-20CA**
250mm	**EZS3-25CA**	**EZS4-25CA**	**EZS6-25CA**
300mm	**EZS3-30CA**	**EZS4-30CA**	**EZS6-30CA**
400mm	**EZS3-40CA**	**EZS4-40CA**	**EZS6-40CA**
500mm	**EZS3-50CA**	**EZS4-50CA**	**EZS6-50CA**

With Electromagnetic Brake 24 VDC Input

Stroke	Model		
50mm	**EZS3-05MCA**	**EZS4-05MCA**	—
100mm	**EZS3-10MCA**	**EZS4-10MCA**	**EZS6-10MCA**
150mm	**EZS3-15MCA**	**EZS4-15MCA**	**EZS6-15MCA**
200mm	**EZS3-20MCA**	**EZS4-20MCA**	**EZS6-20MCA**
250mm	**EZS3-25MCA**	**EZS4-25MCA**	**EZS6-25MCA**
300mm	**EZS3-30MCA**	**EZS4-30MCA**	**EZS6-30MCA**
400mm	**EZS3-40MCA**	**EZS4-40MCA**	**EZS6-40MCA**
500mm	**EZS3-50MCA**	**EZS4-50MCA**	**EZS6-50MCA**

■ Product Number Code

●EZS Series

EZS ① **4** ② **-** **10** ③ **M** ④ **C** ⑤ **I** ⑥

①	**EZS** Series	④	None：Without Electromagnetic Brake **M** ：With Electromagnetic Brake
②	Slider Size		
③	Stroke **05**： 50mm **10**：100mm **15**：150mm **20**：200mm **25**：250mm **30**：300mm **40**：400mm **50**：500mm	⑤	With Controller
		⑥	**I** ：Incremental Type **A**：Absolute Type

●EZHS Series

◇Incremental Type

Without Electromagnetic Brake Single-Phase 100-115 V Input

Stroke	Model		
50mm	**EZHS3A-05I**	**EZHS4A-05I**	—
100mm	**EZHS3A-10I**	**EZHS4A-10I**	**EZHS6A-10I**
150mm	**EZHS3A-15I**	**EZHS4A-15I**	**EZHS6A-15I**
200mm	**EZHS3A-20I**	**EZHS4A-20I**	**EZHS6A-20I**
250mm	**EZHS3A-25I**	**EZHS4A-25I**	**EZHS6A-25I**
300mm	**EZHS3A-30I**	**EZHS4A-30I**	**EZHS6A-30I**
400mm	**EZHS3A-40I**	**EZHS4A-40I**	**EZHS6A-40I**
500mm	**EZHS3A-50I**	**EZHS4A-50I**	**EZHS6A-50I**

Single-Phase 200-230 V Input

Stroke	Model
50mm	—
100mm	**EZHS6C-10I**
150mm	**EZHS6C-15I**
200mm	**EZHS6C-20I**
250mm	**EZHS6C-25I**
300mm	**EZHS6C-30I**
400mm	**EZHS6C-40I**
500mm	**EZHS6C-50I**

With Electromagnetic Brake Single-Phase 100-115 V Input

Stroke	Model		
50mm	**EZHS3A-05MI**	**EZHS4A-05MI**	—
100mm	**EZHS3A-10MI**	**EZHS4A-10MI**	**EZHS6A-10MI**
150mm	**EZHS3A-15MI**	**EZHS4A-15MI**	**EZHS6A-15MI**
200mm	**EZHS3A-20MI**	**EZHS4A-20MI**	**EZHS6A-20MI**
250mm	**EZHS3A-25MI**	**EZHS4A-25MI**	**EZHS6A-25MI**
300mm	**EZHS3A-30MI**	**EZHS4A-30MI**	**EZHS6A-30MI**
400mm	**EZHS3A-40MI**	**EZHS4A-40MI**	**EZHS6A-40MI**
500mm	**EZHS3A-50MI**	**EZHS4A-50MI**	**EZHS6A-50MI**

Single-Phase 200-230 V Input

Stroke	Model
50mm	—
100mm	**EZHS6C-10MI**
150mm	**EZHS6C-15MI**
200mm	**EZHS6C-20MI**
250mm	**EZHS6C-25MI**
300mm	**EZHS6C-30MI**
400mm	**EZHS6C-40MI**
500mm	**EZHS6C-50MI**

◇ Absolute Type

Without Electromagnetic Brake Single-Phase 100-115 V Input

Stroke	Model		
50mm	**EZHS3A-05A**	**EZHS4A-05A**	—
100mm	**EZHS3A-10A**	**EZHS4A-10A**	**EZHS6A-10A**
150mm	**EZHS3A-15A**	**EZHS4A-15A**	**EZHS6A-15A**
200mm	**EZHS3A-20A**	**EZHS4A-20A**	**EZHS6A-20A**
250mm	**EZHS3A-25A**	**EZHS4A-25A**	**EZHS6A-25A**
300mm	**EZHS3A-30A**	**EZHS4A-30A**	**EZHS6A-30A**
400mm	**EZHS3A-40A**	**EZHS4A-40A**	**EZHS6A-40A**
500mm	**EZHS3A-50A**	**EZHS4A-50A**	**EZHS6A-50A**

Single-Phase 200-230 V Input

Stroke	Model
50mm	—
100mm	**EZHS6C-10A**
150mm	**EZHS6C-15A**
200mm	**EZHS6C-20A**
250mm	**EZHS6C-25A**
300mm	**EZHS6C-30A**
400mm	**EZHS6C-40A**
500mm	**EZHS6C-50A**

With Electromagnetic Brake　Single-Phase 100-115 V Input

Stroke	Model		
50mm	**EZHS3A-05MA**	**EZHS4A-05MA**	—
100mm	**EZHS3A-10MA**	**EZHS4A-10MA**	**EZHS6A-10MA**
150mm	**EZHS3A-15MA**	**EZHS4A-15MA**	**EZHS6A-15MA**
200mm	**EZHS3A-20MA**	**EZHS4A-20MA**	**EZHS6A-20MA**
250mm	**EZHS3A-25MA**	**EZHS4A-25MA**	**EZHS6A-25MA**
300mm	**EZHS3A-30MA**	**EZHS4A-30MA**	**EZHS6A-30MA**
400mm	**EZHS3A-40MA**	**EZHS4A-40MA**	**EZHS6A-40MA**
500mm	**EZHS3A-50MA**	**EZHS4A-50MA**	**EZHS6A-50MA**

Single-Phase 200-230 V Input

Stroke	Model
50mm	—
100mm	**EZHS6C-10MA**
150mm	**EZHS6C-15MA**
200mm	**EZHS6C-20MA**
250mm	**EZHS6C-25MA**
300mm	**EZHS6C-30MA**
400mm	**EZHS6C-40MA**
500mm	**EZHS6C-50MA**

■ Product Number Code

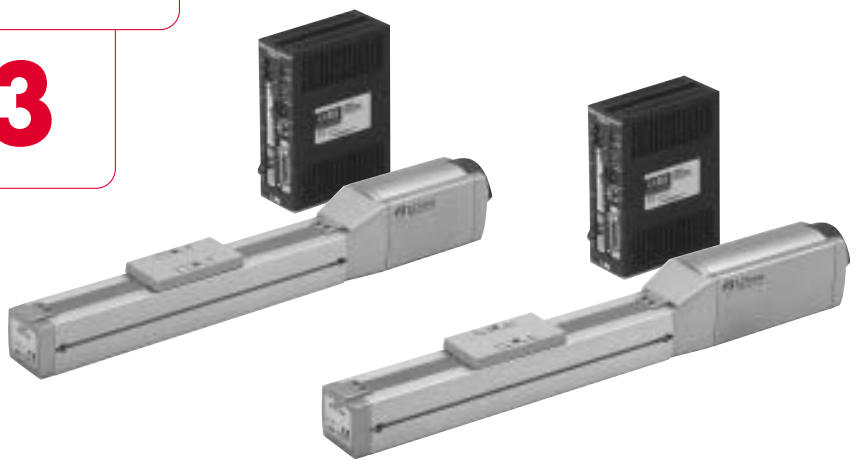
●EZHS Series

EZHS ① **4** ② **A** ③ **-** **10** ④ **M** ⑤ **I** ⑥

①	**EZHS** Series	④	Stroke **05**: 50mm **10**:100mm **15**:150mm **20**:200mm **25**:250mm **30**:300mm **40**:400mm **50**:500mm
②	Slider Size		
③	Power Supply **A**：Single-Phase 100-115V **C**：Single-Phase 200-230V	⑤	None：Without Electromagnetic Brake **M**：With Electromagnetic Brake
		⑥	**I**：Incremental Type **A**：Absolute Type

EZS Series

EZS3



■ Specifications

Model		Incremental Type	EZS3-□CI	EZS3-□MCI
		Absolute Type	EZS3-□CA	EZS3-□MCA
Motor Type			Stepping Motor with Encoder	
Drive Method			Ball Screw	
Electromagnetic Brake			Not equipped	Equipped
Speed Range		mm/s	～300	～300
Max. Transportable Mass	kg	Horizontal Direction	5	5
		Vertical Direction	—	2
Max. Acceleration	m/s²	Horizontal Direction	2	2
		Vertical Direction	—	2
Max. Thrust Force		N kgf	23 2.3	23 2.3
Max. Holding Brake Force	N kgf	Power ON	23 2.3	23 2.3
		Power OFF	0	0
		Electromagnetic Brake	—	23 2.3
Repetitive Positioning Accuracy		mm	±0.02	
Resolution		mm	0.015	
Lead		mm	12	
Stroke		mm	50、100、150、200、250、300、400、500	
Slider Mass (Figure in the parentheses shows the mass of the model with electromagnetic brake.)		kg	**Stroke** **50** : 1.5 (1.7) **100** : 1.6 (1.8) **150** : 1.7 (1.9) **200** : 1.8 (2.0) **250** : 1.9 (2.1) **300** : 2.0 (2.2) **400** : 2.2 (2.4) **500** : 2.4 (2.6)	
Ambient Temperature		℃	0～+40 (Nonfreezing)	

●See page 52 for the specification and dimensions of the controller.

■ General Specifications

Item	Specification
Insulation Resistance	100 MΩ minimum when measured by a DC 500 V megger between the following places. • Windings — Case • Case — Windings of electromagnetic brake (Only for electromagnetic brake equipped model)
Dielectric Strength	Sufficient to withstand the following for one minute. • Windings — Case AC 0.5 kV 50 Hz • Case — Windings of electromagnetic brake (Only for electromagnetic brake equipped model) AC 0.5 kV 50 Hz

■ Slider/Controller Combinations

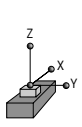
Type	Electromagnetic Brake	Model	Slider Model	Controller Model
Incremental Type	Not equipped	**EZS3-□CI**	EZS3-□	EZMC36I
	Equipped	**EZS3-□MCI**	EZS3-□M	
Absolute Type	Not equipped	**EZS3-□CA**	EZS3-□	EZMC36A
	Equipped	**EZS3-□MCA**	EZS3-□M	

*The box (□) in the model name and slider model name represents the code for stroke length.

■ Allowable Overhung Length (mm)

* The length from the center of load's mounting surface to the center of gravity of the object being carried.

• Horizontal Installation

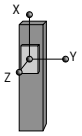


Carried Weight	X	Y	Z
1kg	205	300	300
2.5kg	75	136	300
5kg	32	58	157

• Wall Mount Installation

Carried Weight	X	Y	Z
1kg	155	300	300
2.5kg	62	300	105
5kg	22	106	31

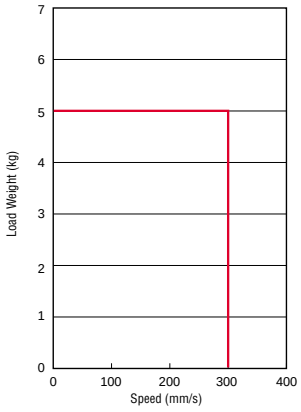
• Vertical Installation



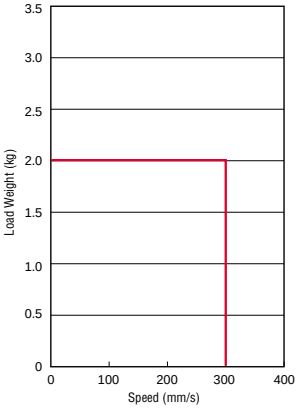
Carried Weight	X	Y	Z
0.5kg	300	257	300
1kg	142	129	142
2kg	62	62	52

Correlation Diagram of Speed and Load Weight

●Horizontal Direction



●Vertical Direction

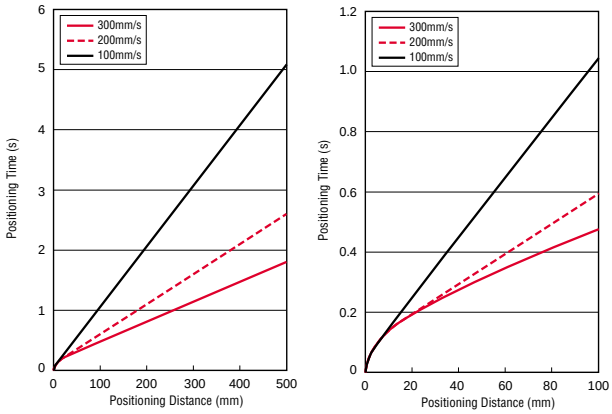


Minimum Positioning Time

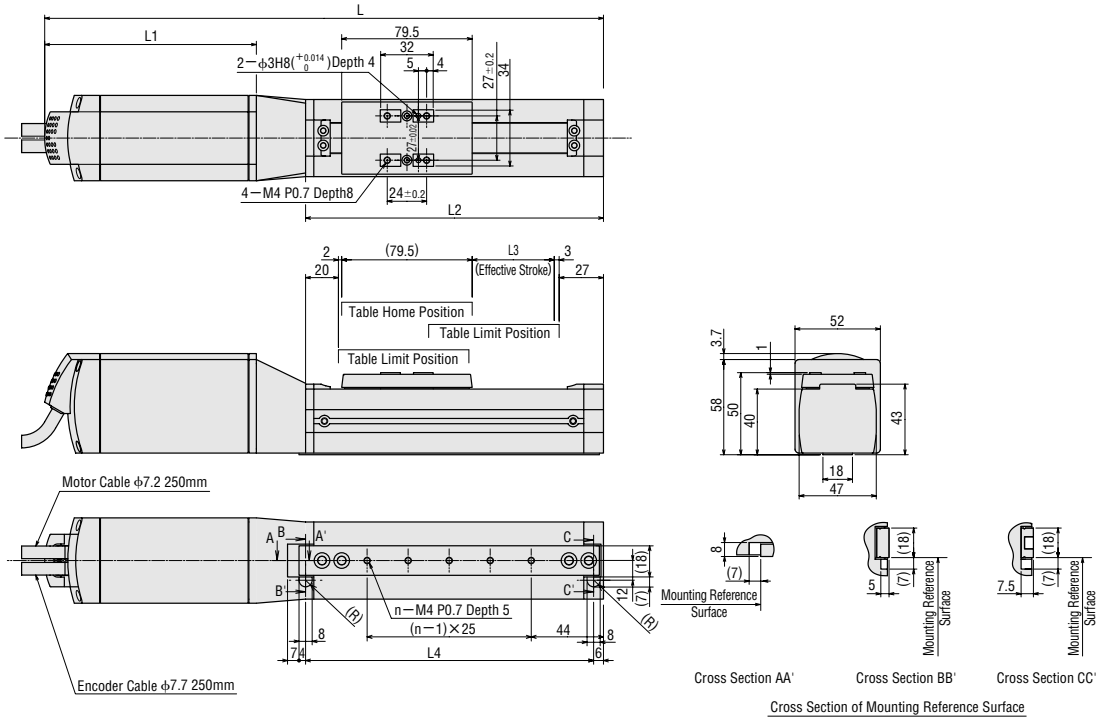
Acceleration: 2 m/s² Starting Speed: 6 mm/s

●Horizontal Direction/ Vertical Direction

Enlargement of Positioning Distance under 100 mm



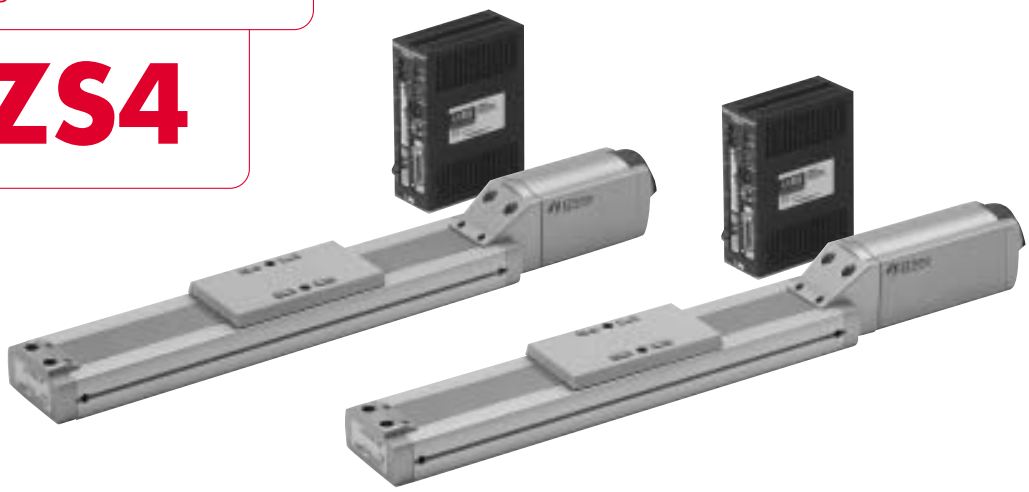
Dimensions unit: mm



Slider Model	L	L1	L2	L3	L4	n
EZS3-05	340.5	129	181.5	50	175.5	5
EZS3-05M	370.5	159				
EZS3-10	390.5	129	231.5	100	225.5	7
EZS3-10M	420.5	159				
EZS3-15	440.5	129	281.5	150	275.5	9
EZS3-15M	470.5	159				
EZS3-20	490.5	129	331.5	200	325.5	11
EZS3-20M	520.5	159				
EZS3-25	540.5	129	381.5	250	375.5	13
EZS3-25M	570.5	159				
EZS3-30	590.5	129	431.5	300	425.5	15
EZS3-30M	620.5	159				
EZS3-40	690.5	129	531.5	400	525.5	19
EZS3-40M	720.5	159				
EZS3-50	790.5	129	631.5	500	625.5	23
EZS3-50M	820.5	159				

EZS Series

EZS4



■ Specifications

Model		Incremental Type	EZS4-□CI			EZS4-□MCI		
		Absolute Type	EZS4-□CA			EZS4-□MCA		
Motor Type			Stepping Motor with Encoder					
Drive Method			Ball Screw					
Electromagnetic Brake			Not equipped			Equipped		
Speed Range		mm/s	～100	～200	～300	～100	～200	～300
Max. Transportable Mass	kg	Horizontal Direction	15	10	5	15	10	5
		Vertical Direction	—	—	—	4.5	4	2
Max. Acceleration	m/s²	Horizontal Direction	2			2		
		Vertical Direction	—			2		
Max. Thrust Force		N kgf	45 4.5	40 4	23 2.3	45 4.5	40 4	23 2.3
Max. Holding Brake Force	N kgf	Power ON	45 4.5			45 4.5		
		Power OFF	0			0		
		Electromagnetic Brake	—			45 4.5		
Repetitive Positioning Accuracy		mm	±0.02					
Resolution		mm	0.015					
Lead		mm	12					
Stroke		mm	50、100、150、200、250、300、400、500					
Slider Mass	Figure in the parentheses shows the mass of the model with electromagnetic brake.	kg	**Stroke**	**50** : 2.3 (2.5)	**100** : 2.5 (2.7)	**150** : 2.7 (2.9)	**200** : 2.9 (3.1)	
				250 : 3.1 (3.3)	**300** : 3.3 (3.5)	**400** : 3.7 (3.9)	**500** : 4.1 (4.3)	
Ambient Temperature		℃	0～+40 (Nonfreezing)					

●See page 52 for the specification and dimensions of the controller.

■ General Specifications

Item	Specification
Insulation Resistance	100 MΩ minimum when measured by a DC 500 V megger between the following places. • Windings — Case • Case — Windings of electromagnetic brake (Only for electromagnetic brake equipped model)
Dielectric Strength	Sufficient to withstand the following for one minute. • Windings — Case AC 0.5 kV 50 Hz • Case — Windings of electromagnetic brake AC 0.5 kV 50 Hz (Only for electromagnetic brake equipped model)

■ Slider/Controller Combinations

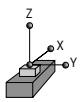
Type	Electromagnetic Brake	Model	Slider Model	Controller Model
Incremental Type	Not equipped	**EZS4-□CI**	EZS4-□	EZMC36I
	Equipped	**EZS4-□MCI**	EZS4-□M	
Absolute Type	Not equipped	**EZS4-□CA**	EZS4-□	EZMC36A
	Equipped	**EZS4-□MCA**	EZS4-□M	

*The box (□) in the model name and slider model name represents the code for stroke length.

■ Allowable Overhung Length (mm)

* The length from the center of load's mounting surface to the center of gravity of the object being carried.

• Horizontal Installation

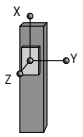


Carried Weight	X	Y	Z
5kg	113	135	300
10kg	51	67	252
15kg	31	45	150

• Wall Mount Installation

Carried Weight	X	Y	Z
5kg	28	135	237
10kg	14	67	99
15kg	9	45	53

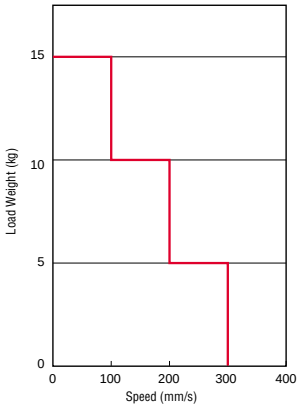
• Vertical Installation



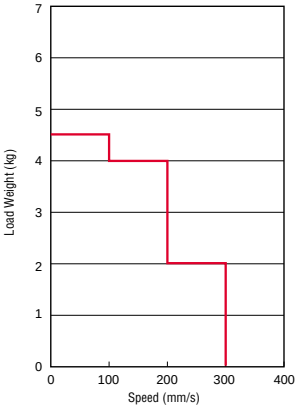
Carried Weight	X	Y	Z
2kg	230	57	230
4kg	102	29	102
4.5kg	87	25	87

Correlation Diagram of Speed and Load Weight

●Horizontal Direction



●Vertical Direction

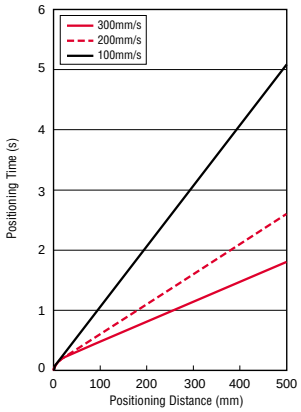


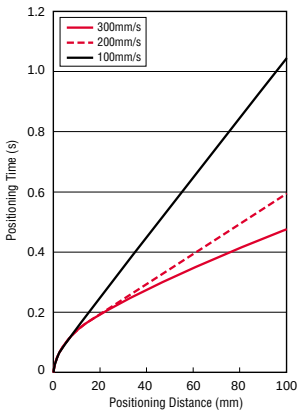
Minimum Positioning Time

Acceleration: 2 m/s² Starting Speed: 6 mm/s

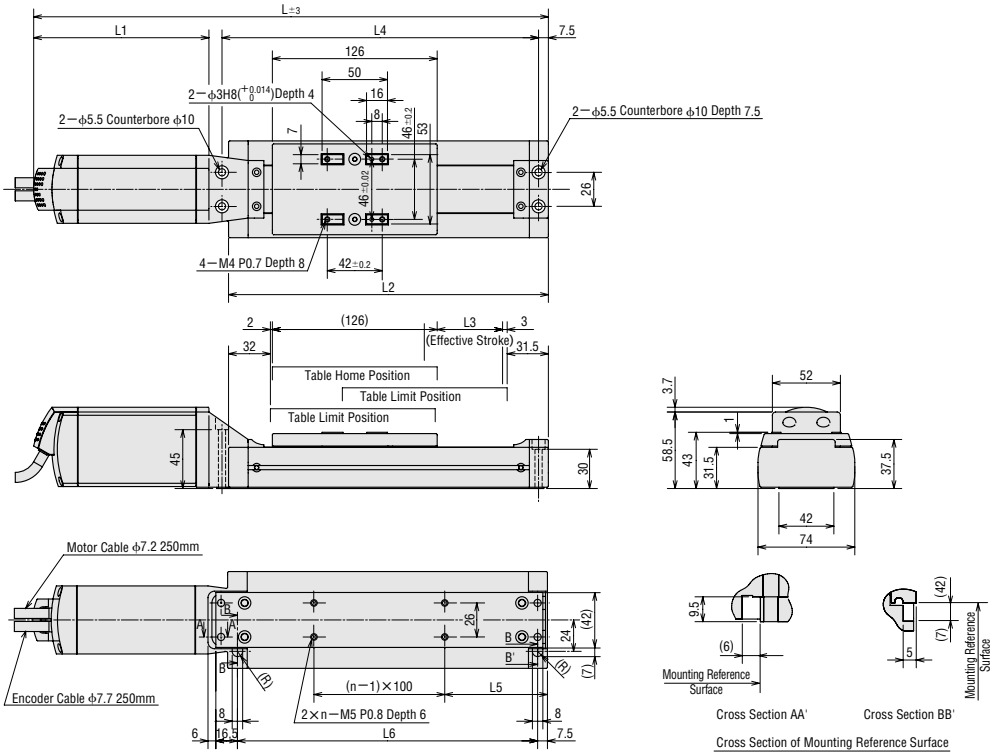
●Horizontal Direction/ Vertical Direction

Enlargement of Positioning Distance under 100 mm





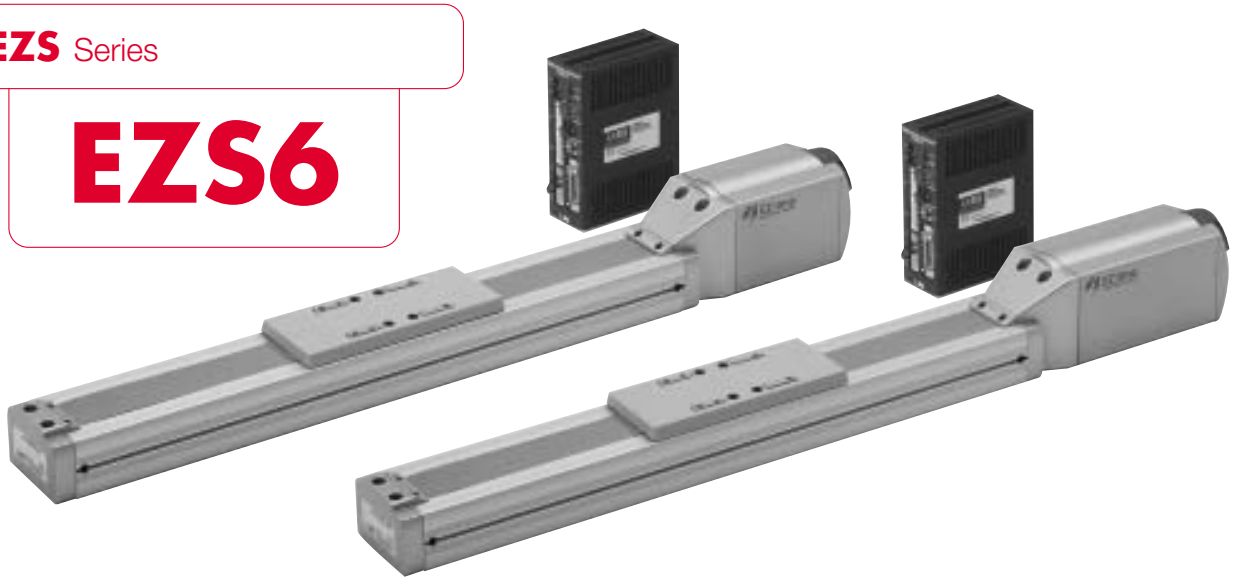
Dimensions unit: mm



Slider Model	L	L1	L2	L3	L4	L5	L6	n
EZS4-05	393.5	134	244.5	50	242	78.5	229.5	2
EZS4-05M	423.5	164						
EZS4-10	443.5	134	294.5	100	292	53.5	279.5	3
EZS4-10M	473.5	164						
EZS4-15	493.5	134	344.5	150	342	78.5	329.5	3
EZS4-15M	523.5	164						
EZS4-20	543.5	134	394.5	200	392	53.5	379.5	4
EZS4-20M	573.5	164						
EZS4-25	593.5	134	444.5	250	442	78.5	429.5	4
EZS4-25M	623.5	164						
EZS4-30	643.5	134	494.5	300	492	53.5	479.5	5
EZS4-30M	673.5	164						
EZS4-40	743.5	134	594.5	400	592	53.5	579.5	6
EZS4-40M	773.5	164						
EZS4-50	843.5	134	694.5	500	692	53.5	679.5	7
EZS4-50M	873.5	164						

EZS Series

EZS6



■ Specifications

Model			EZS6-□CI			EZS6-□MCI		
		Incremental Type	EZS6-□CI			EZS6-□MCI		
		Absolute Type	EZS6-□CA			EZS6-□MCA		
Motor Type			Stepping Motor with Encoder					
Drive Method			Ball Screw					
Electromagnetic Brake			Not equipped			Equipped		
Speed Range		mm/s	～100	～200	～300	～100	～200	～300
Max. Transportable Mass	kg	Horizontal Direction	30	20	10	30	20	10
		Vertical Direction	—	—	—	10	8	3
Max. Acceleration	m/s²	Horizontal Direction	2			2		
		Vertical Direction	—			2		
Max. Thrust Force		N kgf	100 10	94 9.4	35 3.5	100 10	94 9.4	35 3.5
Max. Holding Brake Force	N kgf	Power ON	100 10			100 10		
		Power OFF	0			0		
		Electromagnetic Brake	—			100 10		
Repetitive Positioning Accuracy		mm	±0.02					
Resolution		mm	0.015					
Lead		mm	12					
Stroke		mm	100、150、200、250、300、400、500					
Slider Mass	Figure in the parentheses shows the mass of the model with electromagnetic brake.	kg	**Stroke** **100**：4.0 (4.4) **150**：4.3 (4.7) **200**：4.5 (4.9) **250**：4.7 (5.1) **300**：5.0 (5.4) **400**：5.5 (5.9) **500**：5.9 (6.3)					
Ambient Temperature		℃	0～+40 (Nonfreezing)					

●See page 52 for the specification and dimensions of the controller.

■ General Specifications

Item	Specification
Insulation Resistance	100 MΩ minimum when measured by a DC 500 V megger between the following places. • Windings — Case • Case — Windings of electromagnetic brake (Only for electromagnetic brake equipped model)
Dielectric Strength	Sufficient to withstand the following for one minute. • Windings — Case AC 1.0 kV 50 Hz • Case — Windings of electromagnetic brake AC 1.0 kV 50 Hz (Only for electromagnetic brake equipped model)

■ Slider/Controller Combinations

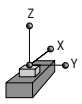
Type	Electromagnetic Brake	Model	Slider Model	Controller Model
Incremental Type	Not equipped	**EZS6-□CI**	EZS6-□	EZMC36I
	Equipped	**EZS6-□MCI**	EZS6-□M	
Absolute Type	Not equipped	**EZS6-□CA**	EZS6-□	EZMC36A
	Equipped	**EZS6-□MCA**	EZS6-□M	

*The box (□) in the model name and slider model name represents the code for stroke length.

■ Allowable Overhung Length (mm)

* The length from the center of load's mounting surface to the center of gravity of the object being carried.

• Horizontal Installation

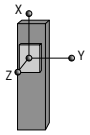


Carried Weight	X	Y	Z
10kg	500	414	500
20kg	386	207	500
30kg	257	137	500

• Wall Mount Installation

Carried Weight	X	Y	Z
10kg	100	490	414
20kg	50	245	179
30kg	33	163	100

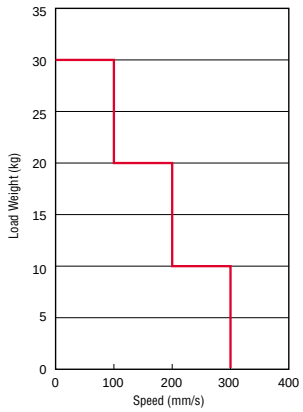
• Vertical Installation



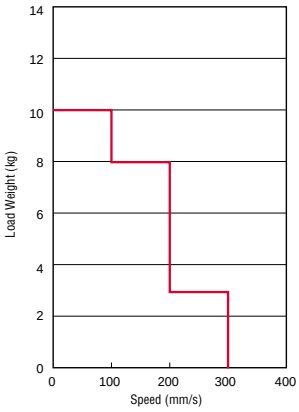
Carried Weight	X	Y	Z
3kg	500	277	500
8kg	500	104	500
10kg	500	83	500

Correlation Diagram of Speed and Load Weight

●Horizontal Direction



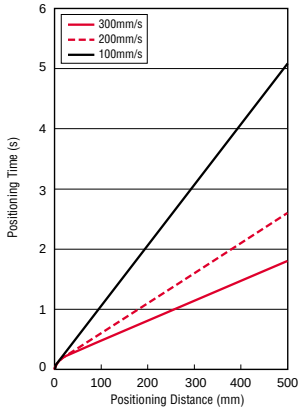
●Vertical Direction



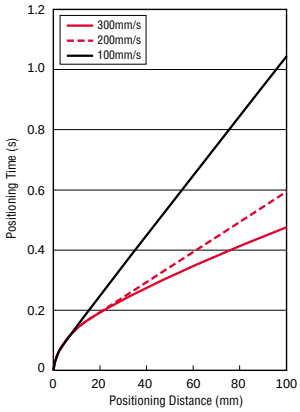
Minimum Positioning Time

Acceleration: 2 m/s² Starting Speed: 6 mm/s

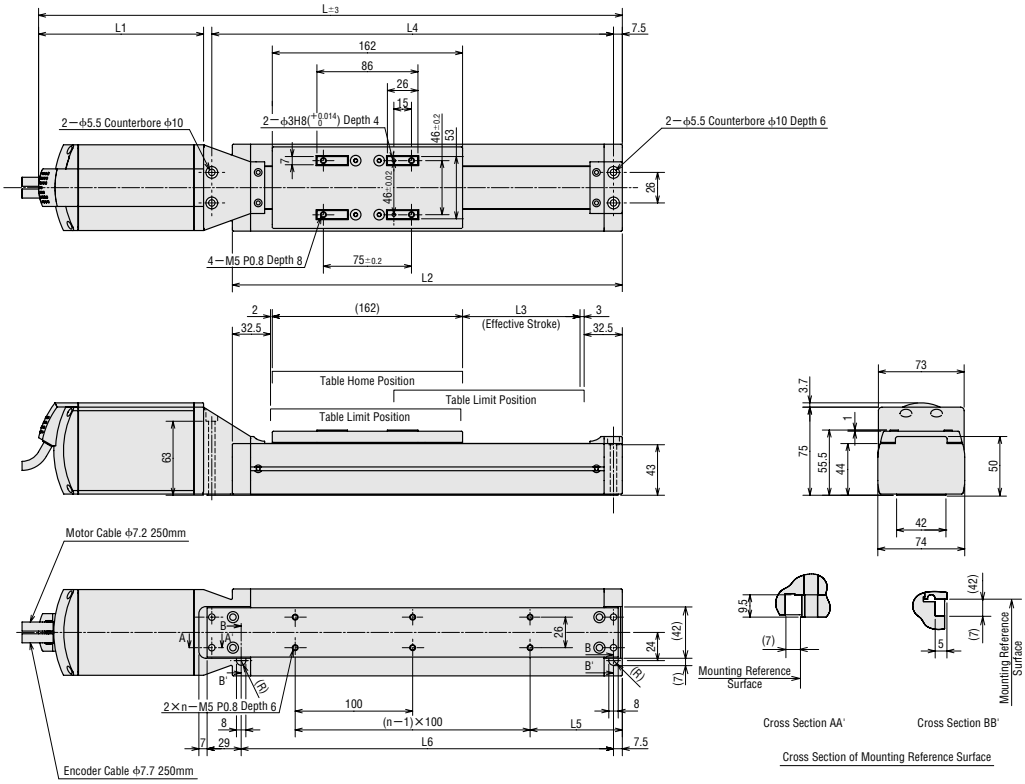
●Horizontal Direction/ Vertical Direction



Enlargement of Positioning Distance under 100 mm



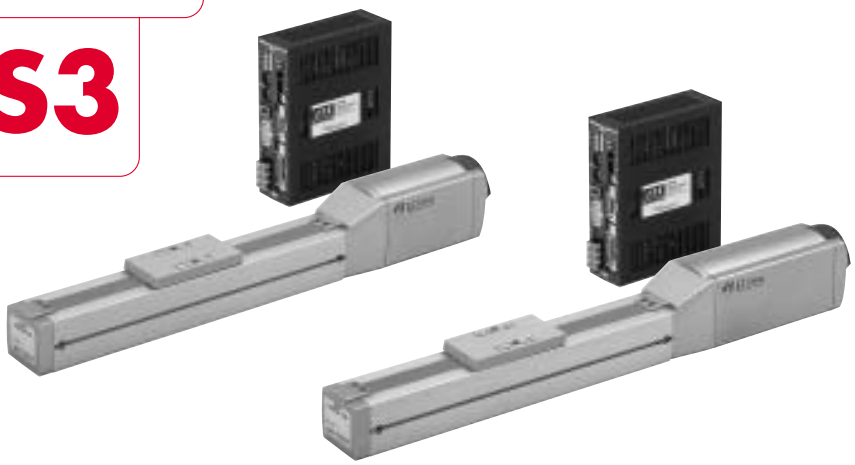
Dimensions unit: mm



Slider Model	L	L1	L2	L3	L4	L5	L6	n
EZS6-10	497	140.5	332	100	342	78.5	317	3
EZS6-10M	532	175.5						
EZS6-15	547	140.5	382	150	392	53.5	367	4
EZS6-15M	582	175.5						
EZS6-20	597	140.5	432	200	442	78.5	417	4
EZS6-20M	632	175.5						
EZS6-25	647	140.5	482	250	492	53.5	467	5
EZS6-25M	682	175.5						
EZS6-30	697	140.5	532	300	542	78.5	517	5
EZS6-30M	732	175.5						
EZS6-40	797	140.5	632	400	642	78.5	617	6
EZS6-40M	832	175.5						
EZS6-50	897	140.5	732	500	742	78.5	717	7
EZS6-50M	932	175.5						

EZHS Series

EZHS3



■ Specifications

Model		Incremental Type	EZHS3A-□I	EZHS3A-□MI
		Absolute Type	EZHS3A-□A	EZHS3A-□MA
Motor Type			Stepping Motor with Built-in Rotor-Position Sensor	
Drive Method			Ball Screw	
Electromagnetic Brake			Not equipped	Equipped
Speed Range		mm/s	～800	～800
Max. Transportable Mass	kg	Horizontal Direction	5	5
		Vertical Direction	—	2.5
Max. Acceleration	m/s²	Horizontal Direction	2.5	2.5
		Vertical Direction	—	2.5
Max. Thrust Force		N kgf	30 3	30 3
Max. Holding Brake Force	N kgf	Power ON	30 3	30 3
		Power OFF	0	0
		Electromagnetic Brake	—	30 3
Repetitive Positioning Accuracy		mm	±0.02	
Resolution		mm	0.01	
Lead		mm	12	
Stroke		mm	50、100、150、200、250、300、400、500	
Slider Mass (Figure in the parentheses shows the mass of the model with electromagnetic brake.)		kg	**Stroke** **50** : 1.6 (1.8) **100** : 1.7 (1.9) **150** : 1.8 (2.0) **200** : 1.9 (2.1) **250** : 2.0 (2.2) **300** : 2.1 (2.3) **400** : 2.3 (2.5) **500** : 2.5 (2.7)	
Ambient Temperature		℃	0～+40(Nonfreezing)	

●See page 54 for the specification and dimensions of the controller.

■ General Specifications

Item	Specification
Insulation Resistance	100 MΩ minimum when measured by a DC 500 V megger between the following places. • Windings — Case • Case — Windings of electromagnetic brake (Only for electromagnetic brake equipped model)
Dielectric Strength	Sufficient to withstand the following for one minute. • Windings — Case AC 1.0 kV 50 Hz • Case — Windings of electromagnetic brake AC 1.0 kV 50 Hz (Only for electromagnetic brake equipped model)

■ Slider/Controller Combinations

Type	Electromagnetic Brake	Model	Slider Model	Controller Model
Incremental Type	Not equipped	**EZHS3A-□I**	EZHS3A-□	EZMC13I-A
	Equipped	**EZHS3A-□MI**	EZHS3A-□M	
Absolute Type	Not equipped	**EZHS3A-□A**	EZHS3A-□	EZMC13A-A
	Equipped	**EZHS3A-□MA**	EZHS3A-□M	

*The box (□) in the model name and slider model name represents the code for stroke length.

■ Allowable Overhung Length (mm)

* The length from the center of load's mounting surface to the center of gravity of the object being carried.

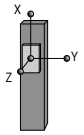
• Horizontal Installation

Carried Weight	X	Y	Z
1kg	203	300	300
2.5kg	73	123	288
5kg	30	50	118

• Wall Mount Installation

Carried Weight	X	Y	Z
1kg	155	300	298
2.5kg	62	243	93
5kg	19	75	25

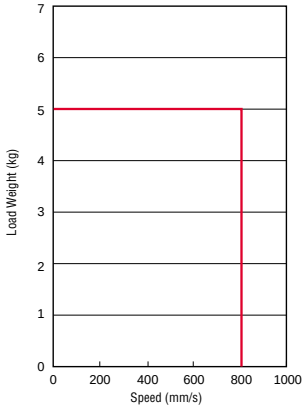
• Vertical Installation



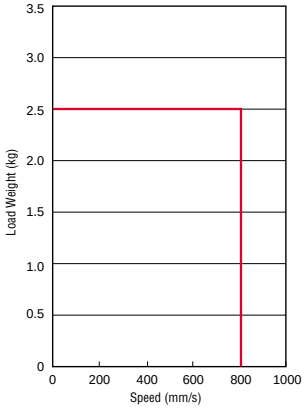
Carried Weight	X	Y	Z
1kg	135	124	135
2kg	58	58	48
2.5kg	37	37	31

Correlation Diagram of Speed and Load Weight

●Horizontal Direction



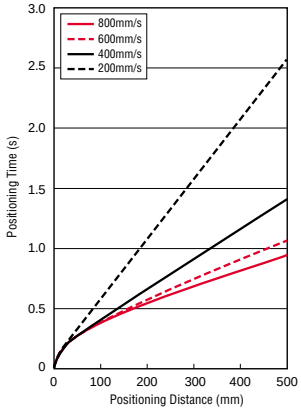
●Vertical Direction



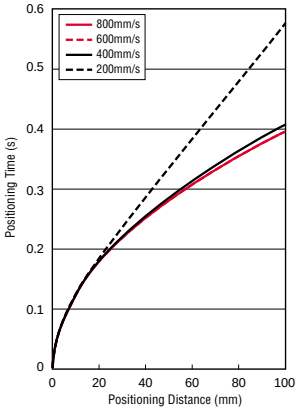
Minimum Positioning Time

Acceleration: 2.5 m/s² Starting Speed: 6 mm/s

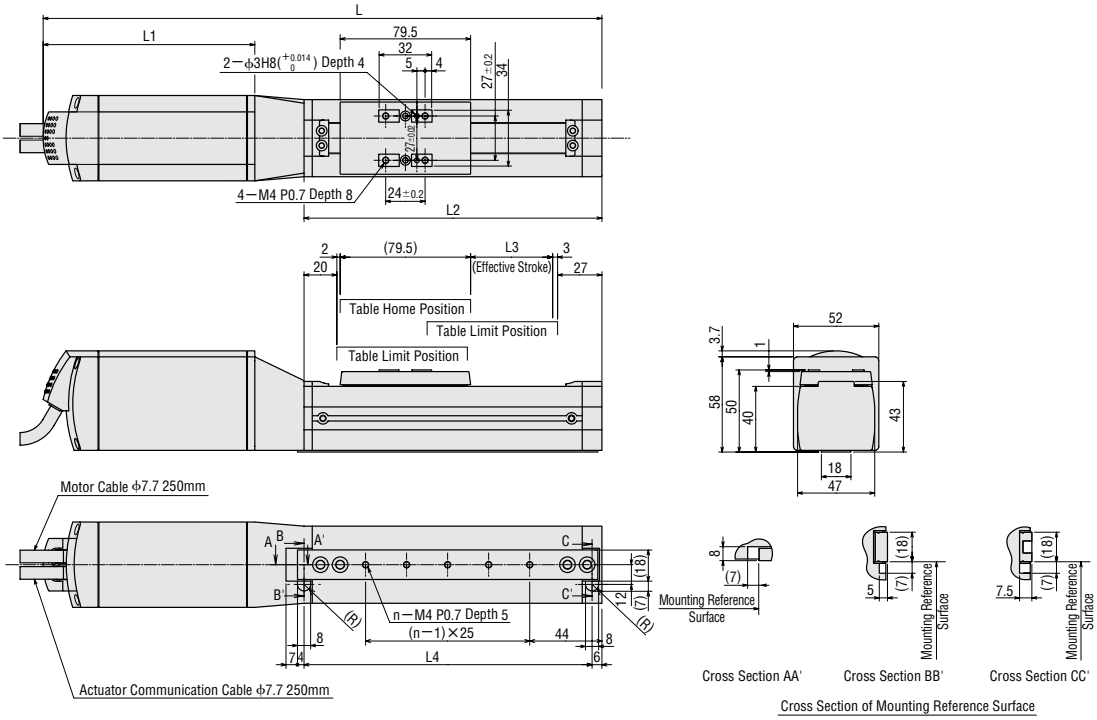
●Horizontal Direction/ Vertical Direction



Enlargement of Positioning Distance under 100 mm



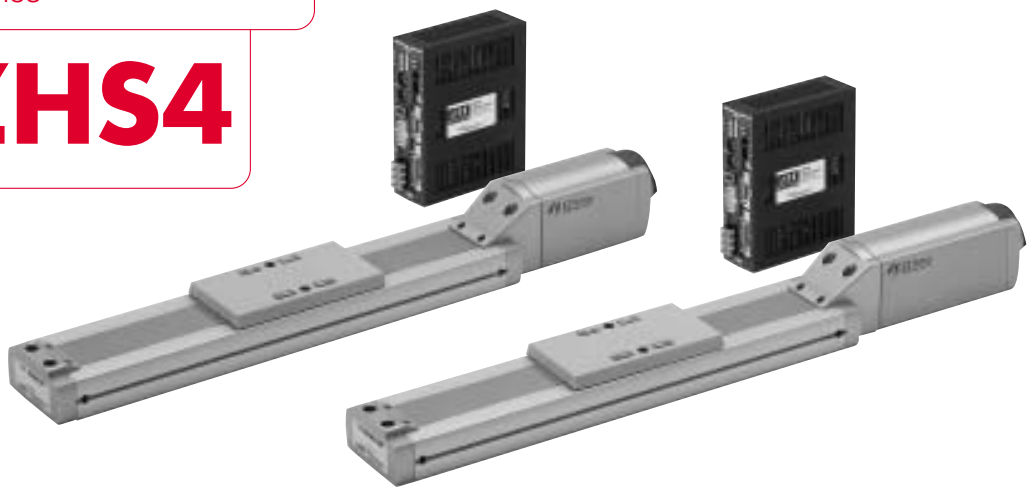
Dimensions unit: mm



Slider Model	L	L1	L2	L3	L4	n
EZHS3A-05	340.5	129	181.5	50	175.5	5
EZHS3A-05M	370.5	159				
EZHS3A-10	390.5	129	231.5	100	225.5	7
EZHS3A-10M	420.5	159				
EZHS3A-15	440.5	129	281.5	150	275.5	9
EZHS3A-15M	470.5	159				
EZHS3A-20	490.5	129	331.5	200	325.5	11
EZHS3A-20M	520.5	159				
EZHS3A-25	540.5	129	381.5	250	375.5	13
EZHS3A-25M	570.5	159				
EZHS3A-30	590.5	129	431.5	300	425.5	15
EZHS3A-30M	620.5	159				
EZHS3A-40	690.5	129	531.5	400	525.5	19
EZHS3A-40M	720.5	159				
EZHS3A-50	790.5	129	631.5	500	625.5	23
EZHS3A-50M	820.5	159				

EZHS Series

EZHS4



■ Specifications

Model		Incremental Type	EZHS4A-□I			EZHS4A-□MI		
		Absolute Type	EZHS4A-□A			EZHS4A-□MA		
Motor Type			Stepping Motor with Built-in Rotor-Position Sensor					
Drive Method			Ball Screw					
Electromagnetic Brake			Not equipped			Equipped		
Speed Range		mm/s	～400	～600	～800	～400	～600	～800
Max. Transportable Mass	kg	Horizontal Direction	15			15		
		Vertical Direction	—			7	4.5	3.5
Max. Acceleration	m/s²	Horizontal Direction	2.5			2.5		
		Vertical Direction	—			2.5		
Max. Thrust Force		N kgf	70 7	55 5.5	43 4.3	70 7	55 5.5	43 4.3
Max. Holding Brake Force	N kgf	Power ON	70 7			70 7		
		Power OFF	0			0		
		Electromagnetic Brake	—			70 7		
Repetitive Positioning Accuracy		mm	±0.02					
Resolution		mm	0.01					
Lead		mm	12					
Stroke		mm	50、100、150、200、250、300、400、500					
Slider Mass (Figure in the parentheses shows the mass of the model with electromagnetic brake.)		kg	**Stroke**	**50** : 2.4 (2.6)	**100** : 2.6 (2.8)	**150** : 2.8 (3.0)	**200** : 3.0 (3.2)	
				250 : 3.2 (3.4)	**300** : 3.4 (3.6)	**400** : 3.8 (4.0)	**500** : 4.2 (4.4)	
Ambient Temperature		℃	0～+40 (Nonfreezing)					

●See page 54 for the specification and dimensions of the controller.

■ General Specifications

Item	Specification
Insulation Resistance	100 MΩ minimum when measured by a DC 500 V megger between the following places. • Windings — Case • Case — Windings of electromagnetic brake (Only for electromagnetic brake equipped model)
Dielectric Strength	Sufficient to withstand the following for one minute. • Windings — Case AC 1.0 kV 50 Hz • Case — Windings of electromagnetic brake AC 1.0 kV 50 Hz (Only for electromagnetic brake equipped model)

■ Slider/Controller Combinations

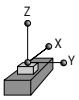
Type	Electromagnetic Brake	Model	Slider Model	Controller Model
Incremental Type	Not equipped	**EZHS4A-□I**	EZHS4A-□	EZMC13I-A
	Equipped	**EZHS4A-□MI**	EZHS4A-□M	
Absolute Type	Not equipped	**EZHS4A-□A**	EZHS4A-□	EZMC13A-A
	Equipped	**EZHS4A-□MA**	EZHS4A-□M	

*The box (□) in the model name and slider model name represents the code for stroke length.

■ Allowable Overhung Length (mm)

* The length from the center of load's mounting surface to the center of gravity of the object being carried.

• Horizontal Installation

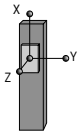


Carried Weight	X	Y	Z
5kg	158	108	300
10kg	73	54	286
15kg	45	36	175

• Wall Mount Installation

Carried Weight	X	Y	Z
5kg	28	108	300
10kg	14	54	132
15kg	9	36	76

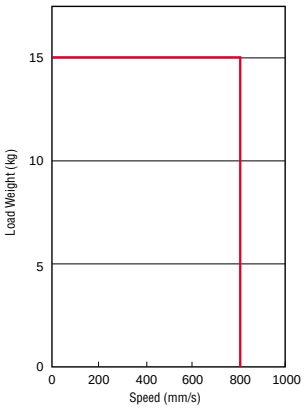
• Vertical Installation



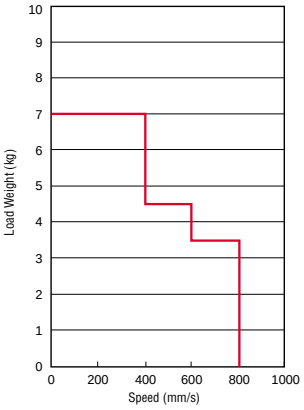
Carried Weight	X	Y	Z
3.5kg	166	31	166
4.5kg	123	24	123
7kg	69	16	69

Correlation Diagram of Speed and Load Weight

●Horizontal Direction



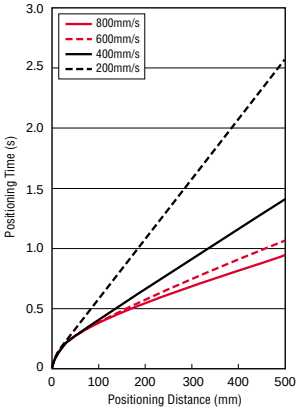
●Vertical Direction



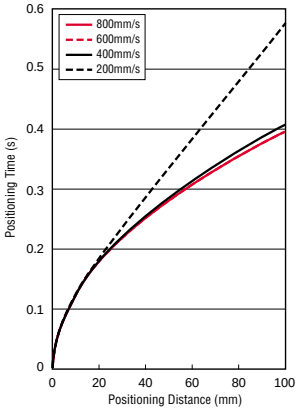
Minimum Positioning Time

Acceleration: 2.5 m/s² Starting Speed: 6 mm/s

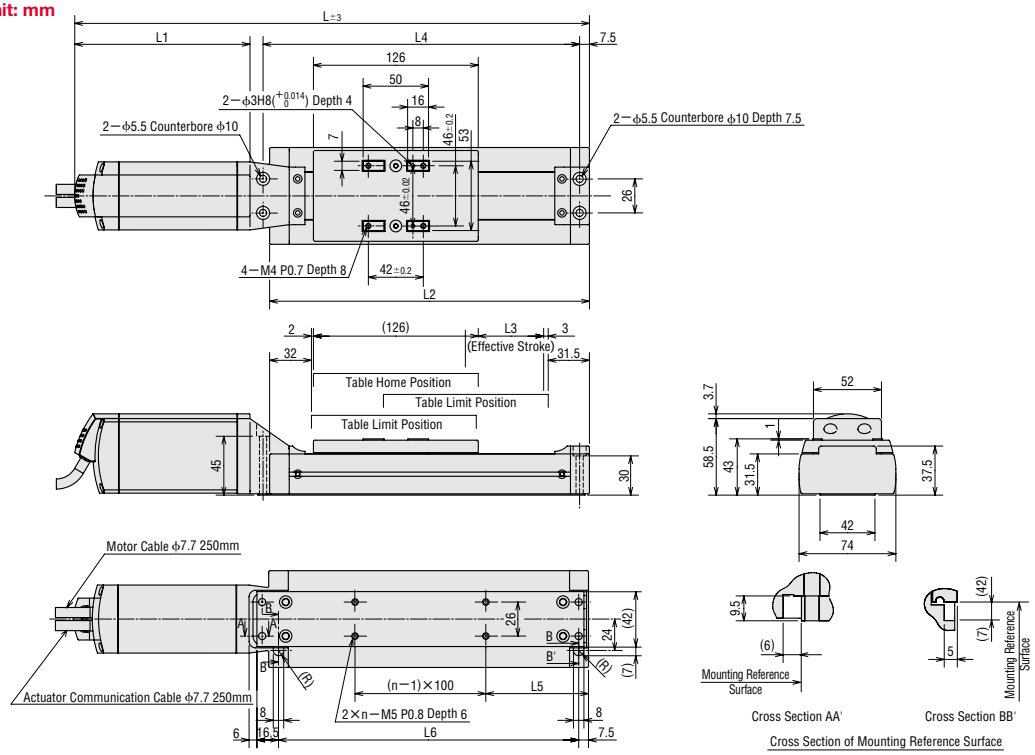
●Horizontal Direction/ Vertical Direction



Enlargement of Positioning Distance under 100 mm



Dimensions unit: mm



Slider Model	L	L1	L2	L3	L4	L5	L6	n
EZHS4A-05	393.5	134	244.5	50	242	78.5	229.5	2
EZHS4A-05M	423.5	164						
EZHS4A-10	443.5	134	294.5	100	292	53.5	279.5	3
EZHS4A-10M	473.5	164						
EZHS4A-15	493.5	134	344.5	150	342	78.5	329.5	3
EZHS4A-15M	523.5	164						
EZHS4A-20	543.5	134	394.5	200	392	53.5	379.5	4
EZHS4A-20M	573.5	164						
EZHS4A-25	593.5	134	444.5	250	442	78.5	429.5	4
EZHS4A-25M	623.5	164						
EZHS4A-30	643.5	134	494.5	300	492	53.5	479.5	5
EZHS4A-30M	673.5	164						
EZHS4A-40	743.5	134	594.5	400	592	53.5	579.5	6
EZHS4A-40M	773.5	164						
EZHS4A-50	843.5	134	694.5	500	692	53.5	679.5	7
EZHS4A-50M	873.5	164						

EZHS Series

EZHS6

■ Specifications

Model		Incremental Type	EZHS6A-□I、EZHS6C-□I			EZHS6A-□MI、EZHS6C-□MI		
		Absolute Type	EZHS6A-□A、EZHS6C-□A			EZHS6A-□MA、EZHS6C-□MA		
Motor Type			Stepping Motor with Built-in Rotor-Position Sensor					
Drive Method			Ball Screw					
Electromagnetic Brake			Not equipped			Equipped		
Speed Range		mm/s	～400	～600	～800	～400	～600	～800
Max. Transportable Mass	kg	Horizontal Direction	30		20	30		20
		Vertical Direction	—		—	15	7.5	3.5
Max. Acceleration	m/s²	Horizontal Direction	2.5			2.5		
		Vertical Direction	—			2.5		
Max. Thrust Force	N kgf		184 18.4	92 9.2	50 5	184 18.4	92 9.2	50 5
Max. Holding Brake Force	N kgf	Power ON	184 18.4			184 18.4		
		Power OFF	0			0		
		Electromagnetic Brake	—			184 18.4		
Repetitive Positioning Accuracy		mm	±0.02					
Resolution		mm	0.01					
Lead		mm	12					
Stroke		mm	100、150、200、250、300、400、500					
Slider Mass	Figure in the parentheses shows the mass of the model with electromagnetic brake.	kg	**Stroke**	**100**：4.1 (4.5)	**150**：4.4 (4.8)	**200**：4.6 (5.0)	**250**：4.8 (5.2)	**300**：5.1 (5.5) **400**：5.6 (6.0) **500**：6.0 (6.4)
Ambient Temperature		℃	0～+40 (Nonfreezing)					

●See page 54 for the specification and dimensions of the controller.

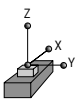
■ General Specifications

Item	Specification
Insulation Resistance	100 MΩ minimum when measured by a DC 500 V megger between the following places. • Windings — Case • Case — Windings of electromagnetic brake (Only for electromagnetic brake equipped model)
Dielectric Strength	Sufficient to withstand the following for one minute. • Windings — Case AC 1.5 kV 50 Hz • Case — Windings of electromagnetic brake AC 1.0 kV 50 Hz (Only for electromagnetic brake equipped model)

■ Allowable Overhung Length (mm)

* The length from the center of load's mounting surface to the center of gravity of the object being carried.

• Horizontal Installation

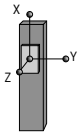


Carried Weight	X	Y	Z
10kg	500	392	500
20kg	386	196	500
30kg	257	131	500

• Wall Mount Installation

Carried Weight	X	Y	Z
10kg	100	392	414
20kg	50	196	207
30kg	33	131	138

• Vertical Installation



Carried Weight	X	Y	Z
3.5kg	500	228	500
7.5kg	500	106	500
15kg	410	53	410

■ Slider/Controller Combinations

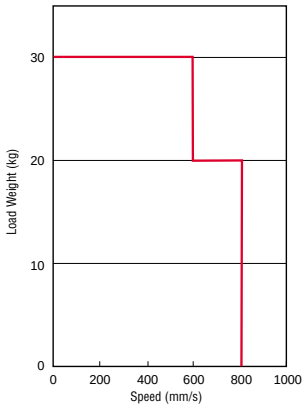
Type	Electromagnetic Brake	Model	Slider Model	Controller Model
Incremental Type	Not equipped	**EZHS6A-□I**	EZHS6A-□	EZMC24I-A
		EZHS6C-□I	EZHS6C-□	EZMC12I-C
	Equipped	**EZHS6A-□MI**	EZHS6A-□M	EZMC24I-A
		EZHS6C-□MI	EZHS6C-□M	EZMC12I-C

Type	Electromagnetic Brake	Model	Slider Model	Controller Model
Absolute Type	Not equipped	**EZHS6A-□A**	EZHS6A-□	EZMC24A-A
		EZHS6C-□A	EZHS6C-□	EZMC12A-C
	Equipped	**EZHS6A-□MA**	EZHS6A-□M	EZMC24A-A
		EZHS6C-□MA	EZHS6C-□M	EZMC12A-C

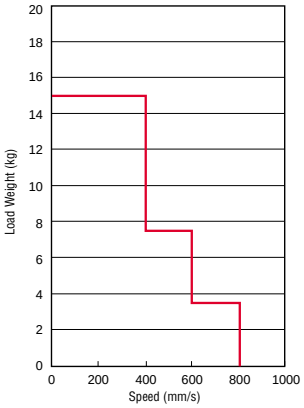
*The box (□) in the model name and slider model name represents the code for stroke length.

Correlation Diagram of Speed and Load Weight

●Horizontal Direction



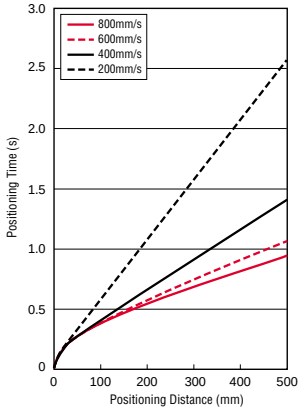
●Vertical Direction



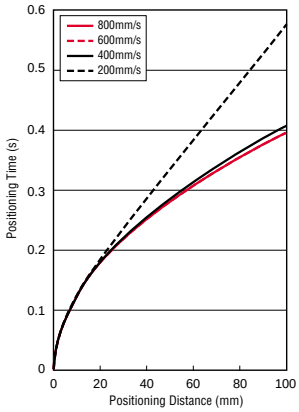
Minimum Positioning Time

Acceleration: 2.5 m/s² Starting Speed: 6 mm/s

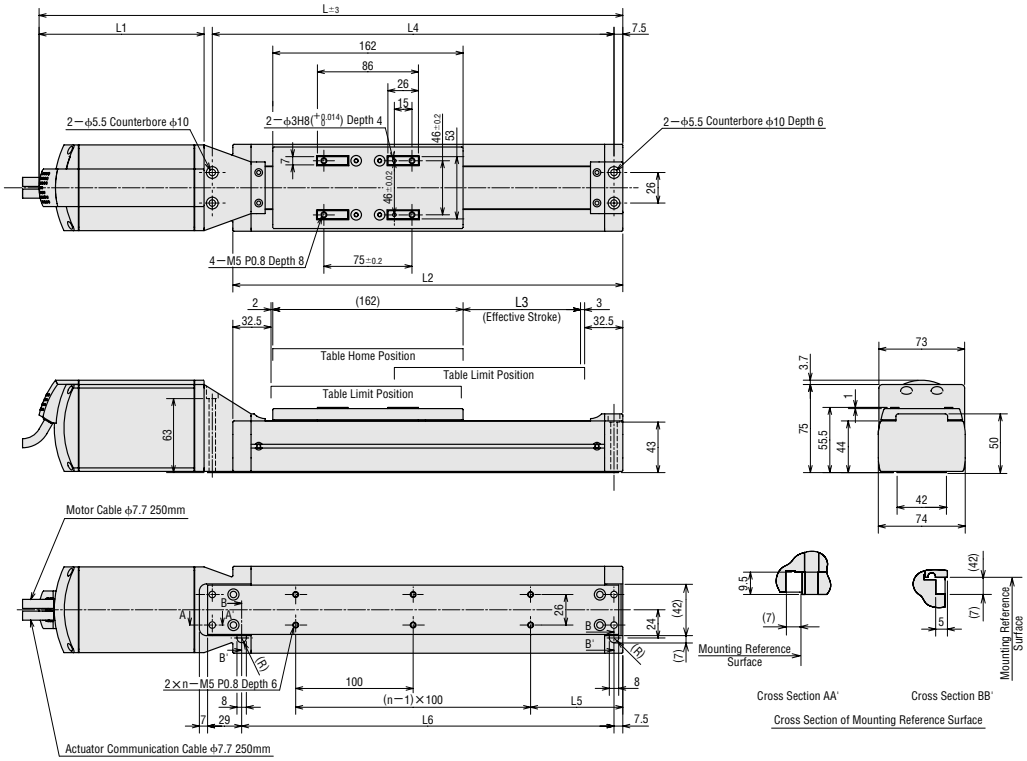
●Horizontal Direction/ Vertical Direction



Enlargement of Positioning Distance under 100 mm



Dimensions unit: mm

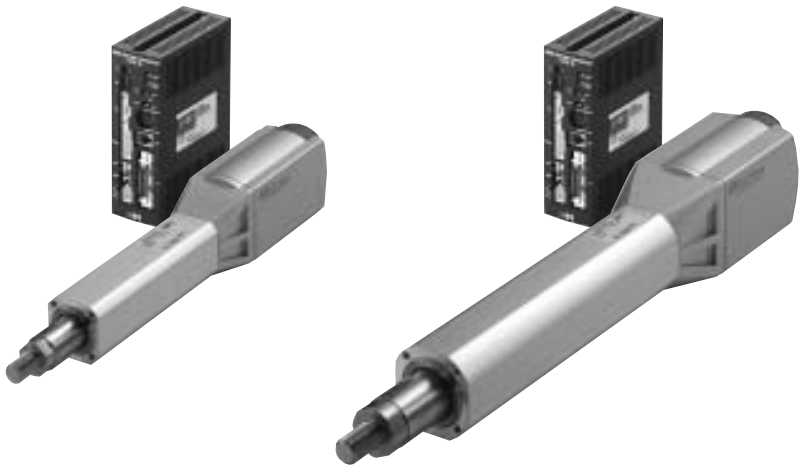


Slider Model	L	L1	L2	L3	L4	L5	L6	n
EZHS6□-10	497	140.5	332	100	342	78.5	317	3
EZHS6□-10M	532	175.5						
EZHS6□-15	547	140.5	382	150	392	53.5	367	4
EZHS6□-15M	582	175.5						
EZHS6□-20	597	140.5	432	200	442	78.5	417	4
EZHS6□-20M	632	175.5						
EZHS6□-25	647	140.5	482	250	492	53.5	467	5
EZHS6□-25M	682	175.5						
EZHS6□-30	697	140.5	532	300	542	78.5	517	5
EZHS6□-30M	732	175.5						
EZHS6□-40	797	140.5	632	400	642	78.5	617	6
EZHS6□-40M	832	175.5						
EZHS6□-50	897	140.5	732	500	742	78.5	717	7
EZHS6□-50M	932	175.5						

* Enter the power supply voltage **A** or **C** in the box (□) within the cylinder model name.

EZC Series
EZHC Series
EZHP Series

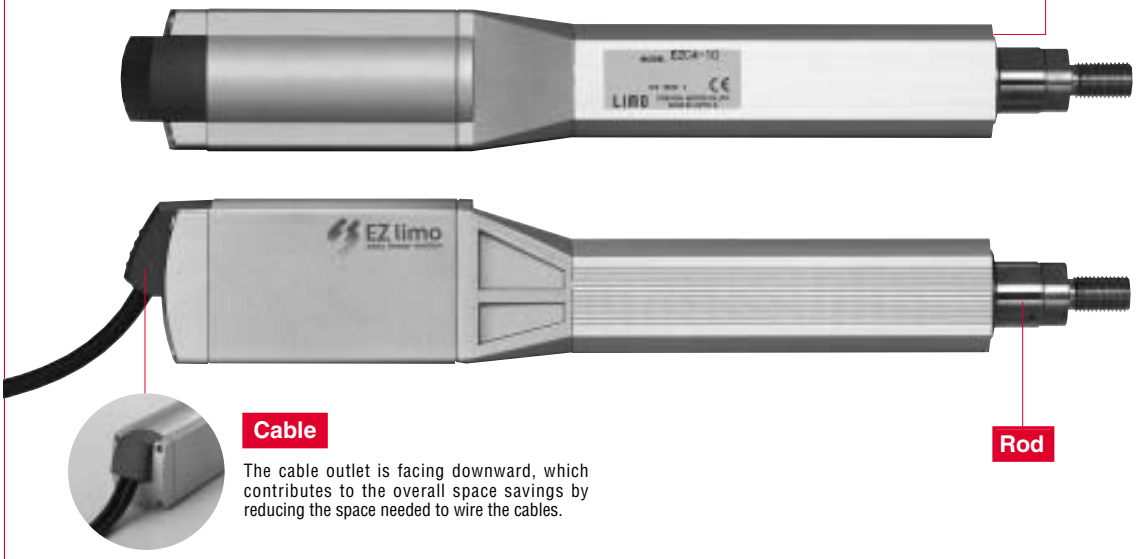
EZC Series



Names and Functions of the Cylinder

Mounting holes

The cylinder can be installed through the dedicated mounting holes, or via flange connection using an optional mounting bracket.

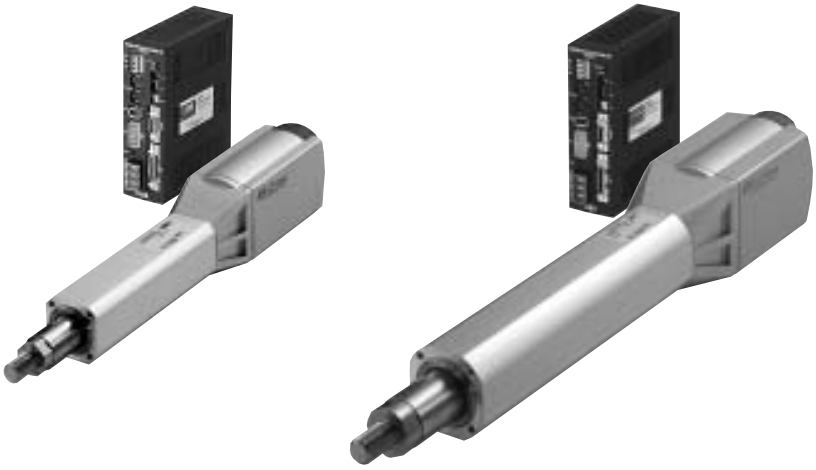


Cable

The cable outlet is facing downward, which contributes to the overall space savings by reducing the space needed to wire the cables.

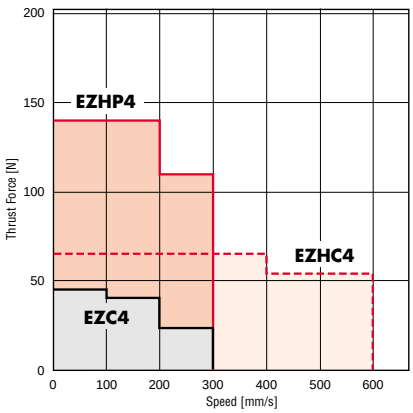
Rod

EZHC Series
EZHP Series

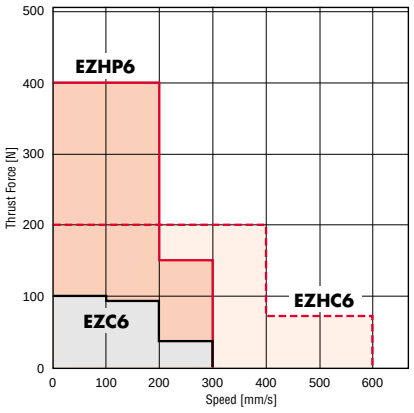


■ Motorized Cylinder Speed – Thrust Force Characteristics

EZC4/EZHC4/EZHP4



EZC6/EZHC6/EZHP6



■ Models

●EZC Series

◇Incremental Type

Without Electromagnetic Brake 24 VDC Input

Stroke	Model	
50mm	**EZC4-05CI**	**EZC6-05CI**
100mm	**EZC4-10CI**	**EZC6-10CI**
200mm	**EZC4-20CI**	**EZC6-20CI**
300mm	**EZC4-30CI**	**EZC6-30CI**

With Electromagnetic Brake 24 VDC Input

Stroke	Model	
50mm	**EZC4-05MCI**	**EZC6-05MCI**
100mm	**EZC4-10MCI**	**EZC6-10MCI**
200mm	**EZC4-20MCI**	**EZC6-20MCI**
300mm	**EZC4-30MCI**	**EZC6-30MCI**

◇Absolute Type

Without Electromagnetic Brake 24 VDC Input

Stroke	Model	
50mm	**EZC4-05CA**	**EZC6-05CA**
100mm	**EZC4-10CA**	**EZC6-10CA**
200mm	**EZC4-20CA**	**EZC6-20CA**
300mm	**EZC4-30CA**	**EZC6-30CA**

With Electromagnetic Brake 24 VDC Input

Stroke	Model	
50mm	**EZC4-05MCA**	**EZC6-05MCA**
100mm	**EZC4-10MCA**	**EZC6-10MCA**
200mm	**EZC4-20MCA**	**EZC6-20MCA**
300mm	**EZC4-30MCA**	**EZC6-30MCA**

■ Product Number Code

●EZC Series

EZC ① **4** ② **-** **10** ③ **M** ④ **C** ⑤ **I** ⑥

①	**EZC** Series	④	None：Without Electromagnetic Brake **M** ：With Electromagnetic Brake
②	Cylinder Size	⑤	With Controller
③	Stroke **05**： 50mm **10**：100mm **20**：200mm **30**：300mm	⑥	**I** ：Incremental Type **A**：Absolute Type

●EZHC Series、EZHP Series

EZHC ① **4** ② **A** ③ **-** **10** ④ **M** ⑤ **I** ⑥

①	**EZHC**: **EZHC** Series **EZHP**: **EZHP** Series	④	Stroke **05**： 50mm **10**：100mm **20**：200mm **30**：300mm
②	Cylinder Size	⑤	None：Without Electromagnetic Brake **M** ：With Electromagnetic Brake
③	Power Supply **A** ： Single-Phase 100-115V **C** ： Single-Phase 200-230V	⑥	**I** ： Incremental Type **A** ： Absolute Type

●EZHC Series

◇Incremental Type

Without Electromagnetic Brake Single-Phase 100-115 V Input

Stroke	Model	
50mm	**EZHC4A-05I**	**EZHC6A-05I**
100mm	**EZHC4A-10I**	**EZHC6A-10I**
200mm	**EZHC4A-20I**	**EZHC6A-20I**
300mm	**EZHC4A-30I**	**EZHC6A-30I**

Single-Phase 200-230 V Input

Stroke	Model
50mm	**EZHC6C-05I**
100mm	**EZHC6C-10I**
200mm	**EZHC6C-20I**
300mm	**EZHC6C-30I**

With Electromagnetic Brake Single-Phase 100-115 V Input

Stroke	Model	
50mm	**EZHC4A-05MI**	**EZHC6A-05MI**
100mm	**EZHC4A-10MI**	**EZHC6A-10MI**
200mm	**EZHC4A-20MI**	**EZHC6A-20MI**
300mm	**EZHC4A-30MI**	**EZHC6A-30MI**

Single-Phase 200-230 V Input

Stroke	Model
50mm	**EZHC6C-05MI**
100mm	**EZHC6C-10MI**
200mm	**EZHC6C-20MI**
300mm	**EZHC6C-30MI**

◇Absolute Type

Without Electromagnetic Brake Single-Phase 100-115 V Input

Stroke	Model	
50mm	**EZHC4A-05A**	**EZHC6A-05A**
100mm	**EZHC4A-10A**	**EZHC6A-10A**
200mm	**EZHC4A-20A**	**EZHC6A-20A**
300mm	**EZHC4A-30A**	**EZHC6A-30A**

Single-Phase 200-230 V Input

Stroke	Model
50mm	**EZHC6C-05A**
100mm	**EZHC6C-10A**
200mm	**EZHC6C-20A**
300mm	**EZHC6C-30A**

With Electromagnetic Brake Single-Phase 100-115 V Input

Stroke	Model	
50mm	**EZHC4A-05MA**	**EZHC6A-05MA**
100mm	**EZHC4A-10MA**	**EZHC6A-10MA**
200mm	**EZHC4A-20MA**	**EZHC6A-20MA**
300mm	**EZHC4A-30MA**	**EZHC6A-30MA**

Single-Phase 200-230 V Input

Stroke	Model
50mm	**EZHC6C-05MA**
100mm	**EZHC6C-10MA**
200mm	**EZHC6C-20MA**
300mm	**EZHC6C-30MA**

●EZHP Series

◇Incremental Type

Without Electromagnetic Brake Single-Phase 100-115V Input

Stroke	Model	
50mm	**EZHP4A-05I**	**EZHP6A-05I**
100mm	**EZHP4A-10I**	**EZHP6A-10I**
200mm	**EZHP4A-20I**	**EZHP6A-20I**
300mm	**EZHP4A-30I**	**EZHP6A-30I**

Single-Phase 200-230V Input

Stroke	Model
50mm	**EZHP6C-05I**
100mm	**EZHP6C-10I**
200mm	**EZHP6C-20I**
300mm	**EZHP6C-30I**

With Electromagnetic Brake Single-Phase 100-115V Input

Stroke	Model	
50mm	**EZHP4A-05MI**	**EZHP6A-05MI**
100mm	**EZHP4A-10MI**	**EZHP6A-10MI**
200mm	**EZHP4A-20MI**	**EZHP6A-20MI**
300mm	**EZHP4A-30MI**	**EZHP6A-30MI**

Single-Phase 200-230V Input

Stroke	Model
50mm	**EZHP6C-05MI**
100mm	**EZHP6C-10MI**
200mm	**EZHP6C-20MI**
300mm	**EZHP6C-30MI**

◇Absolute Type

Without Electromagnetic Brake Single-Phase 100-115V Input

Stroke	Model	
50mm	**EZHP4A-05A**	**EZHP6A-05A**
100mm	**EZHP4A-10A**	**EZHP6A-10A**
200mm	**EZHP4A-20A**	**EZHP6A-20A**
300mm	**EZHP4A-30A**	**EZHP6A-30A**

Single-Phase 200-230V Input

Stroke	Model
50mm	**EZHP6C-05A**
100mm	**EZHP6C-10A**
200mm	**EZHP6C-20A**
300mm	**EZHP6C-30A**

With Electromagnetic Brake Single-Phase 100-115V Input

Stroke	Model	
50mm	**EZHP4A-05MA**	**EZHP6A-05MA**
100mm	**EZHP4A-10MA**	**EZHP6A-10MA**
200mm	**EZHP4A-20MA**	**EZHP6A-20MA**
300mm	**EZHP4A-30MA**	**EZHP6A-30MA**

Single-Phase 200-230V Input

Stroke	Model
50mm	**EZHP6C-05MA**
100mm	**EZHP6C-10MA**
200mm	**EZHP6C-20MA**
300mm	**EZHP6C-30MA**

EZC Series

EZC4

Specifications

Model	Incremental Type	EZC4-□CI			EZC4-□MCI		
	Absolute Type	EZC4-□CA			EZC4-□MCA		
Motor Type		Stepping Motor with Encoder					
Drive Method		Ball Screw					
Electromagnetic Brake		Not equipped			Equipped		
Speed Range	mm/s	～100	～200	～300	～100	～200	～300
Max. Transportable Mass	kg Horizontal Direction*	—	—	—	—	—	—
	kg Vertical Direction	—	—	—	4.5	4	2
Max. Acceleration	m/s² Horizontal Direction	—			—		
	m/s² Vertical Direction	—			2		
Max. Thrust Force	N kgf	45 4.5	40 4	23 2.3	45 4.5	40 4	23 2.3
Push Force	N kgf	45 4.5 (Speed: 6 mm/s or less)					
Max. Holding Brake Force	N kgf Power ON	45 4.5			45 4.5		
	N kgf Power OFF	0			0		
	N kgf Electromagnetic Brake	—			45 4.5		
Repetitive Positioning Accuracy	mm	±0.02					
Resolution	mm	0.015					
Lead	mm	12					
Stroke	mm	50、100、200、300					
Cylinder Mass (Figure in the parentheses shows the mass of the model with electromagnetic brake.)	kg	**Stroke**	**50**：1.6 (1.8)	**100**：1.9 (2.1)	**200**：2.4 (2.6)	**300**：2.9 (3.1)	
Ambient Temperature	℃	0～+40 (Nonfreezing)					

*In a horizontal direction, the value cannot be shown because it varies by frictional resistance of the sliding surface.
●See page 52 for the specification and dimensions of the controller.

General Specifications

Item	Specification
Insulation Resistance	100 MΩ minimum when measured by a DC 500 V megger between the following places. • Windings — Case • Case — Windings of electromagnetic brake (Only for electromagnetic brake equipped model)
Dielectric Strength	Sufficient to withstand the following for one minute. • Windings — Case AC 0.5 kV 50 Hz • Case — Windings of electromagnetic brake AC 0.5 kV 50 Hz (Only for electromagnetic brake equipped model)

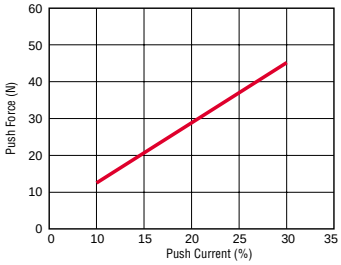
Cylinder/Controller Combinations

Type	Electromagnetic Brake	Model	Cylinder Model	Controller Model
Incremental Type	Not equipped	**EZC4-□CI**	EZC4-□	EZMC36I
	Equipped	**EZC4-□MCI**	EZC4-□M	
Absolute Type	Not equipped	**EZC4-□CA**	EZC4-□	EZMC36A
	Equipped	**EZC4-□MCA**	EZC4-□M	

*The box (□) in the model name and cylinder model name represents the code for stroke length.

Push Force

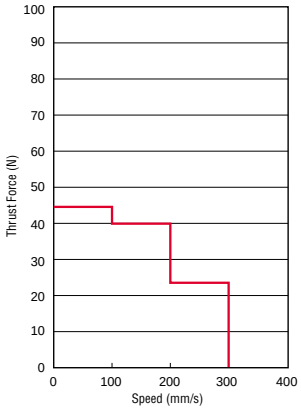
Push force can be set through "Push current setting" in the parameter mode.



Notes:
- The above value is a reference, not guaranteed.
- When the cylinder is used in a vertical direction, an external force calculated by multiplying the weight of the carried object by the rate of gravitational acceleration is applied. Therefore, the cylinder push force must be set so as to accommodate this external force. Measure the push force using an actual load, and set an appropriate push current.

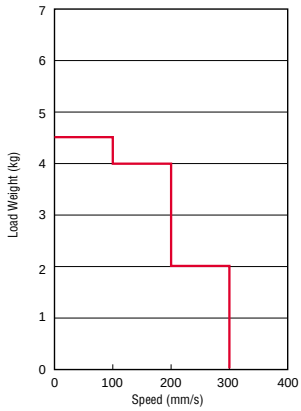
Correlation Diagram of Speed and Thrust Force

●Horizontal Direction/ Vertical Direction



Correlation Diagram of Speed and Load Weight

●Vertical Direction

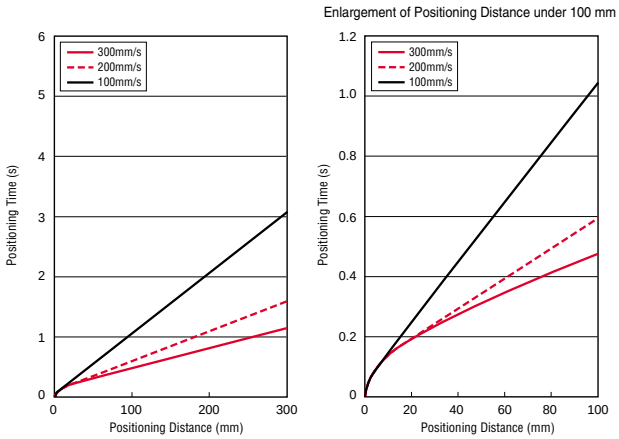


Minimum Positioning Time

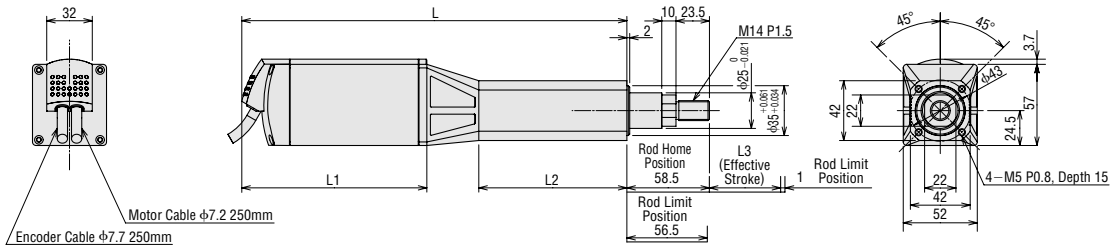
Acceleration: 2 m/s² Starting Speed: 6 mm/s

●Horizontal Direction/ Vertical Direction

Enlargement of Positioning Distance under 100 mm



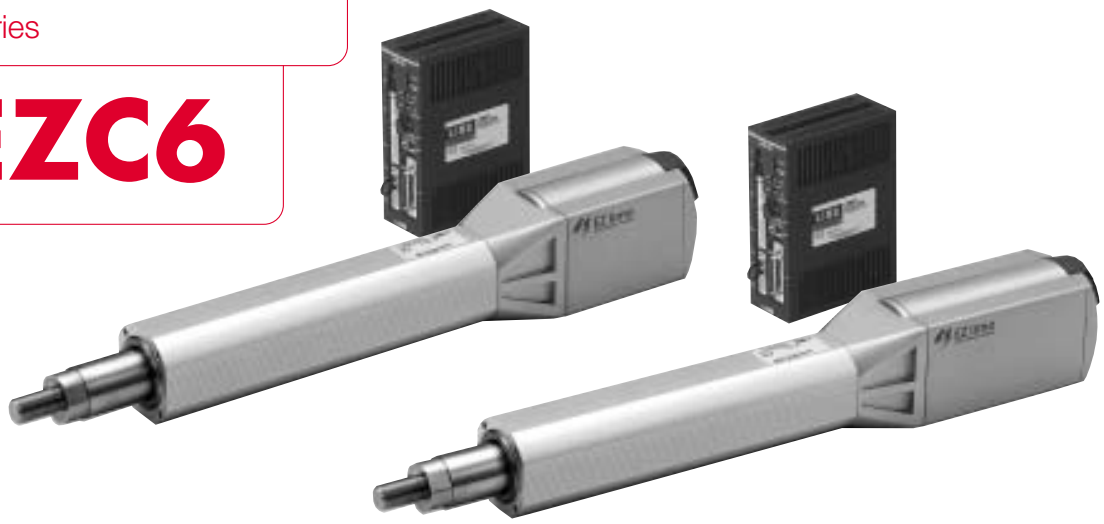
Dimensions unit: mm



Cylinder Model	L	L1	L2	L3
EZC4-05	270.5	130	104	50
EZC4-05M	300.5	160		
EZC4-10	320.5	130	154	100
EZC4-10M	350.5	160		
EZC4-20	420.5	130	254	200
EZC4-20M	450.5	160		
EZC4-30	520.5	130	354	300
EZC4-30M	550.5	160		

EZC Series

EZC6



Specifications

Model			EZC6-□CI			EZC6-□MCI		
	Incremental Type							
	Absolute Type		EZC6-□CA			EZC6-□MCA		
Motor Type			Stepping Motor with Encoder					
Drive Method			Ball Screw					
Electromagnetic Brake			Not equipped			Equipped		
Speed Range		mm/s	～100	～200	～300	～100	～200	～300
Max. Transportable Mass	kg	Horizontal Direction*	—	—	—	—	—	—
		Vertical Direction	—	—	—	10	8	3
Max. Acceleration	m/s²	Horizontal Direction	—			—		
		Vertical Direction	—			2		
Max. Thrust Force		N kgf	100 10	94 9.4	35 3.5	100 10	94 9.4	35 3.5
Push Force		N kgf	100 10 (Speed: 6 mm/s or less)					
Max. Holding Brake Force	N kgf	Power ON	100 10			100 10		
		Power OFF	0			0		
		Electromagnetic Brake	—			100 10		
Repetitive Positioning Accuracy		mm	±0.02					
Resolution		mm	0.015					
Lead		mm	12					
Stroke		mm	50、100、200、300					
Cylinder Mass	Figure in the parentheses shows the mass of the model with electromagnetic brake.	kg	**Stroke**	**50**：3.2 (3.6)	**100**：3.6 (4.0)	**200**：4.5 (4.9)	**300**：5.5 (5.9)	
Ambient Temperature		℃	0～＋40(Nonfreezing)					

*In a horizontal direction, the value cannot be shown because it varies by frictional resistance of the sliding surface.
●See page 52 for the specification and dimensions of the controller.

General Specifications

Item	Specification
Insulation Resistance	100 MΩ minimum when measured by a DC 500 V megger between the following places. • Windings — Case • Case — Windings of electromagnetic brake (Only for electromagnetic brake equipped model)
Dielectric Strength	Sufficient to withstand the following for one minute. • Windings — Case AC 1.0 kV 50 Hz • Case — Windings of electromagnetic brake AC 1.0 kV 50 Hz (Only for electromagnetic brake equipped model)

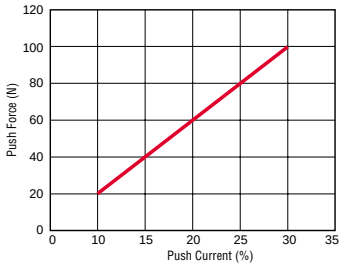
Cylinder/Controller Combinations

Type	Electromagnetic Brake	Model	Cylinder Model	Controller Model
Incremental Type	Not equipped	**EZC6-□CI**	EZC6-□	EZMC36I
	Equipped	**EZC6-□MCI**	EZC6-□M	
Absolute Type	Not equipped	**EZC6-□CA**	EZC6-□	EZMC36A
	Equipped	**EZC6-□MCA**	EZC6-□M	

*The box (□) in the model name and cylinder model name represents the code for stroke length.

Push Force

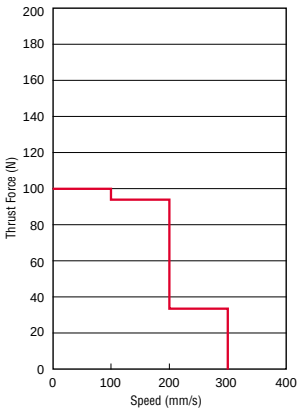
Push force can be set through "Push current setting" in the parameter mode.



Notes:
- The above value is a reference, not guaranteed.
- When the cylinder is used in a vertical direction, an external force calculated by multiplying the weight of the carried object by the rate of gravitational acceleration is applied. Therefore, the cylinder push force must be set so as to accommodate this external force. Measure the push force using an actual load, and set an appropriate push current.

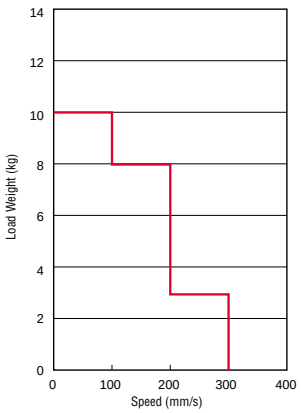
Correlation Diagram of Speed and Thrust Force

●Horizontal Direction/ Vertical Direction



Correlation Diagram of Speed and Load Weight

●Vertical Direction

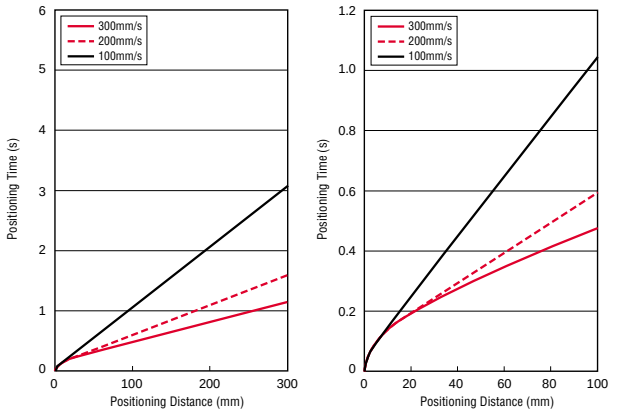


Minimum Positioning Time

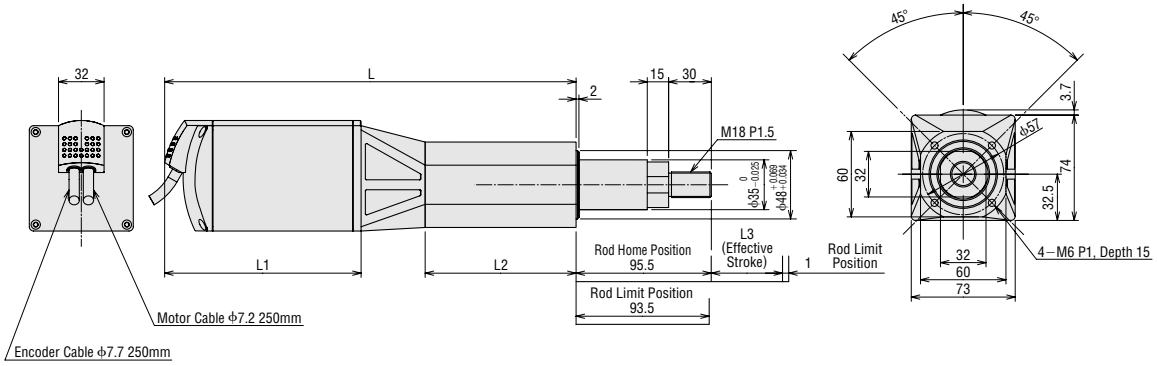
Acceleration: 2 m/s² Starting Speed: 6 mm/s

●Horizontal Direction/ Vertical Direction

Enlargement of Positioning Distance under 100 mm



Dimensions unit: mm



Cylinder Model	L	L1	L2	L3
EZC6-05	289	138	106	50
EZC6-05M	324	173		
EZC6-10	339	138	156	100
EZC6-10M	374	173		
EZC6-20	439	138	256	200
EZC6-20M	474	173		
EZC6-30	539	138	356	300
EZC6-30M	574	173		

EZHC Series

EZHC4

Specifications

Model		Incremental Type	EZHC4A-□I		EZHC4A-□MI	
		Absolute Type	EZHC4A-□A		EZHC4A-□MA	
Motor Type			Stepping Motor with Built-in Rotor-Position Sensor			
Drive Method			Ball Screw			
Electromagnetic Brake			Not equipped		Equipped	
Speed Range		mm/s	～400	～600	～400	～600
Max. Transportable Mass	kg	Horizontal Direction*	—	—	—	—
		Vertical Direction	—	—	6.5	4.5
Max. Acceleration	m/s²	Horizontal Direction	—		—	
		Vertical Direction	—		2.5	
Max. Thrust Force		N kgf	65 6.5	55 5.5	65 6.5	55 5.5
Push Force		N kgf	65 6.5 (Speed: 6 mm/s or less)			
Max. Holding Brake Force	N kgf	Power ON	65 6.5		65 6.5	
		Power OFF	0		0	
		Electromagnetic Brake	—		65 6.5	
Repetitive Positioning Accuracy		mm	±0.02			
Resolution		mm	0.01			
Lead		mm	12			
Stroke		mm	50、100、200、300			
Cylinder Mass	Figure in the parentheses shows the mass of the model with electromagnetic brake.	kg	**Stroke**	**50** : 1.7 (1.9)	**100** : 2.0 (2.2)	**200** : 2.5 (2.7) **300** : 3.0 (3.2)
Ambient Temperature		℃	0～+40 (Nonfreezing)			

*In a horizontal direction, the value cannot be shown because it varies by frictional resistance of the sliding surface.
●See page 54 for the specification and dimensions of the controller.

General Specifications

Item	Specification
Insulation Resistance	100 MΩ minimum when measured by a DC 500 V megger between the following places. • Windings — Case • Case — Windings of electromagnetic brake (Only for electromagnetic brake equipped model)
Dielectric Strength	Sufficient to withstand the following for one minute. • Windings — Case AC 1.0 kV 50 Hz • Case — Windings of electromagnetic brake AC 1.0 kV 50 Hz (Only for electromagnetic brake equipped model)

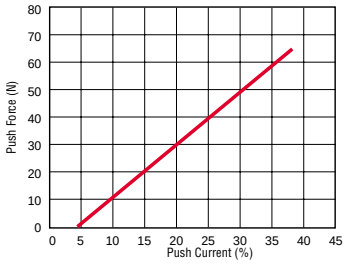
Cylinder/Controller Combinations

Type	Electromagnetic Brake	Model	Cylinder Model	Controller Model
Incremental Type	Not equipped	**EZHC4A-□I**	EZHC4A-□	EZMC13I-A
	Equipped	**EZHC4A-□MI**	EZHC4A-□M	
Absolute Type	Not equipped	**EZHC4A-□A**	EZHC4A-□	EZMC13A-A
	Equipped	**EZHC4A-□MA**	EZHC4A-□M	

*The box (□) in the model name and cylinder model name represents the code for stroke length.

Push Force

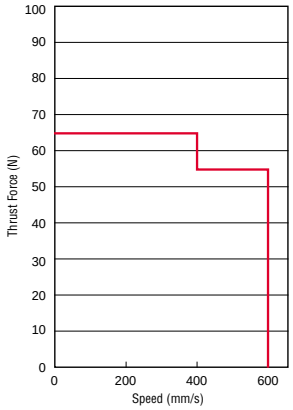
Push force can be set through "Push current setting" in the program mode.



Notes:
- The above value is a reference, not guaranteed.
- When the cylinder is used in a vertical direction, an external force calculated by multiplying the weight of the carried object by the rate of gravitational acceleration is applied. Therefore, the cylinder push force must be set so as to accommodate this external force. Measure the push force using an actual load, and set an appropriate push current.

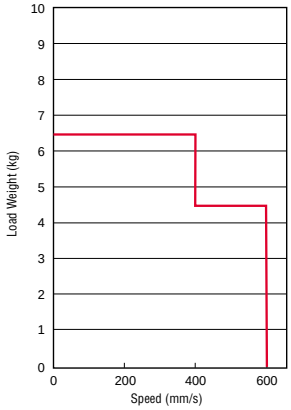
Correlation Diagram of Speed and Thrust Force

●Horizontal Direction/ Vertical Direction



Correlation Diagram of Speed and Load Weight

●Vertical Direction

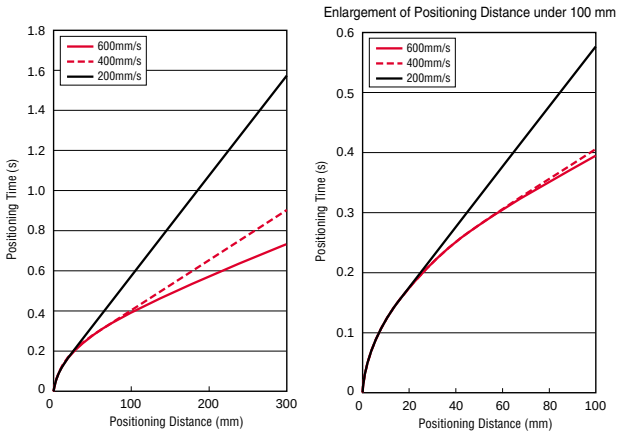


Minimum Positioning Time

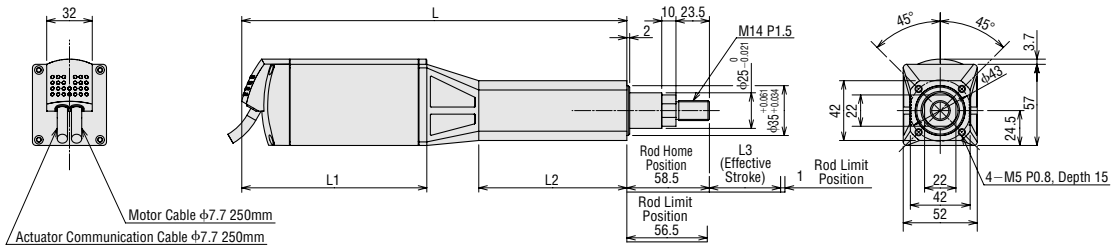
Acceleration: 2.5 m/s² Starting Speed: 6 mm/s

●Horizontal Direction/ Vertical Direction

Enlargement of Positioning Distance under 100 mm



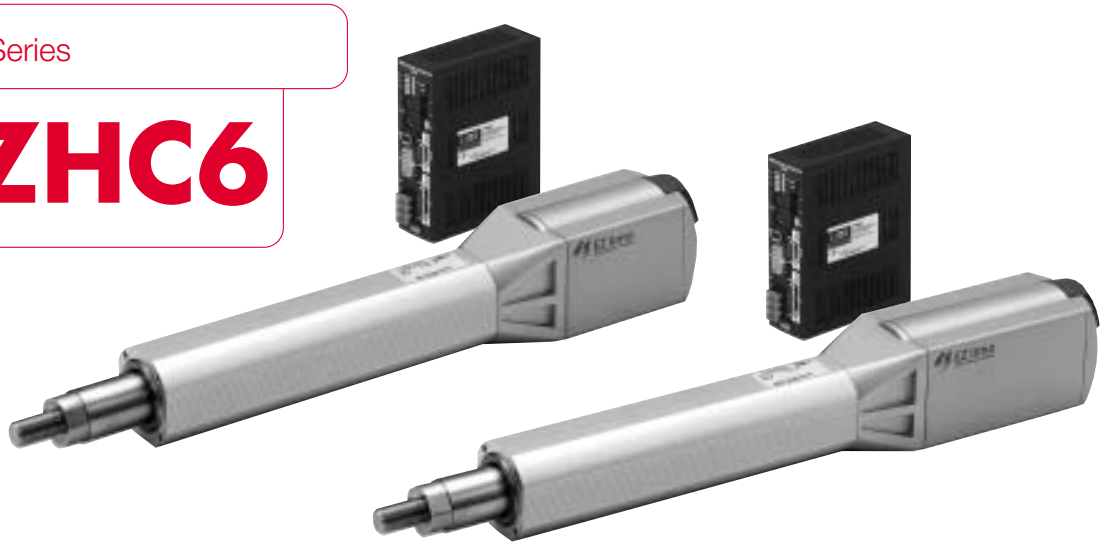
Dimensions unit: mm



Cylinder Model	L	L1	L2	L3
EZHC4A-05	270.5	130	104	50
EZHC4A-05M	300.5	160		
EZHC4A-10	320.5	130	154	100
EZHC4A-10M	350.5	160		
EZHC4A-20	420.5	130	254	200
EZHC4A-20M	450.5	160		
EZHC4A-30	520.5	130	354	300
EZHC4A-30M	550.5	160		

EZHC Series

EZHC6



Specifications

Model		Incremental Type	EZHC6A-□I、EZHC6C-□I		EZHC6A-□MI、EZHC6C-□MI	
		Absolute Type	EZHC6A-□A、EZHC6C-□A		EZHC6A-□MA、EZHC6C-□MA	
Motor Type			Stepping Motor with Built-in Rotor-Position Sensor			
Drive Method			Ball Screw			
Electromagnetic Brake			Not equipped		Equipped	
Speed Range		mm/s	～400	～600	～400	～600
Max. Transportable Mass	kg	Horizontal Direction*	—	—	—	—
		Vertical Direction	—	—	15	6
Max. Acceleration	m/s²	Horizontal Direction	—		—	
		Vertical Direction	—		2.5	
Max. Thrust Force		N kgf	200 20	73 7.3	200 20	73 7.3
Push Force		N kgf	200 20 (Speed: 6 mm/s or less)			
Max. Holding Brake Force	N kgf	Power ON	200 20		200 20	
		Power OFF	0		0	
		Electromagnetic Brake	—		200 20	
Repetitive Positioning Accuracy		mm	±0.02			
Resolution		mm	0.01			
Lead		mm	12			
Stroke		mm	50、100、200、300			
Cylinder Mass	Figure in the parentheses shows the mass of the model with electromagnetic brake.	kg	**Stroke** **50** : 3.3 (3.7)	**100** : 3.7 (4.1)	**200** : 4.6 (5.0)	**300** : 5.6 (6.0)
Ambient Temperature		℃	0～+40 (Nonfreezing)			

*In a horizontal direction, the value cannot be shown because it varies by frictional resistance of the sliding surface.
●See page 54 for the specification and dimensions of the controller.

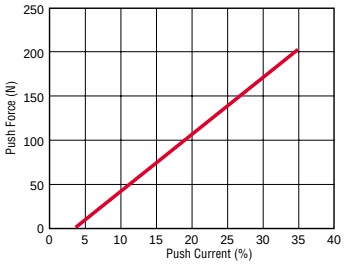
General Specifications

Item	Specification
Insulation Resistance	100 MΩ minimum when measured by a DC 500 V megger between the following places. • Windings — Case • Case — Windings of electromagnetic brake (Only for electromagnetic brake equipped model)
Dielectric Strength	Sufficient to withstand the following for one minute. • Windings — Case AC 1.5 kV 50 Hz • Case — Windings of electromagnetic brake (Only for electromagnetic brake equipped model) AC 1.0 kV 50 Hz

Push Force

Push force can be set through "Push current setting" in the program mode.

Notes:
- The above value is a reference, not guaranteed.
- When the cylinder is used in a vertical direction, an external force calculated by multiplying the weight of the carried object by the rate of gravitational acceleration is applied. Therefore, the cylinder push force must be set so as to accommodate this external force. Measure the push force using an actual load, and set an appropriate push current.



Cylinder/Controller Combinations

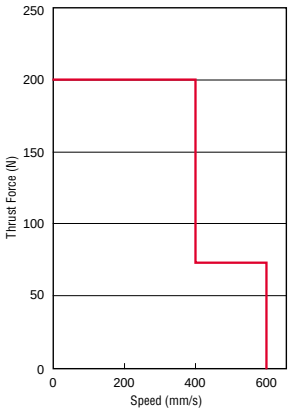
Type	Electromagnetic Brake	Model	Cylinder Model	Controller Model
Incremental Type	Not equipped	**EZHC6A-□I**	EZHC6A-□	EZMC24I-A
		EZHC6C-□I	EZHC6C-□	EZMC12I-C
	Equipped	**EZHC6A-□MI**	EZHC6A-□M	EZMC24I-A
		EZHC6C-□MI	EZHC6C-□M	EZMC12I-C

Type	Electromagnetic Brake	Model	Cylinder Model	Controller Model
Absolute Type	Not equipped	**EZHC6A-□A**	EZHC6A-□	EZMC24A-A
		EZHC6C-□A	EZHC6C-□	EZMC12A-C
	Equipped	**EZHC6A-□MA**	EZHC6A-□M	EZMC24A-A
		EZHC6C-□MA	EZHC6C-□M	EZMC12A-C

*The box (□) in the model name and cylinder model name represents the code for stroke length.

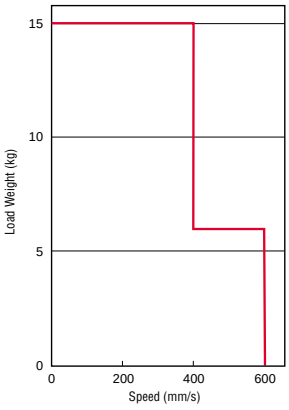
Correlation Diagram of Speed and Thrust Force

●Horizontal Direction/ Vertical Direction



Correlation Diagram of Speed and Load Weight

●Vertical Direction

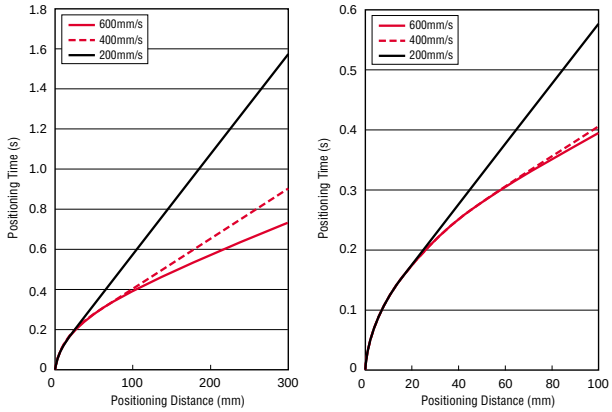


Minimum Positioning Time

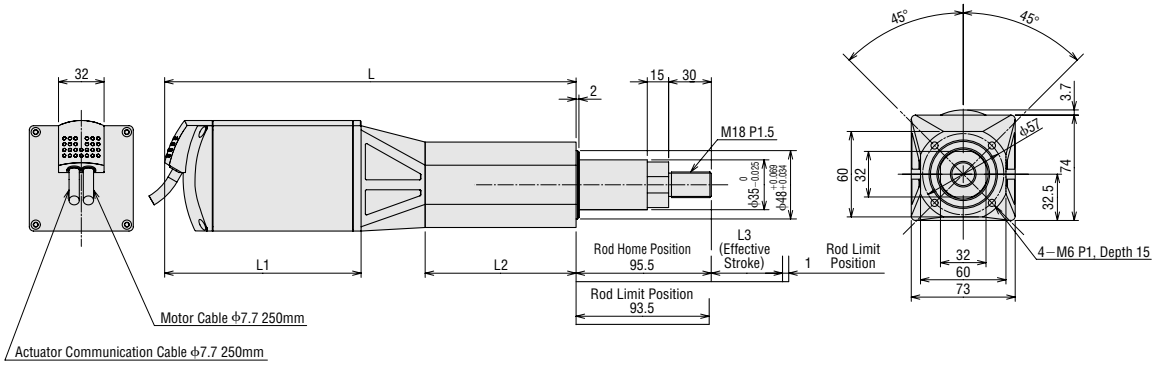
Acceleration: 2.5 m/s² Starting Speed: 6 mm/s

●Horizontal Direction/ Vertical Direction

Enlargement of Positioning Distance under 100 mm



Dimensions unit: mm



Cylinder Model	L	L1	L2	L3
EZHC6□-05	289	138	106	50
EZHC6□-05M	324	173		
EZHC6□-10	339	138	156	100
EZHC6□-10M	374	173		
EZHC6□-20	439	138	256	200
EZHC6□-20M	474	173		
EZHC6□-30	539	138	356	300
EZHC6□-30M	574	173		

* Enter the power supply voltage **A** or **C** in the box (□) within the cylinder model name.

EZHP Series

EZHP4

Specifications

Model		Incremental Type	EZHP4A-□I		EZHP4A-□MI	
		Absolute Type	EZHP4A-□A		EZHP4A-□MA	
Motor Type			Stepping Motor with Built-in Rotor-Position Sensor			
Drive Method			Ball Screw			
Electromagnetic Brake			Not equipped		Equipped	
Speed Range		mm/s	～200	～300	～200	～300
Max. Transportable Mass	kg	Horizontal Direction*	—	—	—	—
		Vertical Direction	—	—	14	9
Max. Acceleration	m/s²	Horizontal Direction	—		—	
		Vertical Direction	—		2.5	
Max. Thrust Force		N kgf	140 14	110 11	140 14	110 11
Push Force		N kgf	140 14 (Speed: 6 mm/s or less)			
Max. Holding Brake Force	N kgf	Power ON	140 14		140 14	
		Power OFF	0		0	
		Electromagnetic Brake	—		140 14	
Repetitive Positioning Accuracy		mm	±0.02			
Resolution		mm	0.01			
Lead		mm	6			
Stroke		mm	50、100、200、300			
Cylinder Mass	Figure in the parentheses shows the mass of the model with electromagnetic brake.	kg	**Stroke** **50** : 1.7 (1.9)	**100** : 2.0 (2.2)	**200** : 2.5 (2.7)	**300** : 3.0 (3.2)
Ambient Temperature		℃	0～+40 (Nonfreezing)			

*In a horizontal direction, the value cannot be shown because it varies by frictional resistance of the sliding surface.
●See page 54 for the specification and dimensions of the controller.

General Specifications

Item	Specification
Insulation Resistance	100 MΩ minimum when measured by a DC 500 V megger between the following places. • Windings — Case • Case — Windings of electromagnetic brake (Only for electromagnetic brake equipped model)
Dielectric Strength	Sufficient to withstand the following for one minute. • Windings — Case AC 1.0 kV 50 Hz • Case — Windings of electromagnetic brake AC 1.0 kV 50 Hz (Only for electromagnetic brake equipped model)

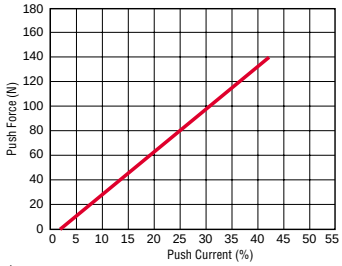
Cylinder/Controller Combinations

Type	Electromagnetic Brake	Model	Cylinder Model	Controller Model
Incremental Type	Not equipped	**EZHP4A-□I**	EZHP4A-□	EZMC13I-A
	Equipped	**EZHP4A-□MI**	EZHP4A-□M	
Absolute Type	Not equipped	**EZHP4A-□A**	EZHP4A-□	EZMC13A-A
	Equipped	**EZHP4A-□MA**	EZHP4A-□M	

*The box (□) in the model name and cylinder model name represents the code for stroke length.

Push Force

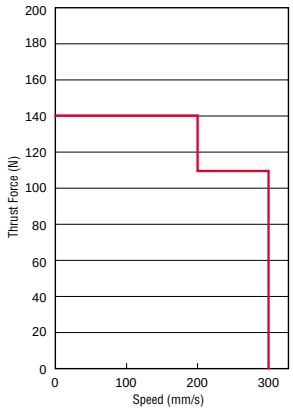
Push force can be set through "Push current setting" in the program mode.



Notes:
- The above value is a reference, not guaranteed.
- When the cylinder is used in a vertical direction, an external force calculated by multiplying the weight of the carried object by the rate of gravitational acceleration is applied. Therefore, the cylinder push force must be set so as to accommodate this external force. Measure the push force using an actual load, and set an appropriate push current.

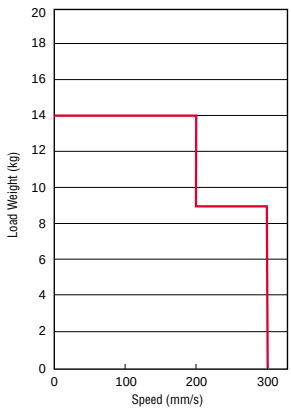
Correlation Diagram of Speed and Thrust Force

●Horizontal Direction/ Vertical Direction



Correlation Diagram of Speed and Load Weight

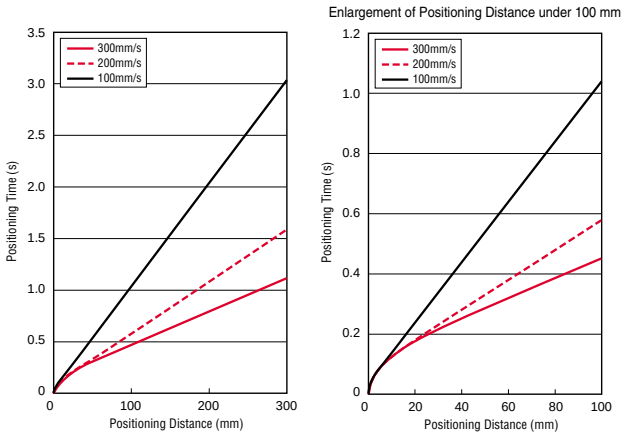
●Vertical Direction



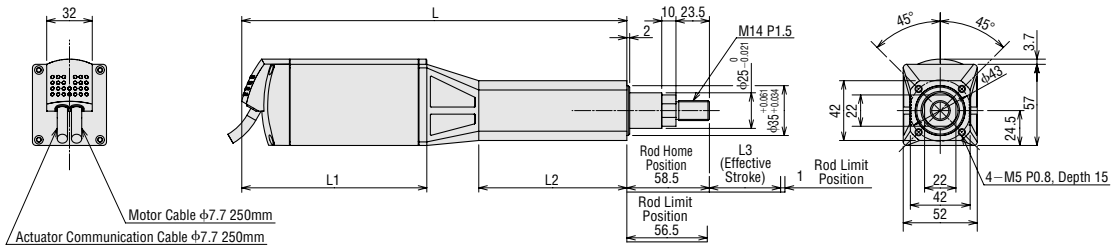
Minimum Positioning Time

Acceleration: 2.5 m/s² Starting Speed: 3 mm/s

●Horizontal Direction/ Vertical Direction



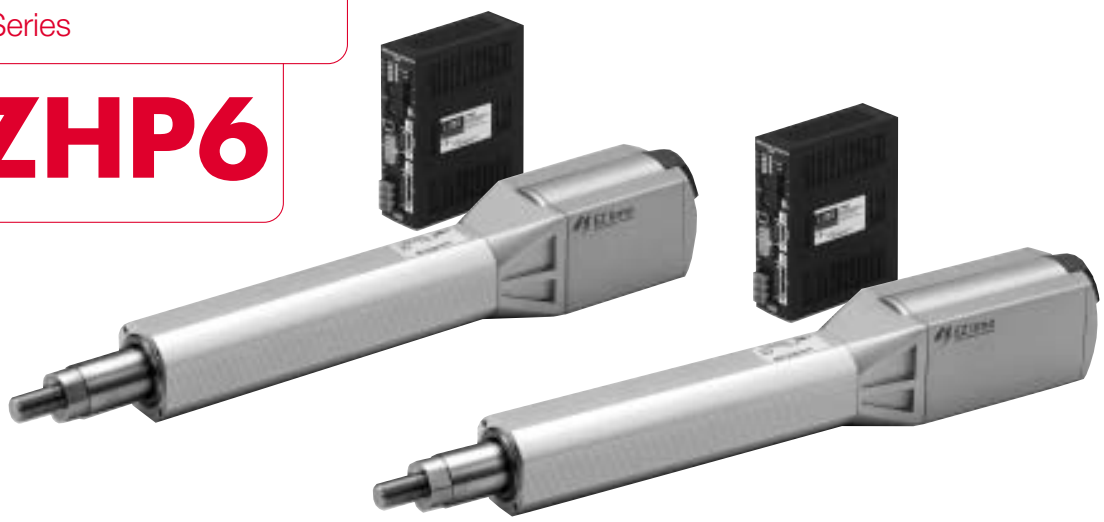
Dimensions unit: mm



Cylinder Model	L	L1	L2	L3
EZHP4A-05	270.5	130	104	50
EZHP4A-05M	300.5	160		
EZHP4A-10	320.5	130	154	100
EZHP4A-10M	350.5	160		
EZHP4A-20	420.5	130	254	200
EZHP4A-20M	450.5	160		
EZHP4A-30	520.5	130	354	300
EZHP4A-30M	550.5	160		

EZHP Series

EZHP6



Specifications

Model		Incremental Type	EZHP6A-□I、EZHP6C-□I		EZHP6A-□MI、EZHP6C-□MI	
		Absolute Type	EZHP6A-□A、EZHP6C-□A		EZHP6A-□MA、EZHP6C-□MA	
Motor Type			Stepping Motor with Built-in Rotor-Position Sensor			
Drive Method			Ball Screw			
Electromagnetic Brake			Not equipped		Equipped	
Speed Range	mm/s		～200	～300	～200	～300
Max. Transportable Mass	kg	Horizontal Direction*	—	—	—	—
		Vertical Direction	—	—	30	12
Max. Acceleration	m/s²	Horizontal Direction	—		—	
		Vertical Direction	—		2.5	
Max. Thrust Force	N kgf		400 40	147 14.7	400 40	147 14.7
Push Force	N kgf		400 40 (Speed: 6 mm/s or less)			
Max. Holding Brake Force	N kgf	Power ON	400 40		400 40	
		Power OFF	0		0	
		Electromagnetic Brake	—		400 40	
Repetitive Positioning Accuracy	mm		±0.02			
Resolution	mm		0.01			
Lead	mm		6			
Stroke	mm		50、100、200、300			
Cylinder Mass (Figure in the parentheses shows the mass of the model with electromagnetic brake.)	kg		**Stroke** **50** : 3.3 (3.7) **100** : 3.7 (4.1) **200** : 4.6 (5.0) **300** : 5.6 (6.0)			
Ambient Temperature	℃		0～+40 (Nonfreezing)			

*In a horizontal direction, the value cannot be shown because it varies by frictional resistance of the sliding surface.
●See page 54 for the specification and dimensions of the controller.

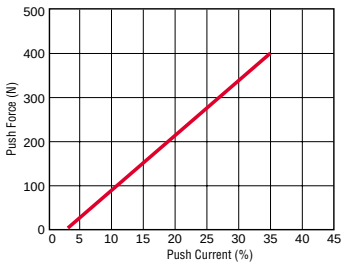
General Specifications

Item	Specification
Insulation Resistance	100 MΩ minimum when measured by a DC 500 V megger between the following places. • Windings — Case • Case — Windings of electromagnetic brake (Only for electromagnetic brake equipped model)
Dielectric Strength	Sufficient to withstand the following for one minute. • Windings — Case AC 1.5 kV 50 Hz • Case — Windings of electromagnetic brake (Only for electromagnetic brake equipped model) AC 1.0 kV 50 Hz

Push Force

Push force can be set through "Push current setting" in the program mode.

Notes:
- The above value is a reference, not guaranteed.
- When the cylinder is used in a vertical direction, an external force calculated by multiplying the weight of the carried object by the rate of gravitational acceleration is applied. Therefore, the cylinder push force must be set so as to accommodate this external force. Measure the push force using an actual load, and set an appropriate push current.



Cylinder/Controller Combinations

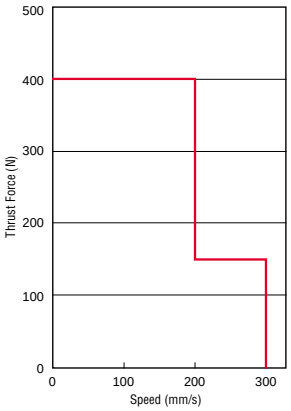
Type	Electromagnetic Brake	Model	Cylinder Model	Controller Model
Incremental Type	Not equipped	**EZHP6A-□I**	EZHP6A-□	EZMC24I-A
		EZHP6C-□I	EZHP6C-□	EZMC12I-C
	Equipped	**EZHP6A-□MI**	EZHP6A-□M	EZMC24I-A
		EZHP6C-□MI	EZHP6C-□M	EZMC12I-C

Type	Electromagnetic Brake	Model	Cylinder Model	Controller Model
Absolute Type	Not equipped	**EZHP6A-□A**	EZHP6A-□	EZMC24A-A
		EZHP6C-□A	EZHP6C-□	EZMC12A-C
	Equipped	**EZHP6A-□MA**	EZHP6A-□M	EZMC24A-A
		EZHP6C-□MA	EZHP6C-□M	EZMC12A-C

*The box (□) in the model name and cylinder model name represents the code for stroke length.

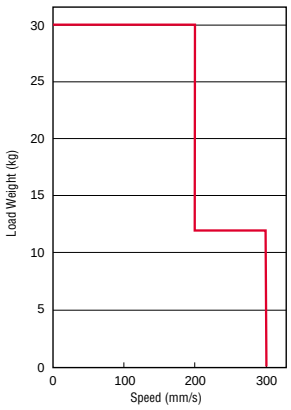
Correlation Diagram of Speed and Thrust Force

●Horizontal Direction/ Vertical Direction



Correlation Diagram of Speed and Load Weight

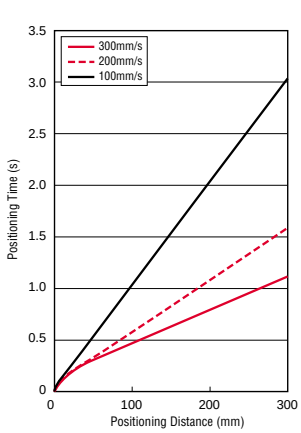
●Vertical Direction



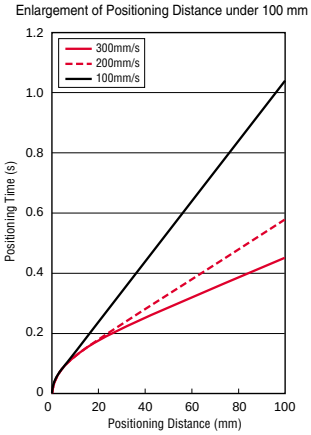
Minimum Positioning Time

Acceleration: 2.5 m/s² Starting Speed: 3 mm/s

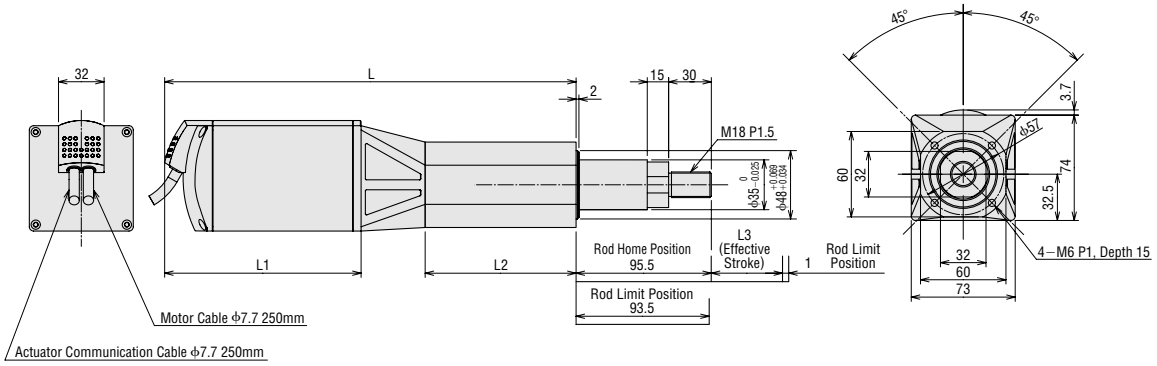
●Horizontal Direction/ Vertical Direction



Enlargement of Positioning Distance under 100 mm



Dimensions unit: mm



Cylinder Model	L	L1	L2	L3
EZHP6□-05	289	138	106	50
EZHP6□-05M	324	173		
EZHP6□-10	339	138	156	100
EZHP6□-10M	374	173		
EZHP6□-20	439	138	256	200
EZHP6□-20M	474	173		
EZHP6□-30	539	138	356	300
EZHP6□-30M	574	173		

* Enter the power supply voltage **A** or **C** in the box (□) within the cylinder model name.

EZS and EZC Series

■ Specifications

●Controller Mode

Item	Specification
Type	Stored-data type
Number of Control Axes	1 axis
Maximum Speed	300.000 mm/s
Number of Motion Profiles	63
Motion Profile Setting Mode	Absolute mode (absolute-position specification) Incremental mode (relative-position specification)
Motion Profile Setting Method	Data is set using the teaching pendant (EZT1) or data editing software (EZED1).
Data Execution Mode	Selective positioning Sequential positioning
Travel Amount Setting Range	Absolute mode: -9999.990 to +9999.990 mm Incremental mode: -9999.990 to +9999.990 mm (value set in units of 0.015 mm)
Starting Speed	0.015 to 250.000 mm/s (value set in units of 0.015 mm/s) *Data can be set using the teaching pendant or data editing software.
Operating Speed	0.015 to 300.000 mm/s (value set in units of 0.015 mm/s) *Data can be set using the teaching pendant or data editing software.
Acceleration/Deceleration	0.015 to 150.000 m/s² (value set in units of 0.015 m/s²) *Data can be set using the teaching pendant or data editing software.
Control Mode	External input mode (EXT) Program mode (PRG) Parameter mode (PAR) Test mode (TST)
Operation Mode	Positioning operation Return-to-home operation Linked operation (a max of 63 profiles) Push-motion operation
Input Signal	24 VDC photocoupler isolated input Input resistance 4.7 Ω
Output Signal	Photocoupler-connected transistor output 24 VDC, 25 mA or less
Power Supply Input	24 VDC ±10% 4.0 A (Controller only: 3.5 A) *Take into account safety margin of +0.2 A for the teaching pendant, and/or +0.3 A for the electromagnetic brake type.
Program Backup	EEPROM

●Driver Mode

Item	Specification
Maximum Response Frequency	20 kHz
Pulse-Input Mode mode	Switchable between 1-pulse input mode and 2-pulse input mode (switching via DIP switches on front panel)
Input Signal	5 VDC photocoupler isolated input, input resistance 220 Ω negative logic pulse input (CW Pulse, CCW Pulse) 24 VDC photocoupler isolated input, input resistance 4.7 k Ω (ACL, RUN0～RUN2, STOP0～STOP2, C.OFF)
●CW Pulse Signal	Pulse width 2 μs or more, rise/fall time 2 μs or less (The operation command pulse is input in the 1-pulse input mode.)
●CCW Pulse Signal	Pulse width 2 μs or more, rise/fall time 2 μs or less (The direction of movement is input in the 1-pulse input mode.)
Output Signal	Photocoupler-connected transistor output (The TIM signal uses a photocoupler output.) 24 VDC, 25 mA or less
Power Supply Input	24 VDC ±10% 4.0 A (Controller only: 3.5 A) *Take into account safety margin of +0.2 A for the teaching pendant, and/or +0.3 A for the electromagnetic brake type.

●General Specifications

Item	Specification
Insulation Resistance	100 M minimum when measured by a 500 V DC megger between the following places; ●Protective earth terminal – Power input terminal ●Protective earth terminal – Signal input terminal
Dielectric Strength	Sufficient to withstand the following for one minute; ●Protective earth terminal – Power input terminal AC 0.5 kV 50Hz ●Protective earth terminal – Signal input terminal AC 0.5 kV 50Hz
Ambient Temperature	0 °C to +40 °C (nonfreezing)
Ambient Humidity	85% or below (noncondensing)

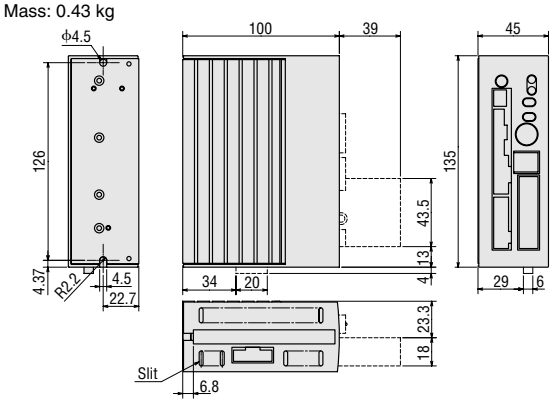
■ Battery Specifications (for the absolute type only)

Item	Specification
Battery Type	Cylindrical sealed nickel-cadmium storage cell
Nominal Voltage	1.2 V
Rated Capacity	10000 mAh
Mass	430 g
Life	Approx. 4 years *1
Charge Time	48 hours *1
Data Retention Period *1 *2	Standard backup: Approx. 96 hours Optional backup: Approx. 70 hours
Ambient Temperature	0 °C to +40 °C (nonfreezing)
Ambient Humidity	20 to 85% (noncondensing)

*1 At an ambient temperature of 20℃
*2 After the power is cut off with the battery fully charged

■ Dimensions unit: mm

Mass: 0.43 kg



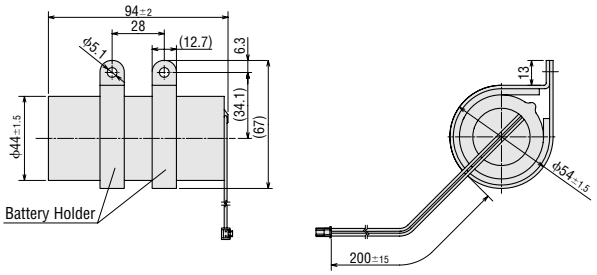
●Accessories (common to incremental and absolute type)

I/O Connector Case 54331-1361 (MOLEX)
I/O Connector 54306-3611 (MOLEX)

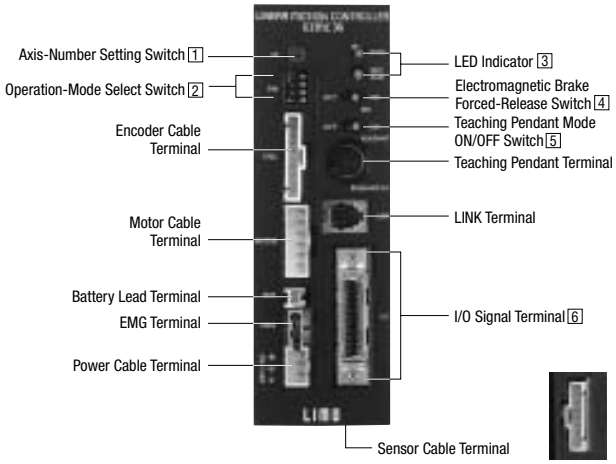
Power Supply Cable 600 mm

Name	Conductor
+24V	AWG20
GND	AWG20
FG	AWG18

Battery (Supplied with absolute type models. Battery holder provided.)



■ Names and Functions of Parts

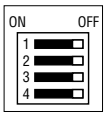


1 Axis-Number Setting Switch

Display	Function
ID	Set controller axis number

2 Operation-Mode Select Switch

Display	Function
1	Invalid (not used)
2	
3	Set Pulse Input Mode (in driver mode) ON: 1-Pulse Input Mode OFF: 2-Pulse Input Mode
4	Operation Modes ON: Driver Mode OFF: Controller Mode



* The area in white indicates the switch position.

* All switches are factory-set to "OFF".

3 LED Indicator

Display	Color	Name
PWR	Green	Power ON Indicator
RDY/ALM	Green/Red	Status Indicator

4 Electromagnetic Brake Forced-Release Switch

Display	Function
MB	Switch electromagnetic brake operation modes ON : Actuation OFF: Release

Note: This switch becomes effective only when a protective function is actuated.

5 Teaching Pendant Mode ON/OFF Switch

Display	Function
PENDANT	Set whether or not the teaching pendant is used ON: Teaching pendant used OFF: Teaching pendant not used

6 I/O Signals

●Controller Mode

Display	I/O	Terminal Number	Terminal Name	Function
I/O	Input Signal	23	+COM	Output signal power +24 V
		25		
		27	COM	Input signal power +24 V
		28		
		24	-COM	Output signal power GND
		26		
	Output Signal	1	READY	Turns ON when the START input can be received.
		2	ALM	Turns ON when the EMG input is OFF or upon the occurrence of a controller alarm.
		4	END	Turns ON when the operation has ended.
		5	MOVE	Turns ON during operation
		9	AREA	Turns ON when positioning is performed inside the set area or while the set area is being passed.
		10	T-UP	Turns ON during push-motion operation (cylinder only).
		31	ALM0	Alarm information is output in a five-bit code.
		32	ALM1	
		33	ALM2	
		34	ALM3	
		35	ALM4	
	Input Signal	36	ACL	Clear an alarm.
		11	M0	M0 through M5 input signals are combined to select a positioning point. (If all signals are OFF, the sequential positioning mode will be selected.)
		12	M1	
		13	M2	
		14	M3	
		15	M4	
		16	M5	
		3	STOP	Stop the operation.
		6	START	Start the positioning operation.
		7	PAUSE	Stop the operation temporarily.
		8	HOME	Perform return-to-home operation.

●Driver Mode

Display	I/O	Terminal Number	Terminal Name	Function
I/O	Input Signal	23	+COM	Output signal power +24 V
		25		
		27	COM	Input signal power +24 V
		28		
		24	-COM	Output signal power GND
		26		
	Output Signal	2	ALM	Turns ON when the EMG input is OFF or upon the occurrence of a controller alarm.
		4	END	Turns ON when the operation has ended.
		31	ALM0	Alarm information is output in a five-bit code.
		32	ALM1	
		33	ALM2	
		34	ALM3	
		35	ALM4	
		21	TIM+	Indicate that the motor is at the initial point of excitation (step [0]). This signal is output once each time the excitation sequence returns to step [0], in synchronism the input pulse. (The circuit is configured so that the excitation sequence completes one cycle when the slider, table or cylinder rod has moved by 0.24 mm.)
		22	TIM-	
	Input Signal	36	ACL	Clear an alarm.
		11	RUN0	RUN0 through RUN2 input signals are combined to set the motor operating current.
		12	RUN1	
		13	RUN2	
		14	STOP0	STOP0 through STOP2 input signals are combined to set the motor standstill current.
		15	STOP1	
		16	STOP2	
		17	CW+	Move the slider table or cylinder rod away from the motor.
		18	CW-	
		19	CCW+	Move the slider table or cylinder rod toward the motor.
		20	CCW-	
		7	C.OFF	When this signal is ON, the current flow to the motor or is cut off and the holding-brake force generated through motor torque is lost. Switching this signal from ON to OFF does not change the motor's excitation sequence.

EZHS, EZHC and EZHP Series

■ Specifications

●Controller Mode

Item		Specification
Type		Stored-data type
Number of Control Axes		1 axis
Maximum Speed		**EZHS** Series : 800.00mm/s **EZHC** Series : 600.00mm/s **EZHP** Series : 300.00mm/s
Number of Motion Profiles		63
Motion Profile Setting Mode		Absolute mode (absolute-position specification) Incremental mode (Relative-position specification)
Motion Profile Setting Method		Data is set using the teaching pendant (EZT1).
Data Execution Modes		Selective positioning / Sequential positioning
Travel Amount Setting Range		Absolute mode: -83886.08 to +83886.07 mm Incremental mode: -83886.08 to +83886.07 mm (value set in units of 0.01 mm)
Starting Speed		0.01 to 250.00 mm/s (value set in units of 0.01 mm/s) *Data can be set using the teaching pendant.
Operating Speed		0.01 to 800.00 mm/s (value set in units of 0.01 mm/s) *Data can be set using the teaching pendant.
Acceleration/Deceleration		0.01 to 100.00 m/s² (value set in units of 0.01 m/s²) *Data can be set using the teaching pendant.
Control Mode		External input mode (EXT) Program mode (PRG) Parameter mode (PAR) Test mode (TST)
Operation Mode		Positioning operation Return-to-home operation Linked operation (a maximum of 4 data) Push-motion operation Continuous operation
Input Signal		24 VDC photocoupler isolated input, input resistance 4.7 kΩ (START, STOP, HOME/PRESET, FREE, M0～M5, REQ, ACL/CK) 5 VDC photocoupler isolated input, input resistance 180 Ω or 24 VDC photocoupler isolated input, input resistance 2.7 kΩ (FWD,RVS)
Output Signal		Photocoupler-connected transistor output 24 VDC, 15 mA or less Line driver output
Power Supply Input	Control Power	24 VDC ±10%, 1.0 A (Controller only: 0.5 A) *Take into account safty margin of +0.2 A for the teaching pendant, and/or +0.3 A for the electromagnetic brake type.
	Main Power	EZMC13I(A)-A : AC100 -115V -15%, +10% 50/60Hz 3.3A EZMC24I(A)-A : AC100 -115V -15%, +10% 50/60Hz 5.0A EZMC12I(A)-C : AC200 -230V -15%, +10% 50/60Hz 3.0A
Program Backup		EEPROM

●Driver Mode

Item		Specification
Maximum Response Frequency		80 kHz
Pulse-Input Mode		Switchable between 1-pulse input mode and 2-pulse input mode (switching via DIP switches on front panel) Deviation pulse input (Switching from the teaching pendant)
Input Signal		5 VDC photocoupler isolated input, input resistance 180 Ω or 24 VDC photocoupler isolated input, input resistance 2.7 kΩ, negative logic pulse input(FP, RP) 24 VDC photocoupler isolated input, input resistance 4.7 kΩ (ACL/CK, FREE, C.OFF, PRESET, REQ)
●FP Pulse Signal		Pulse width 2 μs or more, rise/fall time 2 μs or less (The operation command pulse is input in the 1-pulse input mode.)
●RP Pulse Signal		Pulse width 2 μs or more, rise/fall time 2 μs or less (The direction of movement is input in the 1-pulse input mode.)
Output Signal		Photocoupler-connected transistor output 24 VDC, 15 mA or less Line driver output
Power Supply Input	Control Power	24 VDC ±10%, 1.0 A (Controller only: 0.5 A) *Take into account safty margin of +0.2 A for the teaching pendant, and/or +0.3 A for the electromagnetic brake type.
	Main Power	EZMC13I(A)-A : AC100 -115V -15%, +10% 50/60Hz 3.3A EZMC24I(A)-A : AC100 -115V -15%, +10% 50/60Hz 5.0A EZMC12I(A)-C : AC200 -230V -15%, +10% 50/60Hz 3.0A

●General Specifications

Item	Specification
Insulation Resistance	100 MΩ minimum when measured by a 500 V DC megger between the following terminals; ●Signal I/O, Control Power supply, PE - Main Power Supply ●Signal I/O, Control Power supply, PE - Motor output ●Signal I/O, Control Power supply, PE - Battery input
Dielectric Strength	Sufficient to withstand the following terminals for one minute; ●Signal I/O, Control Power supply - Main Power Supply 1.8kV ●Signal I/O, Control Power supply - Motor output 1.8kV ●Signal I/O, Control Power supply - Battery input 1.8kV ●PE - Main Power Supply 1.5kV ●PE - Motor output 1.5kV ●PE - Battery input 1.5kV
Ambient Temperature	0 °C to +40 °C (nonfreezing)
Ambient Humidity	85% or below (noncondensing)

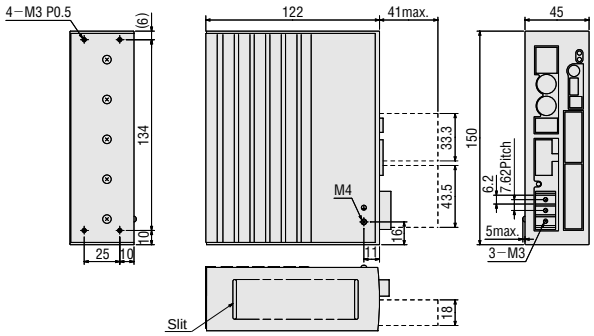
■ Battery Specifications (for the absolute type only)

Item	Specification
Battery Type	Cylindrical sealed nickel-cadmium storage cell
Nominal Voltage	2.4 V
Rated Capacity	2000 mAh
Mass	180 g
Life	Approx. 4 years *1
Charge Time	48 hours *1
Data Retention Period	Approx. 360 hours (15days) *1 *2
Ambient Temperature	0 °C to +40 °C (nonfreezing)
Ambient Humidity	20 to 85% (noncondensing)

*1 At an ambient temperature of 20℃
*2 After the power is cut off with the battery fully charged.

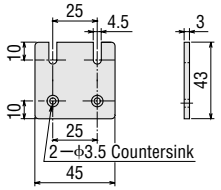
■ Dimensions unit: mm

Mass: 0.8kg



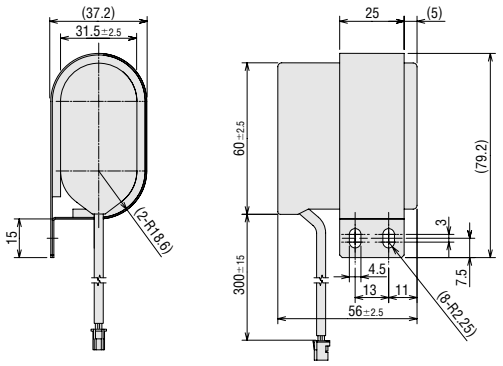
●Accessories (common to incremental and absolute type)

Mounting Bracket (2 pieces)

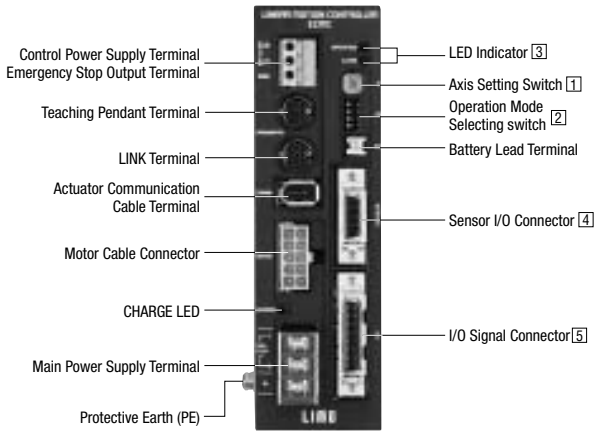


I/O Connector case (1 piece)	54331-1361 (MOLEX)
I/O Connector (1 piece)	54306-3611 (MOLEX)
I/O Connector case for Sensor (1 piece)	54331-1201 (MOLEX)
I/O Connector for Sensor (1 piece)	54306-2011 (MOLEX)

Battery (Supplied with absolute type models. Battery holder provided.)



■ Names and Functions of Parts

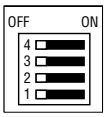


1 Axis-Number Setting Switch

Display	Function
ID	Set controller axis number

2 Operation-Mode Select Switch

Display	Function
4	Invalid (not used)
3	
2	Set Pulse Input Mode (in driver mode) ON: 1-Pulse Input Mode OFF: 2-Pulse Input Mode
1	Operation Modes ON: Driver Mode OFF: Controller Mode



* The area in white indicates the switch position.

* All switches are factory-set to "OFF".

3 LED Indicator

Display	Color	Name
OPERATION	Green	Control power supply indicator
ALARM	Red	Alarm indicator

4 Sensor I/O Connector

Display	I/O	Terminal Number	Terminal Name	Function
SENSOR	Output	1	P24	Power supply for sensor +24V
		11		
		19		
		2	N24	Power supply for sensor GND
		12		
		20		
	Input	13	+LS	+LS (counter-motor side) limit sensor
		14	-LS	-LS (Motor side) limit sensor
		15	HOMELS	Home position sensor

5 I/O Connector

●Controller Mode

Display	I/O	Terminal Number	Terminal Name	Function
I/O	Input Signal	18	P24	Power supply for I/O signal +24 V
		1	N24	Power supply for I/O signal GND
		19		
	Output Signal	2	ALM	Turns ON when the controller has generated an alarm.
		3	MOVE	Turns ON during operation.
		4	END/OUTR	END: Turns ON when the operation has ended. OUTR: Turns ON when current position output is ready.
		5	AREA/OUT0	AREA: Turns ON when the work has moved to a position inside the specified range or while passing the specified range. OUT0: Outputs the current position.
		6	T-UP/OUT1	T-UP: Turns ON during push-motion operation. (cylinder only) OUT1: Outputs the current position.
		20	ASG1(oc)	Outputs the position of the slider table or cylinder rod via pulse signal.(Open-collector output)
		21	BSG1(oc)	
		22	ASG2(dif)	Outputs the position of the slider table or cylinder rod via pulse signal.(Line-driver output)
		23	$\overline{\text{ASG2(dif)}}$	
		24	BSG2(dif)	
		25	$\overline{\text{BSG2(dif)}}$	
	Input Signal	7	START	Start positioning operation.
		8	ACL/CK	ACL: Clear the alarm currently present. CK: Used when the current position is output.
		9	FREE	Stop motor excitation and release the electromagnetic brake.
		10	STOP	Stop the operation.
		11	M0	Positioning point is selected via combination of M0 to M5 input signals. (When all signals are OFF, sequential positioning is performed.)
		12	M1	
		13	M2	
		14	M3	
		15	M4	
		16	M5	
		17	HOME/ PRESET	HOME: Perform return-to-home operation. PRESET: Preset the current position.
		30	REQ	Request current position output.
		31	FWD+	Move the slider table or cylinder rod to the away from the motor. (Continuous operation input)
		32	FWD-	
		33	P24-FWD	
		34	RVS+	Move the slider table or cylinder rod toward the motor. (Continuous operation input)
		35	RVS-	
		36	P24-RVS	

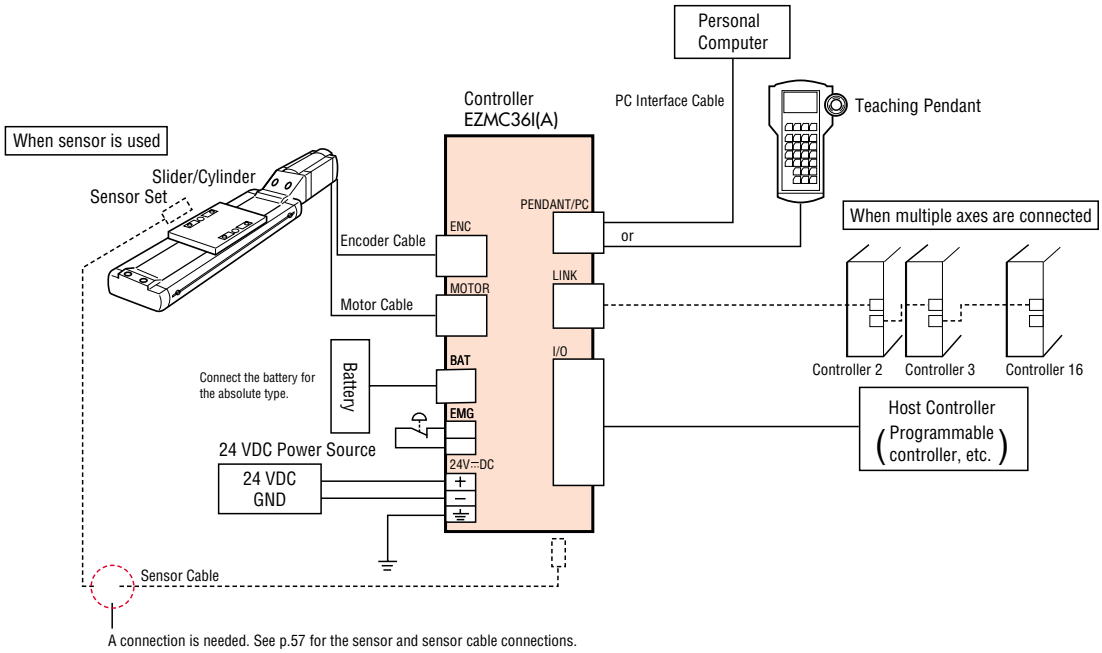
●Driver Mode

Display	I/O	Terminal Number	Terminal Name	Function
I/O	Input Signal	18	P24	Power supply for I/O signal +24 V
		1	N24	Power supply for I/O signal GND
		19		
	Output Signal	2	ALM	Turns ON when the controller has generated an alarm.
		4	END/OUTR	END: Turns ON when the operation has ended. OUTR: Turns ON when current position output is ready.
		5	TIM/OUT0	TIM: Indicates that the motor is at the beginning of its excitation sequence (step 0). This signal is output in sync with the input pulse: the signal is output once whenever the excitation sequence returns to step 0. (The excitation sequence completes when the slider table or cylinder rod has moved by 0.24 mm*.) * **EZHP4**/**EZHP6**: 0.12 mm OUT0: Outputs the current position.
		6	OUT1	Outputs the current position
		20	ASG1(oc)	Outputs the position of the slider table or cylinder rod via pulse signal.(Open-collector output)
		21	BSG1(oc)	
		22	ASG2(dif)	Outputs the position of the slider table or cylinder rod via pulse signal.(Line-driver output)
		23	$\overline{\text{ASG2(dif)}}$	
		24	BSG2(dif)	
		25	$\overline{\text{BSG2(dif)}}$	
	Input Signal	8	ACL/CK	ACL: Clear the alarm currently present. CK: Used when the current position is output.
		9	FREE	Stop motor excitation and release the electromagnetic brake.
		10	C.OFF	When this signal turns ON, the current flow to the motor is cut off and the holding-brake force, which is generated by motor torque, will be lost. Turning this signal from ON to OFF does not change the motor's excitation sequence.
		17	PRESET	Preset the current position.
		30	REQ	Request current position output.
		31	FP+	Move the slider table or cylinder rod away from the motor. (Pulse input)
		32	FP-	
		33	P24-FP	
		34	RP+	Move the slider table or cylinder rod toward the motor.(Pulse input)
		35	RP-	
		36	P24-RP	

Connection Diagrams

EZS Series • EZC Series

■ Connection Diagram



A connection is needed. See p.57 for the sensor and sensor cable connections.

●Power Source

Use a 24 VDC power source with a capacity of 4.0 A or more.
If the power capacity is insufficient, motor output may drop, which may cause the slider/cylinder to malfunction (due to lack of thrust force).

●Power Supply to +COM

Use a power source with a capacity of 24 VDC, 100 mA or more.

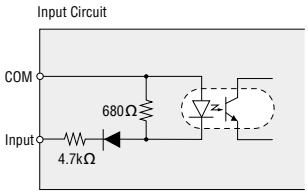
●Connection of Output Signal

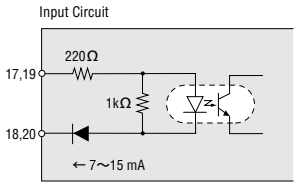
V_0 must be between 5 and 24 VDC.
The current must be 25 mA or less. If the current exceeds 25 mA, connect an external resistance R_0.

●Notes on Wiring

- Wire the control I/O signal lines over as short a distance as possible, using a multiple-core, twisted-pair blanket shield cable (0.08 mm² [AWG 28] or more).
- Be sure to use an optional motor cable and encoder cable to wire the slider/cylinder and controller.
- Wire the control I/O signal lines by providing a minimum distance of 30 cm from the power lines (large-current circuits such as the power supply line and motor line). Do not wire the control I/O signal lines with the power lines in the same duct or bundle them together.

Input Circuit



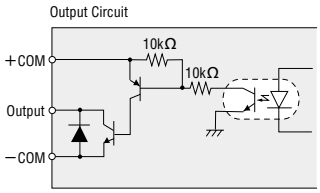


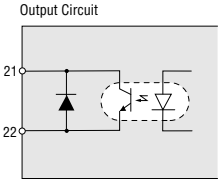
●Controller Mode
Pin No.
36 ACL
11~16 M0~M5
3 STOP
6 START
7 PAUSE
8 HOME

●Driver Mode
Pin No.
36 ACL
11~13 RUN0~RUN2
14~16 STOP0~STOP2
7 C.OFF

●Driver Mode
Pin No.
17 CW+
18 CW-
19 CCW+
20 CCW-

Output Circuit





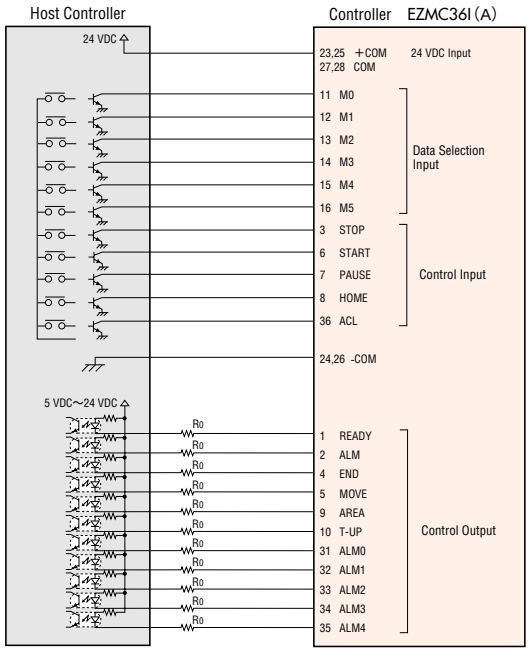
●Controller Mode
Pin No.
1 READY
2 ALM
4 END
5 MOVE
9 AREA
10 T-UP
31~35 ALM0~ALM4

●Driver Mode
Pin No.
2 ALM
4 END
31~35 ALM0~ALM4

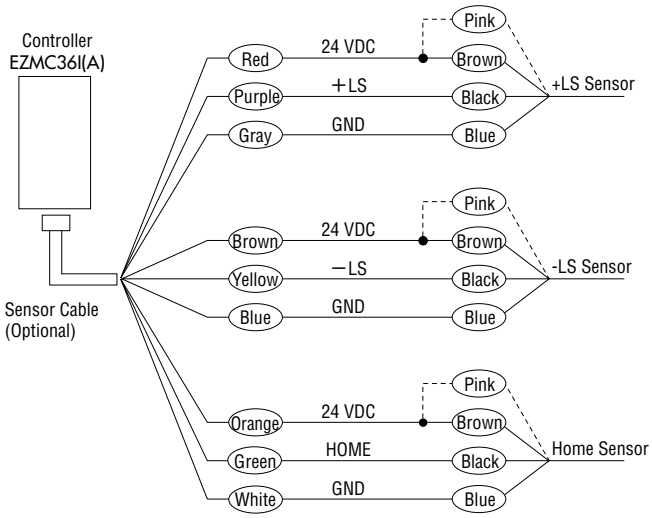
●Driver Mode
Pin No.
21 TIM+
22 TIM-

■ Connection to Host Computer

●Controller Mode

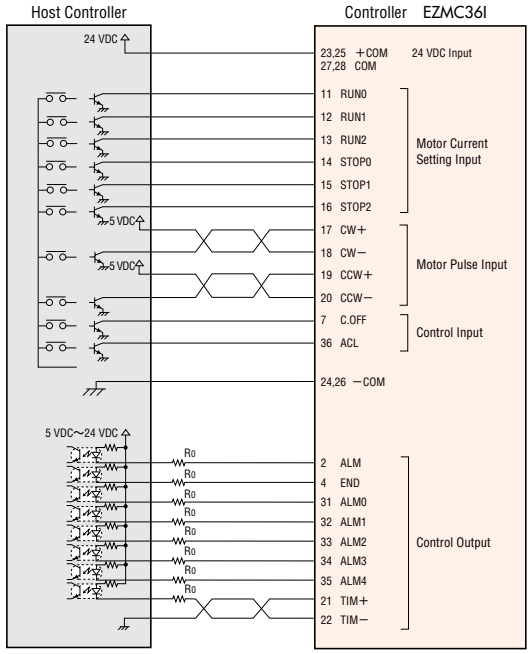


Wiring the Sensors

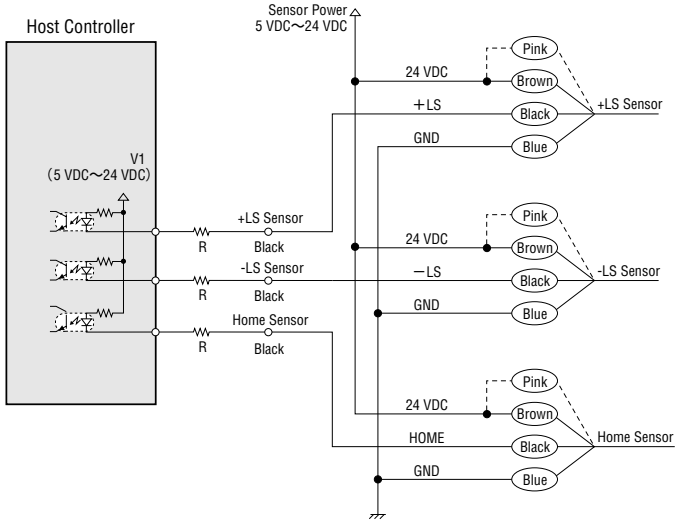


●The 24 VDC output from the controller is used to drive the sensors.
Do not use it as a power supply for any item other than the sensors.
●Connect the pink lead to the brown lead when the sensor logic is N.C. (normally closed).
The pink lead is not connected when the sensor logic is N.O. (normally open).

●Driver Mode



Wiring the Sensors

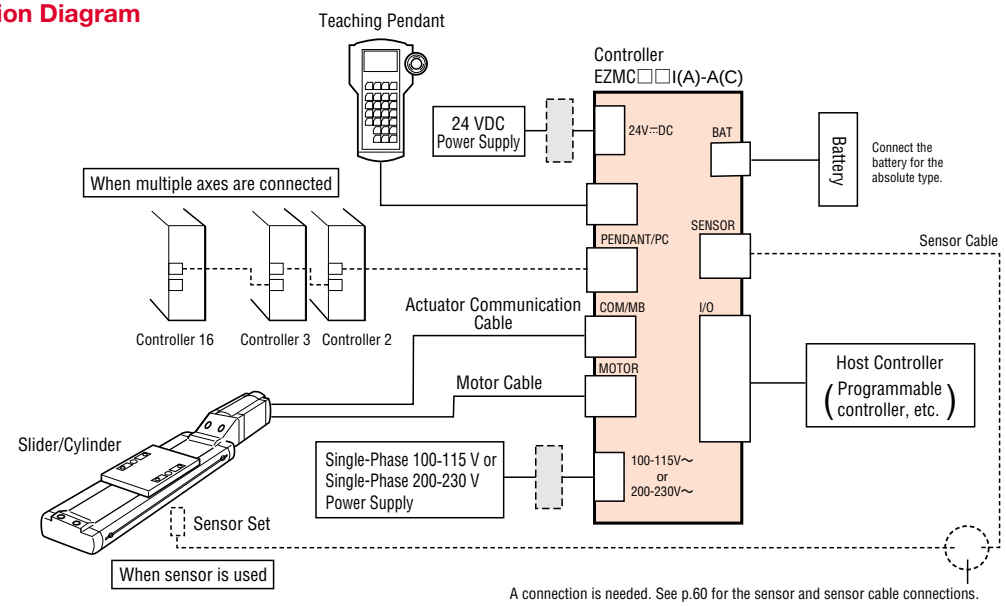


●V1 must be between 5 VDC and 24 VDC. The current must be 100 mA or less. If the current exceeds 100 mA, connect an external resistance R.
●Connect the pink lead to the brown lead when the sensor logic is N.C.(normally closed).
The pink lead is not connected when the sensor logic is N.O. (normally open).

Connection Diagrams

EZHS Series • EZHC Series • EZHP Series

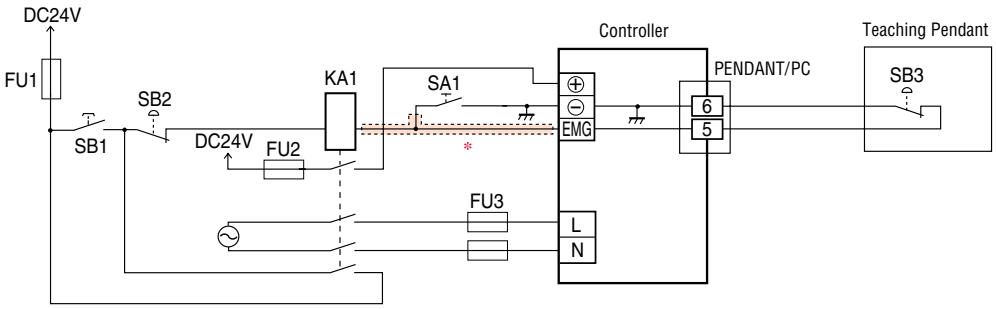
■ Connection Diagram



For the section indicated by broken line, see following "Connection Example of Power System and Emergency Stop System".

Connection Example of Power System and Emergency Stop System

A connection example of controller power system and emergency stop system is given below, which conforms to Stop Category 0 under the EN60204-1 safety standard. See page 15 for details on the applicable standard.



- FU1: Ground-fault protection fuse (500 mA)
- FU2: Ground-fault protection fuse (1 A)
- FU1, FU2, KA1 and SB2 should use EN-certified products.
- Relay (KA1) ratings: 24 VDC/30 mA

- See "**EZHS/EZHC/EZHP** Series Controller User Manual" for examples of connecting multiple controllers using controller link cables.

✻ Provide ground-fault protection in the section indicated by broken line, such as wiring the cables in duct.

●Power Source

Two types of power source, main power and control power, are required. Both power sources must at least have the specified capacity. (See the controller specifications listed on page 54.)

If the power capacity is insufficient, the slider / cylinder may not operate normally (due to lack of thrust force) as a result of a drop in motor output.

●Notes on Wiring

- Wire the control I/O signal lines over as short a distance as possible, using a multiple-core, twisted-pair blanket shield cable (0.08 mm^2 [AWG 28] or more).
- Be sure to use an optional motor cable and actuator communication cable to wire the slider/cylinder and controller.
- Wire the control I/O signal lines by providing a minimum distance of 30 cm from the power lines (large-current circuits such as the power supply line and motor line). Do not wire the control I/O signal lines with the power lines in the same duct or bundle them together.

●Input Circuit 1 Connection

The power source for P24 must have a capacity of 24 VDC/200 mA or more.

When connecting each sensor to a sensor connector and supplying sensor power from the P24 terminal of the sensor connector, use a DC power source capable of supplying 200 mA as specified above plus the current consumed by each sensor. (When the optional sensor set **PAEZ-S** is used, the current capacity must be increased by 35 mA per sensor.)

The 24 VDC supplied to the P24 terminal of the I/O connector is output to the P24 terminal of the sensor connector as pass-through output.

●Input Circuit 2 Connection

The photocoupler diode in the input circuit can receive 7 to 20 mA of current.

- When a 24 VDC power source is used, connect 24 VDC to ㉝ and ㊱ and then connect to ㉜ and ㉟, respectively.
- When a 5 VDC power source is used, connect 5 VDC to ㉛ and ㉞ and then connect to ㉜ and ㉟, respectively.
  If the power source exceeds 5 VDC, connect an external resistor R_2 to keep the input current between 7 to 20 mA.
- If a pulse oscillator of line-driver output is used, connect the + side of line-driver output to ㉛ and ㉞, and the − side of line-driver output to ㉜ and ㉟, respectively. (See the connection diagram on page 61.)

●Output Circuit 1 Connection

The load connected to the open-collector output terminal of output circuit 1 should be 30VDC, 10 mA or less. If the current capacity of the load exceeds 10 mA, connect an external resistor R_0*.

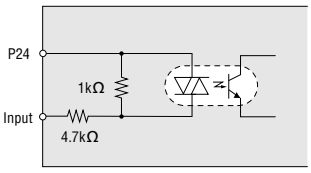
●Output Circuit 2 Connection

The load connected to the open-collector output terminal of output circuit 2 should be 30VDC/15 mA or less. If the current capacity of the load exceeds 15 mA, connect an external resistor R_1*.

* See page 60 and page 61 for the connection positions of external resistors.

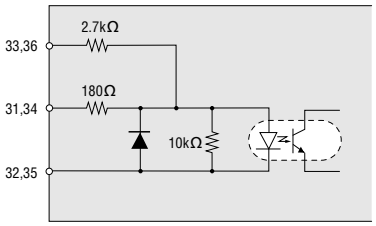
Input Circuit

Input Circuit 1



● Controller Mode Pin No.		● Driver Mode Pin No.	
❼	START	❽	ACL/CK
❽	ACL/CK	❾	FREE
❾	FREE	❿	C.OFF
❿	STOP	⓱	PRESET
⓫～⓰	M0～M5	㉚	REQ
⓱	HOME/PRESET		
㉚	REQ		

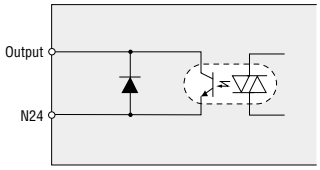
Input Circuit 2



● Controller Mode Pin No.		● Driver Mode Pin No.	
㉛	FWD+	㉛	FP+
㉜	FWD−	㉜	FP−
㉝	P24-FWD	㉝	P24-FP
㉞	RVS+	㉞	RP+
㉟	RVS−	㉟	RP−
㊱	P24-RVS	㊱	P24-RP

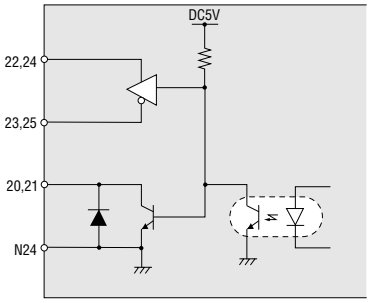
Output Circuit

Output Circuit 1



● Controller Mode Pin No.		● Driver Mode Pin No.	
❷	ALARM	❷	ALARM
❸	MOVE	❹	END/OUTR
❹	END/OUTR	❺	TIM/OUT0
❺	AREA/OUT0	❻	OUT1
❻	T-UP/OUT1		

Output Circuit 2



● Common to Controller Model and Driver Mode

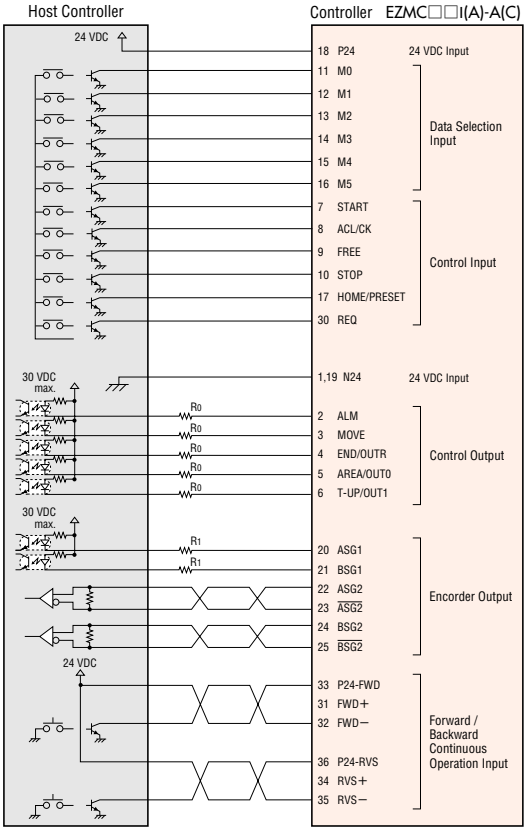
Pin No.		
⓴	ASG1	A-Phase Pulse Output (Open-Collector Output)
㉑	BSG1	B-Phase Pulse Output (Open-Collector Output)
㉒	ASG2+	A-Phase Pulse Output (Line Driver Output +)
㉓	ASG2–	A-Phase Pulse Output (Line Driver Output –)
㉔	BSG2+	B-Phase Pulse Output (Line Driver Output +)
㉕	BSG2–	B-Phase Pulse Output (Line Driver Output –)

Connection Diagrams

EZHS Series • EZHC Series • EZHP Series

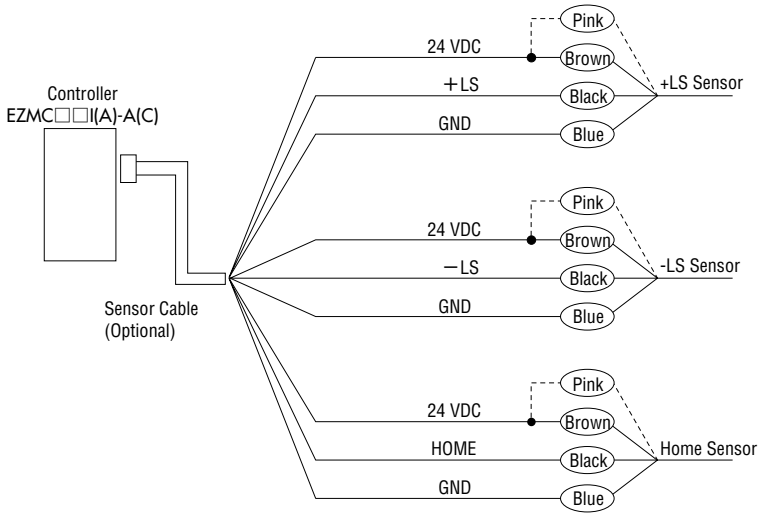
■ Connection to Host Computer

●Controller Mode



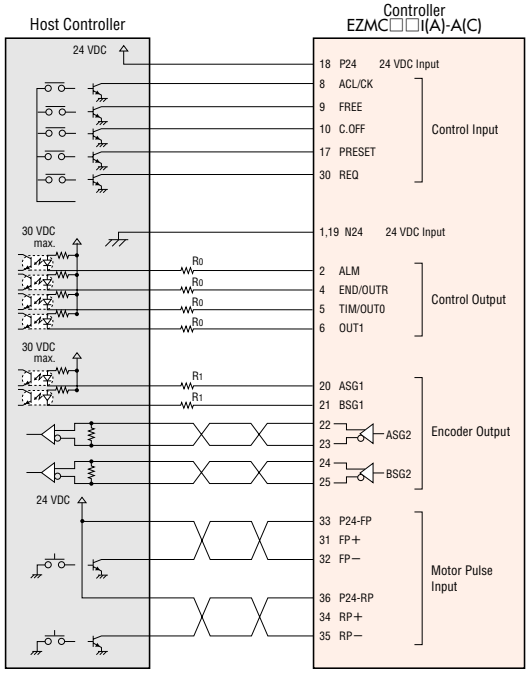
∗See page 59 for the conditions of external resistors R_0 and R_1.

Wiring the Sensors



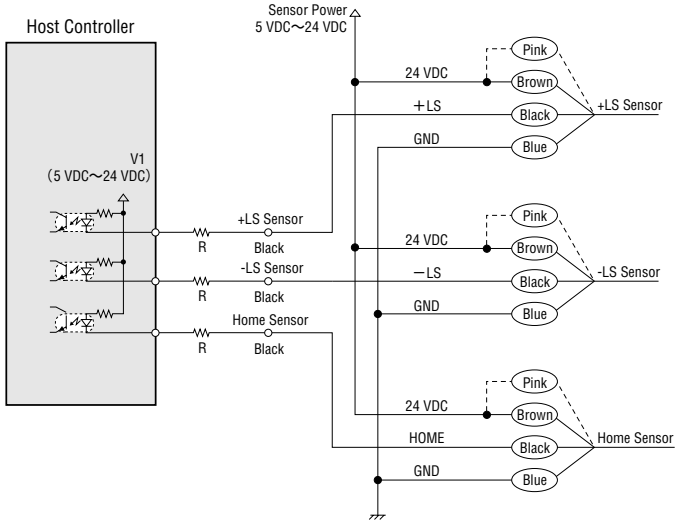
●The 24 VDC output from the controller is used to drive the sensors.
Do not use it as a power supply for any item other than the sensors.
●Connect the pink lead to the brown lead when the sensor logic is N.C. (normally closed).
The pink lead is not connected when the sensor logic is N.O. (normally open).

●Driver Mode



＊See page 59 for the conditions of external resistors R_0 and R_1.

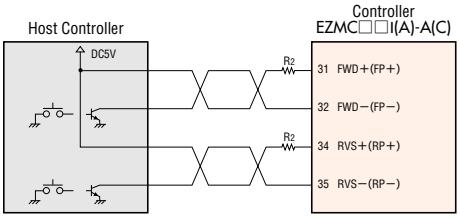
Wiring the Sensors



●V1 must be between 5 VDC and 24 VDC. The current must be 100 mA or less. If the current exceeds 100 mA, connect an external resistance R.
●Connect the pink lead to the brown lead when the sensor logic is N.C.(normally closed). The pink lead is not connected when the sensor logic is N.O. (normally open).

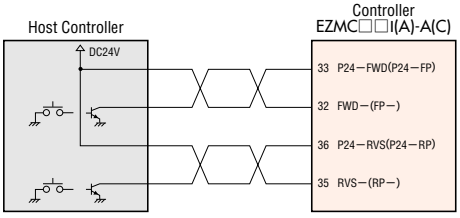
■ FWD (FP), RVS (RP) Signals

When connected to a 5 VDC open-collector output signal

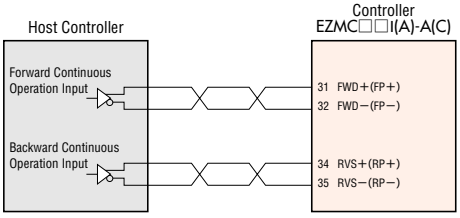


●When the output signal is 5 VDC, the external resistor R_2 is not required. If the output signal exceed 5 VDC, see page 59.

When connected to a 24 VDC open-collector output signal



When connected to a line-driver output



■ Installation of Slider/Cylinder

●Installation Conditions of Slider/Cylinder

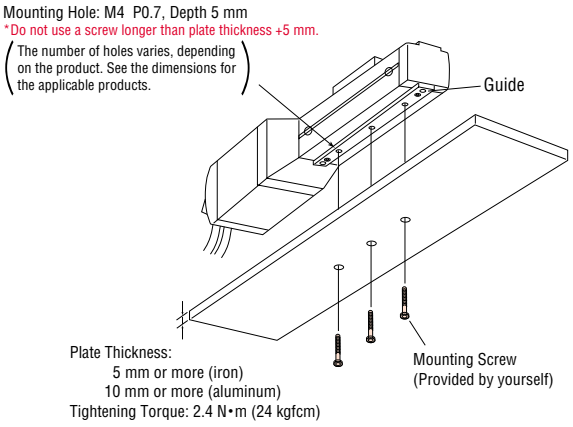
Install the slider/cylinder in a place satisfying the following conditions. Using the slider/cylinder in locations not satisfying these conditions may damage the product.

- Indoor (This product is designed and manufactured for use in equipment as an internal component.)
- An ambient temperature of 0°C to +40°C (nonfreezing)
- A relative humidity of 85% or below (noncondensing)
- A place not exposed to explosive, flammable or corrosive gases
- A well-ventilated place
- A place away from direct sunlight
- A place not subject to dust
- A place not subject to water, oil or other liquids
- A place where the slider/cylinder can easily discharge heat
- A place not subject to continuous vibration or excessive shock

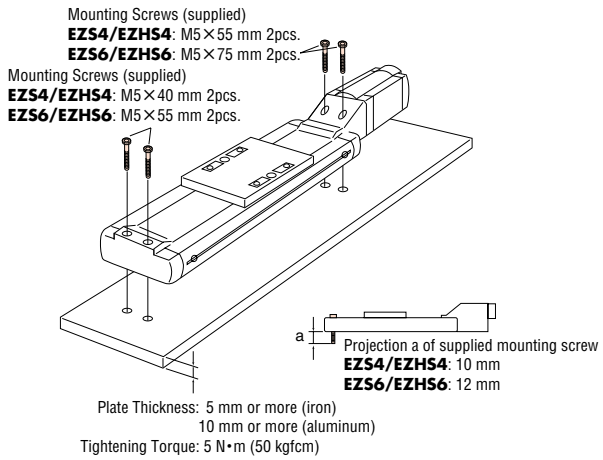
●Installation of Slider

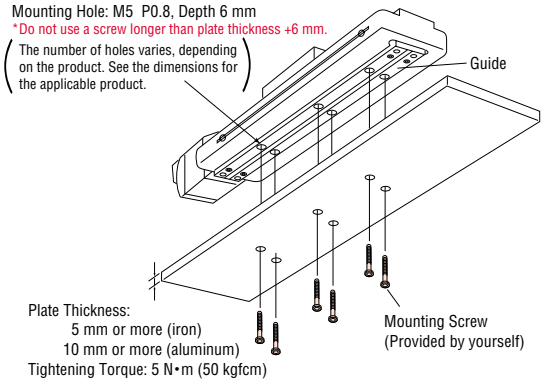
◇Installing the Slider Body

EZS3 and **EZHS3**


Mounting Hole: M4 P0.7, Depth 5 mm
*Do not use a screw longer than plate thickness +5 mm.
The number of holes varies, depending on the product. See the dimensions for the applicable products.
Guide
Plate Thickness:
5 mm or more (iron)
10 mm or more (aluminum)
Tightening Torque: 2.4 N•m (24 kgfcm)
Mounting Screw
(Provided by yourself)

EZS4·EZHS4·EZS6 and **EZHS6**


Mounting Screws (supplied)
EZS4/EZHS4: M5×55 mm 2pcs.
EZS6/EZHS6: M5×75 mm 2pcs.
Mounting Screws (supplied)
EZS4/EZHS4: M5×40 mm 2pcs.
EZS6/EZHS6: M5×55 mm 2pcs.
a
Projection a of supplied mounting screw
EZS4/EZHS4: 10 mm
EZS6/EZHS6: 12 mm
Plate Thickness: 5 mm or more (iron)
10 mm or more (aluminum)
Tightening Torque: 5 N•m (50 kgfcm)

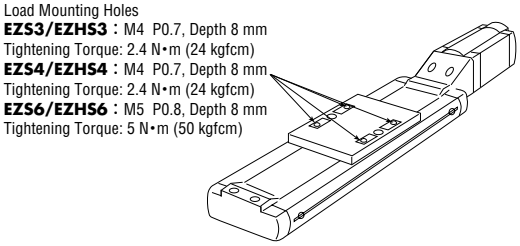

Mounting Hole: M5 P0.8, Depth 6 mm
*Do not use a screw longer than plate thickness +6 mm.
The number of holes varies, depending on the product. See the dimensions for the applicable product.
Guide
Plate Thickness:
5 mm or more (iron)
10 mm or more (aluminum)
Tightening Torque: 5 N•m (50 kgfcm)
Mounting Screw
(Provided by yourself)

Notes:

- Ensure a parallelism of approx. 0.06 mm (**EZS3**, **EZHS3**: 0.035 mm) between the mounting surface and mounting plate, and provide a guide of approx. 200 mm long.
- Unless the slider is installed horizontally so that load moment is not applied, affix the slider using all holes provided in its bottom face.

◇Installing the Load to the Slider

Four mounting holes are provided in the slider table for installation of the work. Use these holes to affix the work.

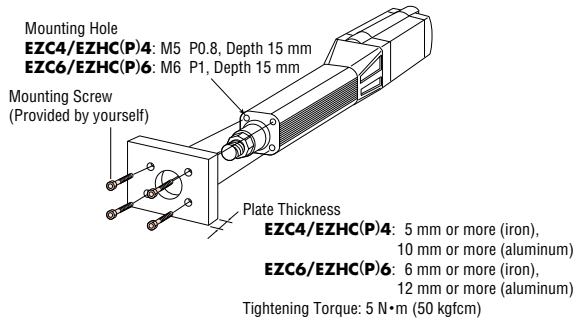

Load Mounting Holes
EZS3/EZHS3 : M4 P0.7, Depth 8 mm
Tightening Torque: 2.4 N•m (24 kgfcm)
EZS4/EZHS4 : M4 P0.7, Depth 8 mm
Tightening Torque: 2.4 N•m (24 kgfcm)
EZS6/EZHS6 : M5 P0.8, Depth 8 mm
Tightening Torque: 5 N•m (50 kgfcm)

Note: The screws used to affix the load to the table shall not be longer than the thickness of the load by more than 8 mm. If the screw is more than 8 mm longer than the thickness of the load, the screw will contact the side cover of the slider.

●Installation of Cylinder

◇Installing the Cylinder Body

Installation using the mounting holes in the cylinder


Mounting Hole
EZC4/EZHC(P)4: M5 P0.8, Depth 15 mm
EZC6/EZHC(P)6: M6 P1, Depth 15 mm
Mounting Screw
(Provided by yourself)
Plate Thickness
EZC4/EZHC(P)4: 5 mm or more (iron),
10 mm or more (aluminum)
EZC6/EZHC(P)6: 6 mm or more (iron),
12 mm or more (aluminum)
Tightening Torque: 5 N•m (50 kgfcm)

Installation using a cylinder flange **PAEZ□-F** (optional)

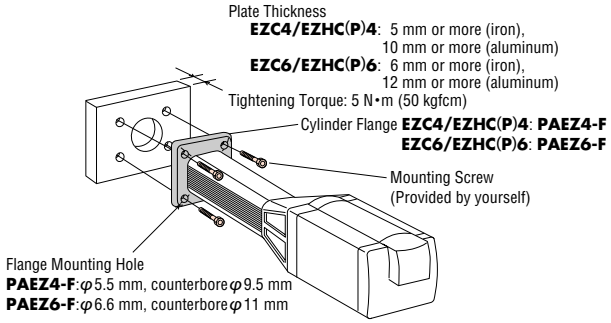
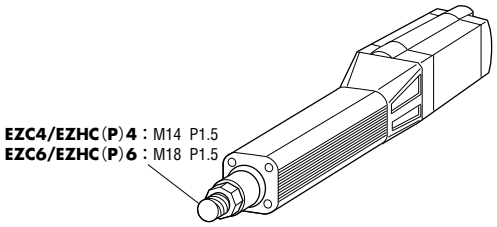


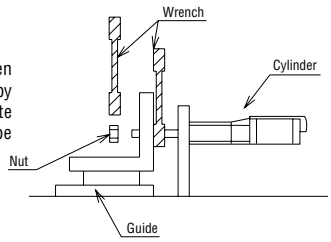
Plate Thickness
EZC4/EZHC(P)4: 5 mm or more (iron),
10 mm or more (aluminum)
EZC6/EZHC(P)6: 6 mm or more (iron),
12 mm or more (aluminum)
Tightening Torque: 5 N•m (50 kgfcm)
Cylinder Flange **EZC4/EZHC(P)4**: **PAEZ4-F**
EZC6/EZHC(P)6: **PAEZ6-F**
Mounting Screw
(Provided by yourself)
Flange Mounting Hole
PAEZ4-F:φ5.5 mm, counterboreφ9.5 mm
PAEZ6-F:φ6.6 mm, counterboreφ11 mm

The flange comes with the screws
for installing the flange to the cylinder.
EZC4/EZHC(P)4: M5×20 mm 4 pcs.
EZC6/EZHC(P)6: M5×25 mm 4 pcs.

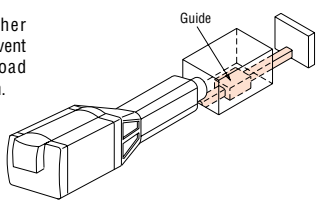
◇Installing the Load to the Cylinder



Notes:
- When affixing the load, tighten the screws with the rod locked by a wrench or other appropriate tool so that the rod will not be subjected to angular moment.



- Provide a guide or other appropriate mechanism to prevent the rod from receiving a load other than in the axial direction.



■ Installation of Controller/Battery

●Installation Conditions

Install the controller/battery in a place satisfying the following conditions. Using the controller/battery in locations not satisfying these conditions may damage the product.

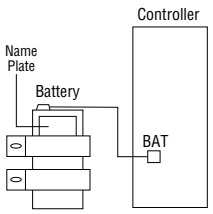
- Indoor (This product is designed and manufactured for use in equipment as an internal component.)
- An ambient temperature of 0°C to +40°C (nonfreezing)
- An ambient humidity
  Controller: 85% or below (noncondensing)
  Battery: 20 to 85% or below (noncondensing)
- A place not exposed to explosive, flammable or corrosive gases
- A place not subject to dust
- A place not subject to water, oil or other liquids
- A place where the controller/battery can easily discharge heat
- A place not subject to continuous vibration or excessive shock

Notes:
- When the controller is installed in an enclosed space such as the interior of a control panel, or near a heat source, always provide ventilation holes to prevent the controller temperature from rising.
- If the installation location is near a vibration source and the controller is subject to vibration, install a shock absorber.
- If a source of significant noise (e.g., a high-frequency welder or large-capacity electromagnetic switch) is located near the controller, provide appropriate measures such as inserting a noise filter, changing the wiring layout and suppressing noise generation.
- Make sure conductive particles (chips, pins, wire offcuts, etc.) will not enter the controller.

●Installation of Battery

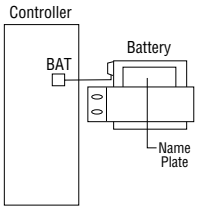
EZS and **EZC** Series

Install the battery using the supplied battery holder in such a way that the recycling mark on the battery nameplate remains visible and by avoiding the protective circuit (see the external view of battery on p.52). The battery may be installed in any orientation, as long as a minimum clearance of 25 mm is provided between the controller and the battery and the battery lead wires can reach the controller.



EZHS·**EZHC** and **EZHP** Series

Install the battery using the supplied battery holder in such a way that the recycling mark on the battery nameplate remains visible. The battery may be installed in any orientation, as long as a minimum clearance of 25 mm is provided between the controller and the battery and the battery leads can reach the controller.



●Installation of Controller

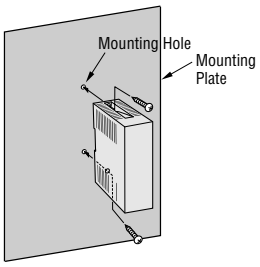
EZS and **EZC** Series

◇Installing with Screws

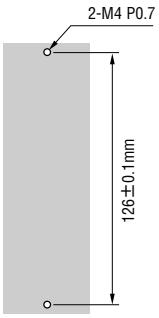
When installing the controller with screws, use the two mounting holes provide on the top and bottom, as shown below.

Use M4 screws and tighten them via a flat washer, etc.

Note: The mounting screws and flat washers are not supplied with the controller. Those items must be provided by the customer.



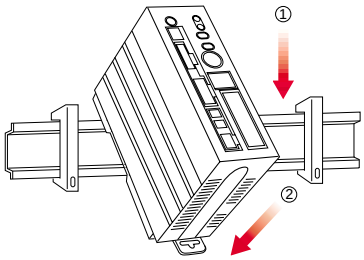
Drilling Dimensions of Mounting Holes



Mounting Screw :
M4 x 10 mm or more, 2 pcs.
Flat Washer : Small, round type
Tightening Torque : 0.5 to 0.6 N·m (5 to 6 kgfcm)

◇Installing to a DIN Rail

The controller may be installed to a DIN rail using a DIN rail mounting plate **PADP01** (optional).

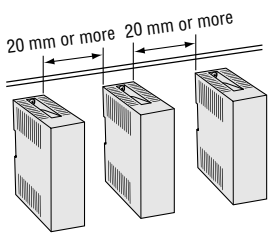


Notes:
- Use a DIN rail with a rail width of 35 mm. Also, use an end plate for affixing the controller.
- The DIN rail and end plate are not supplied with the controller. Those items must be provided by the customer.

◇Installation Clearances

When two or more controllers are connected, the ambient temperature will increase due to rise in the temperature of each controller. Provide a minimum clearance of 20 mm between the two adjacent controllers and a minimum clearance of 25 mm between each controller and other equipment or structure in all directions.

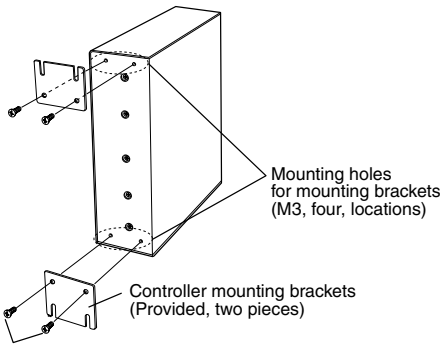
If the ambient temperature is expected to exceed 40°C, provide forced cooling via a fan.



EZHS·EZHC and **EZHP** Series

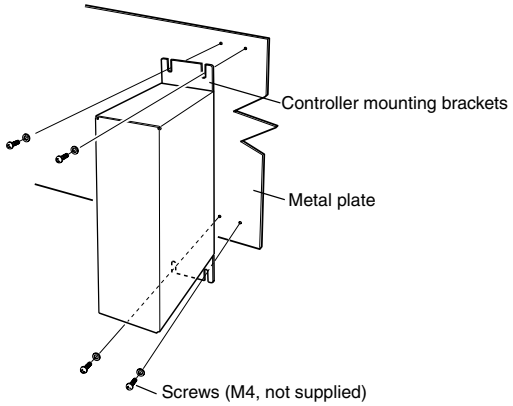
◇Installing using Controller Mounting Brackets

Install the controller mounting brackets over the mounting holes (4 locations) at the back of the controller, using the supplied screws (M3: 4 pieces.)



Screws for controller mounting brackets
(Provided, M3, four pieces)
Tightening Torque: 0.5 to 0.6 N·m(5 to 6 kgfcm)

Using the mounting holes in the controller mounting brackets and four screws (M4: not supplied; to be provided by user;), install the controller by making sure no gaps remain along the metal plate.

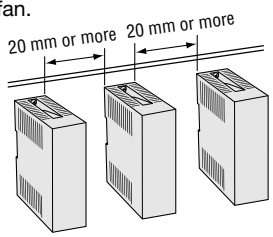


Screws (M4, not supplied)
Tightening Torque: 0.5 to 0.6 N·m(5 to 6 kgfcm)

◇Installation Clearances

When two or more controllers are connected, the ambient temperature will increase due to rise in the temperature of each controller. Provide a minimum clearance of 20 mm between the two adjacent controllers and a minimum clearance of 25 mm between each controller and other equipment or structure in all directions.

If the ambient temperature is expected to exceed 40°C, provide forced cooling via a fan.



■ Teaching Pendant EZT1

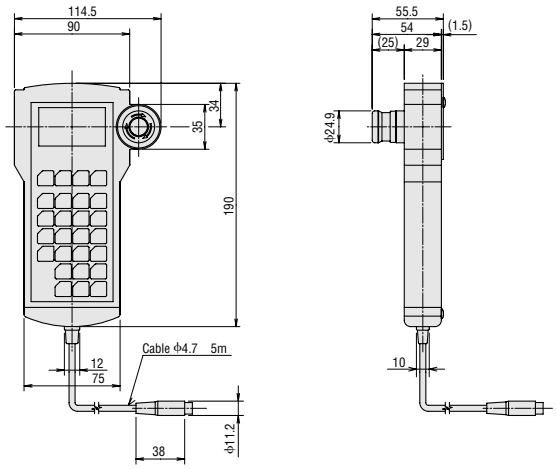
Common

The teaching pendant allows you to set and execute motion profiles, as well as to monitor the set data, current position and I/O status in real time.

●Specifications

Display	LCD with 2-colored back light
Cable Length	5 m
Mass	0.37 kg
Ambient Temperature	0°C to +40°C (nonfreezing)

●Dimensions unit: mm



■ Data Editing Software EZED1 (with PC Interface Cable)

EZS EZC

With this software you can set and edit the operation data on a PC. It comes with a PC interface cable for connecting the controller to the PC's RS-232C port. The software also provides various monitoring functions.

* The data editing software can be used with either the **EZMC36I** or **EZMC36A** controller.

●Specifications

Operating Environment

Model	**EZED1**
Operating Systems	Microsoft® Windows® 95 Service Pack1 or later *1 Microsoft® Windows® 98 Microsoft® Windows® 98SE Microsoft® Windows® Me Microsoft® Windows NT® 4.0 Service Pack6 or later Microsoft® Windows® 2000 Microsoft® Windows® XP
Computer	A personal computer that can install any of the above Windows® operating systems
Display Resolution	SVGA (800 x 600) or more [XGA (1024 x 768) or more is recommended.]
Hard Disk Capacity	Available disk space of 1.5 MB or more
Disk Drive	CD-ROM drive

*1 Internet Explorer 4.01 Service Pack 1 or later is also required.
- Service Pack signifies a service pack provided by Microsoft Corporation.
- Microsoft, Windows and Windows NT are registered trademarks of Microsoft Corporation in the United States and other countries.

PC Interface Cable

Cable Length	5 m
PC Connector Type	D-sub 9-pin
Communication Port	One RS-232C communication port

●Teaching Pendant (**EZT1**)/Data Editing Software (**EZED1**) Function Comparison Table

Item	Teaching pendant	Data editing software
Model	**EZT1**	**EZED1**
Cable length	5 m	5 m*1
Display	LCD 17 charactersx4 lines	PC screen
Emergency stop switch	●	×
Motion Profile setting	●	●
Parameter setting	●	●
Teaching function (direct/remote)	●	×
Motion Profile execution	●	×
Data copy	×	●
Display function	●	●
Operation data monitoring	●	×

●=Available ×=Not available

*1 PC interface cable (supplied) is used.

Optional Parts (sold separately)

■ Cable Set

Common

A set of dedicated cables is used to connect the **EZ limo** slider/cylinder with the controller.
The cable set consists of a motor cable and an encoder cable. The cable length can be selected from 2 m, 5 m and 10 m. Each of the cables can be purchased individually.
The same cable can be used for both the electromagnetic brake type and non-electromagnetic brake type.

Model	Length (L)	Applicable Products
CC02EZ1	2m	**EZS** Series **EZC** Series
CC05EZ1	5m	
CC10EZ1	10m	
CC02EZ2	2m	**EZHS** Series
CC05EZ2	5m	**EZHC** Series
CC10EZ2	10m	**EZHP** Series

●Individual Motor Cable

Model	Length (L)	Applicable Products
CC02EZ1-M	2m	**EZS** Series **EZC** Series
CC05EZ1-M	5m	
CC10EZ1-M	10m	
CC02EZ2-M	2m	**EZHS** Series
CC05EZ2-M	5m	**EZHC** Series
CC10EZ2-M	10m	**EZHP** Series

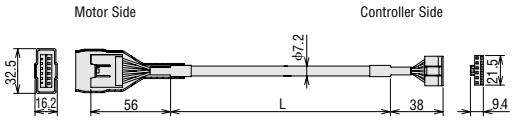
●Individual Encoder Cable, Actuator Communication Cable

Type of Cable	Model	Length (L)	Applicable Products
Encoder Cable	**CC02EZ1-E**	2m	**EZS** Series **EZC** Series
	CC05EZ1-E	5m	
	CC10EZ1-E	10m	
Actuator Communication Cable	**CC02EZ1-T**	2m	**EZHS** Series **EZHC** Series **EZHP** Series
	CC05EZ1-T	5m	
	CC10EZ1-T	10m	

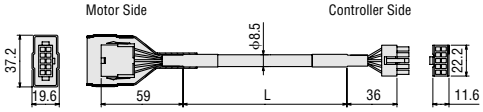
●Dimensions unit: mm

Motor Cable

CC□□EZ1-M

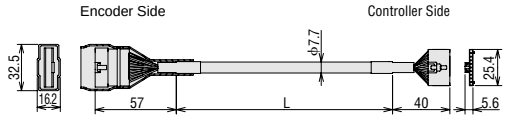


CC□□EZ2-M



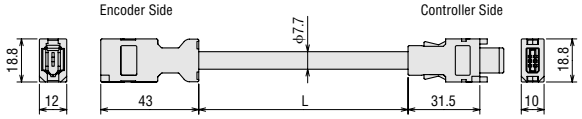
Encoder Cable

CC□□EZ1-E



Actuator Communication Cable

CC□□EZ1-T



■Flexible Cable Set

Common

Use flexible cables in applications where the cables will flex repeatedly.
As with the cable set, flexible cables are available in three lengths of 2 m, 5 m and 10 m. The cables may be purchased individually or as a set.
The same cable can be used for both the electromagnetic brake type and non-electromagnetic brake type.

Model	Length (L)	Applicable Products
CC02EZ1R	2m	**EZS** Series **EZC** Series
CC05EZ1R	5m	
CC10EZ1R	10m	
CC02EZ2R	2m	**EZHS** Series
CC05EZ2R	5m	**EZHC** Series
CC10EZ2R	10m	**EZHP** Series

●Individual Flexible Motor Cable

Model	Length (L)	Applicable Products
CC02EZ1R-M	2m	**EZS** Series **EZC** Series
CC05EZ1R-M	5m	
CC10EZ1R-M	10m	
CC02EZ2R-M	2m	**EZHS** Series
CC05EZ2R-M	5m	**EZHC** Series
CC10EZ2R-M	10m	**EZHP** Series

●Individual Flexible Encoder Cable, Flexible Actuator Communication Cable

Type of Cable	Model	Length (L)	Applicable Products
Flexible Encoder Cable	**CC02EZ1R-E**	2m	**EZS** Series **EZC** Series
	CC05EZ1R-E	5m	
	CC10EZ1R-E	10m	
Flexible Actuator Communication Cable	**CC02EZ1R-T**	2m	**EZHS** Series **EZHC** Series **EZHP** Series
	CC05EZ1R-T	5m	
	CC10EZ1R-T	10m	

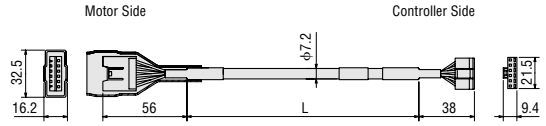
Common Can be used with all series.

EZS EZHS EZC EZHC EZHP Used only with the specified series.

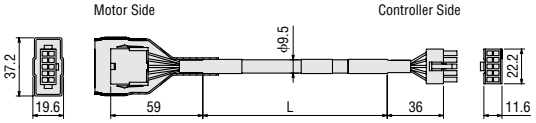
●Dimensions unit: mm

Flexible Motor Cable

CC□□EZ1R-M

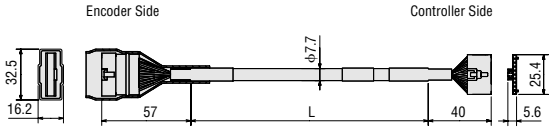


CC□□EZ2R-M



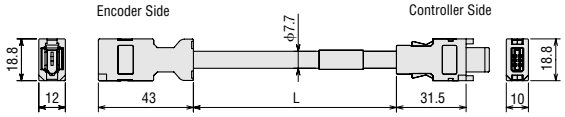
Flexible Encoder Cable

CC□□EZ1R-E



Flexible Actuator Communication Cable

CC□□EZ1R-T



■ Controller Link Cable

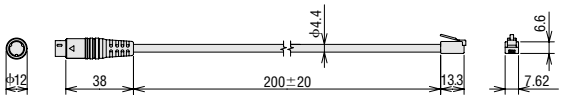
Common

Use these dedicated cables to link the **EZ limo** controllers.

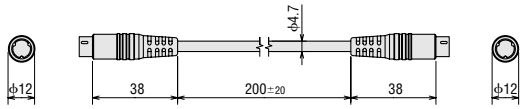
Model	Length (L)	Applicable Products
CC002EZ1-L	0.2m	**EZS** Series **EZC** Series
CC002EZ2-L	0.2m	**EZHS** Series **EZHC** Series **EZHP** Series

●Dimensions unit: mm

CC002EZ1-L



CC002EZ2-L



■ I/O Cable

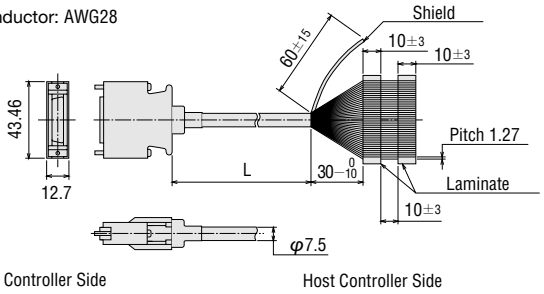
Common

These cables are used exclusively for connection between the **EZ limo** controller and the host controller.
A half-pitch connector allowing one-touch connection to the controller is attached at one end of the flat cable.

Model	Length (L)
CC36D1-1	1m
CC36D2-1	2m

●Dimensions unit: mm

Conductor: AWG28



■ Sensor Cable

Common

Use these cables to connect the sensors used in the controller mode to the controller.

CC02EZ1-S

CC20D□-1

Model	Length (L)	Applicable Products
CC02EZ1-S	2m	**EZS** Series **EZC** Series
CC20D1-1	1m	**EZHS** Series **EZHC** Series **EZHP** Series
CC20D2-1	2m	

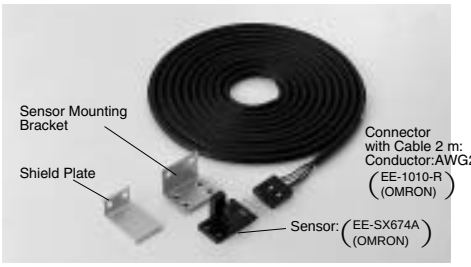
Optional Parts (sold separately)

■ Sensor Set PAEZ-S

Common

These sensors can be used in the controller mode or driver mode. The sensor set consists of three sets of a sensor, a sensor mounting bracket and a cable with connector. The fittings, screws and other parts needed for installation are also provided.

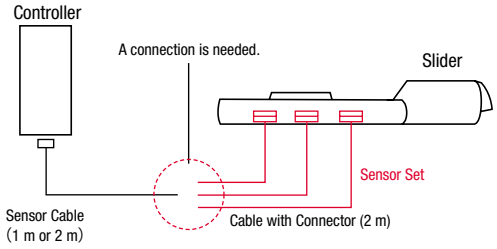
* In the driver mode, connect the sensors to the controller you have provided.



●Specifications

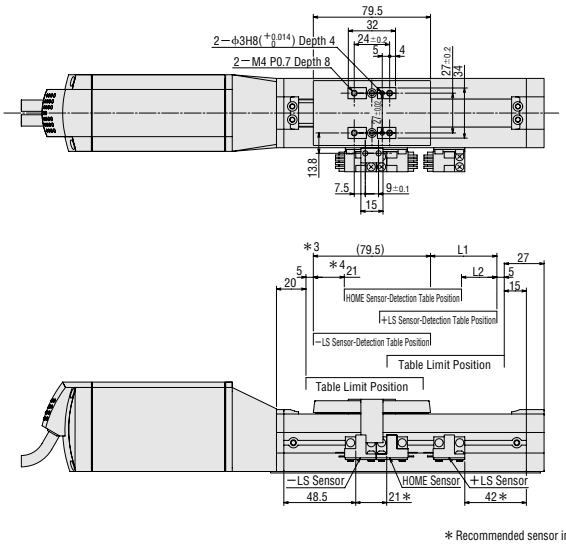
Model	EE-SX674A (Omron)
Power Supply	5 to 24 VDC ± 10%, ripple (P-P) 10% or less
Current Consumption	35 mA or less
Control Output	NPN open-collector output, 5 to 24 VDC, 100 mA or less Residual voltage 0.8 V or less (at load current of 100 mA)
Indicator Lamp	Detection display (red)
Sensor Logic	Normal open/Normal closed (switchable, depending on connection)

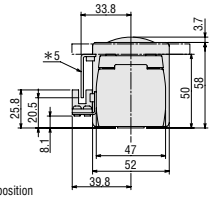
●Connection Example (controller mode)



●Example of Sensor Installation (for the slider only)

EZS3·EZHS3



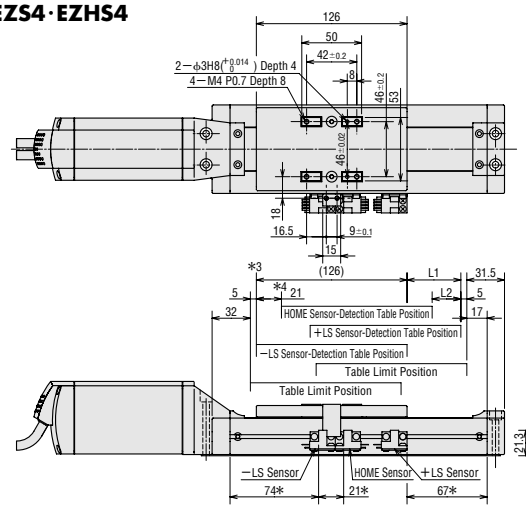


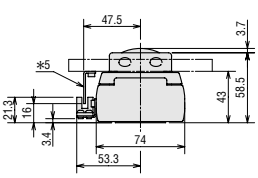
∗ Recommended sensor installation position

Slider Model		∗1 L1	∗2 L2
EZS3-05	EZHS3A-05	45	—
EZS3-05M	EZHS3A-05M		
EZS3-10	EZHS3A-10	95	74
EZS3-10M	EZHS3A-10M		
EZS3-15	EZHS3A-15	145	124
EZS3-15M	EZHS3A-15M		
EZS3-20	EZHS3A-20	195	174
EZS3-20M	EZHS3A-20M		
EZS3-25	EZHS3A-25	245	224
EZS3-25M	EZHS3A-25M		
EZS3-30	EZHS3A-30	295	274
EZS3-30M	EZHS3A-30M		
EZS3-40	EZHS3A-40	395	374
EZS3-40M	EZHS3A-40M		
EZS3-50	EZHS3A-50	495	474
EZS3-50M	EZHS3A-50M		

∗1 L1 indicates the effective stroke when two sensors are used.
∗2 L2 indicates the effective stroke when three sensors are used. The EZS3-05 (M) and EZHS3-05 (M) do not accommodate the use of three sensors.
∗3 Home position when two sensors are used.
∗4 Home position when three sensors are used.
∗5 Install the shield plate onto the work. (Use the two supplied mounting screws: M3 x 5 mm.)

EZS4·EZHS4





∗ Recommended sensor installation position

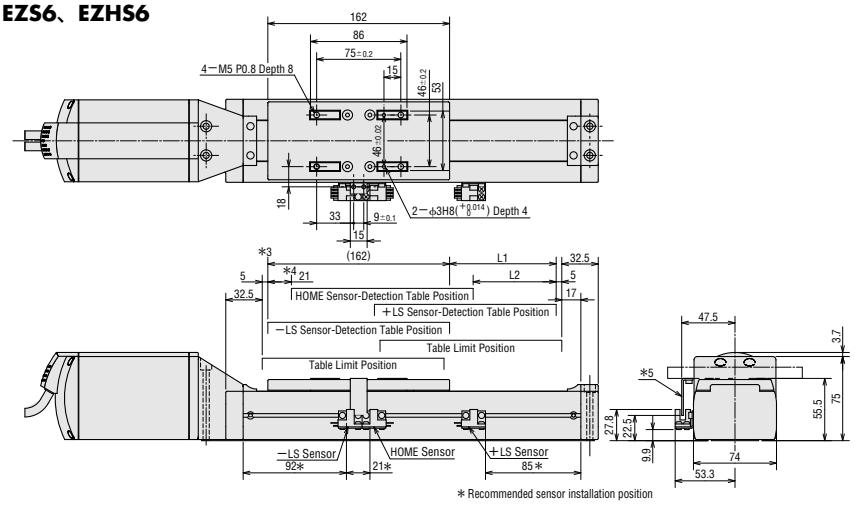
Slider Model		∗1 L1	∗2 L2
EZS4-05	EZHS4A-05	45	—
EZS4-05M	EZHS4A-05M		
EZS4-10	EZHS4A-10	95	74
EZS4-10M	EZHS4A-10M		
EZS4-15	EZHS4A-15	145	124
EZS4-15M	EZHS4A-15M		
EZS4-20	EZHS4A-20	195	174
EZS4-20M	EZHS4A-20M		
EZS4-25	EZHS4A-25	245	224
EZS4-25M	EZHS4A-25M		
EZS4-30	EZHS4A-30	295	274
EZS4-30M	EZHS4A-30M		
EZS4-40	EZHS4A-40	395	374
EZS4-40M	EZHS4A-40M		
EZS4-50	EZHS4A-50	495	474
EZS4-50M	EZHS4A-50M		

∗1 L1 indicates the effective stroke when two sensors are used.
∗2 L2 indicates the effective stroke when three sensors are used. The EZS4-05 (M) and EZHS4-05 (M) do not accommodate the use of three sensors.
∗3 Home position when two sensors are used.
∗4 Home position when three sensors are used.
∗5 Install the shield plate onto the work. (Use the two supplied mounting screws: M3 x 5 mm.)

Common Can be used with all series.

EZS EZHS EZC EZHC EZHP Used only with the specified series.

EZS6、EZHS6



＊Recommended sensor installation position

Slider Model		＊1 L1	＊2 L2
EZS6-10	EZHS6□-10	95	74
EZS6-10M	EZHS6□-10M		
EZS6-15	EZHS6□-15	145	124
EZS6-15M	EZHS6□-15M		
EZS6-20	EZHS6□-20	195	174
EZS6-20M	EZHS6□-20M		
EZS6-25	EZHS6□-25	245	224
EZS6-25M	EZHS6□-25M		
EZS6-30	EZHS6□-30	295	274
EZS6-30M	EZHS6□-30M		
EZS6-40	EZHS6□-40	395	374
EZS6-40M	EZHS6□-40M		
EZS6-50	EZHS6□-50	495	474
EZS6-50M	EZHS6□-50M		

＊1 L1 indicates the effective stroke when two sensors are used.
＊2 L2 indicates the effective stroke when three sensors are used.
＊3 Home position when two sensors are used.
＊4 Home position when three sensors are used.
＊5 Install the shield plate onto the work.
(Use the two supplied mounting screws: M3 x 5 mm.)

■ Dual Axis Mounting Bracket

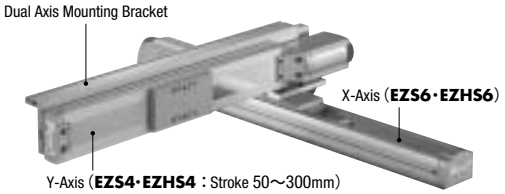
EZS EZHS

This dual axis mounting bracket allows easy installation of a pair of sliders. Various types of brackets are available to support combinations of X-Y and X-Z axes.

●Installation Example

Use **EZS6** or **EZHS6** for the X-axis and **EZS4** or **EZHS4** (stroke: 50 to 300 mm) for the Y- or Z-axis.

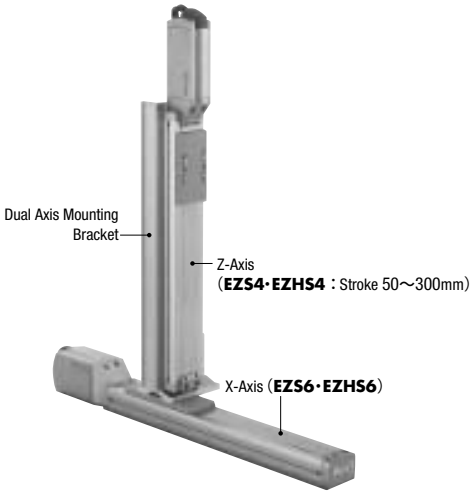
◇ X-Y Configuration



●X-Y Bracket

Y–Axis Stroke	Model
50mm	**PAB-EZ64Y05**
100mm	**PAB-EZ64Y10**
150mm	**PAB-EZ64Y15**
200mm	**PAB-EZ64Y20**
250mm	**PAB-EZ64Y25**
300mm	**PAB-EZ64Y30**

◇ X-Z Configuration



●X-Z Bracket

Z–Axis Stroke	Model
50mm	**PAB-EZ64Z05**
100mm	**PAB-EZ64Z10**
150mm	**PAB-EZ64Z15**
200mm	**PAB-EZ64Z20**
250mm	**PAB-EZ64Z25**
300mm	**PAB-EZ64Z30**

Optional Parts (sold separately)

◇Maximum Transportable Mass in Dual Axis Configuration

●Maximum Transportable Mass in X-Y Configuration

Unit: kg

Applicable Products	Speed Range		Y–Axis Stroke					
	X–Axis	Y–Axis	50mm	100mm	150mm	200mm	250mm	300mm
EZS	300mm/s	300mm/s	4.3	4.0	3.6	3.3	3.0	2.6
	200mm/s	300mm/s	5.0					
		200mm/s	10.0		9.2	7.8	6.6	5.6
		100mm/s	13.5	11.1				
EZHS	800mm/s	800mm/s	13.5	11.1	9.2	7.8	6.6	5.6

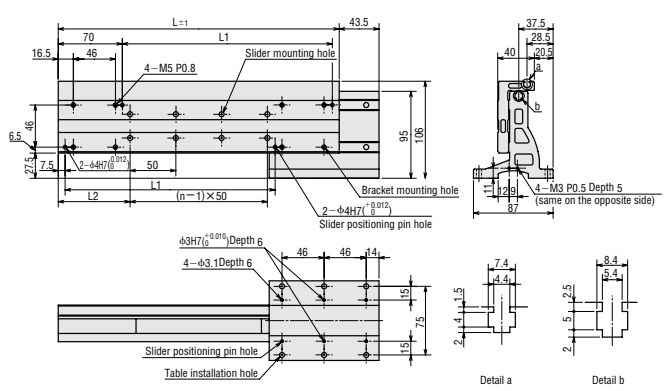
●Maximum Transportable Mass in X-Z Configuration

Unit: kg

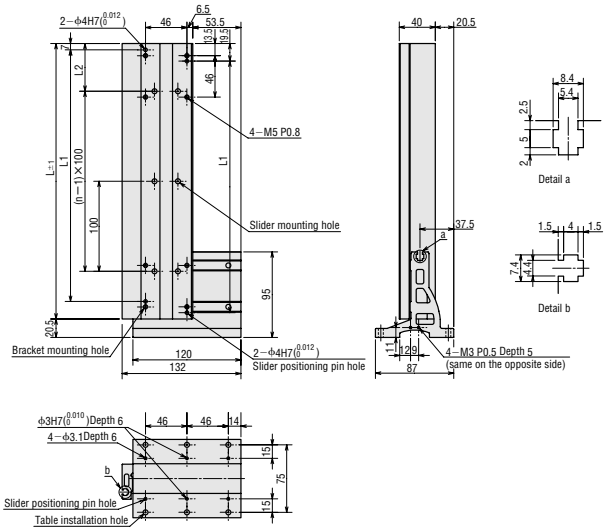
Applicable Products	Speed Range		Z–Axis Stroke					
	X–Axis	Z–Axis	50mm	100mm	150mm	200mm	250mm	300mm
EZS	300mm/s	300mm/s	2.0					
		200mm/s	4.0		3.8	3.4	3.1	2.7
		100mm/s	4.4	4.1				
	200mm/s	300mm/s	2.0					
		200mm/s	4.0					
		100mm/s	4.5					
EZHS	800mm/s	800mm/s	3.5					
		600mm/s	4.5					
		400mm/s	7.5					

◇Dimensions unit: mm

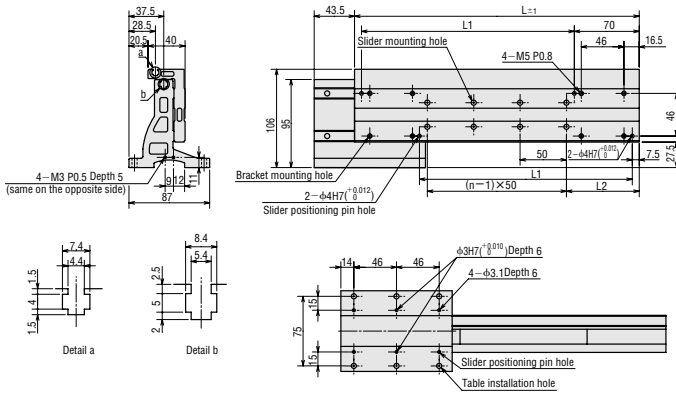
X-Y Configuration 1



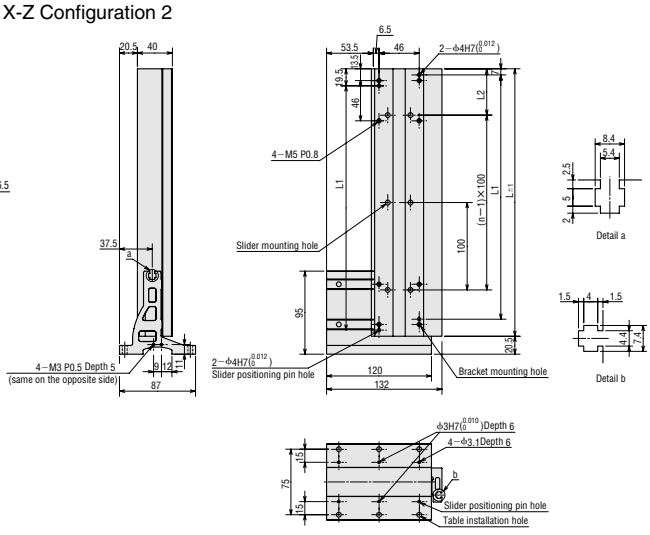
X-Z Configuration 1



X-Y Configuration 2



X-Z Configuration 2



Model	L	L1	L2	n	Mass(kg)
PAB-EZ64Y05	307	229.5	78.5	4	1.62
PAB-EZ64Y10	357	279.5	53.5	6	1.75
PAB-EZ64Y15	407	329.5	78.5	6	1.88
PAB-EZ64Y20	457	379.5	53.5	8	2.01
PAB-EZ64Y25	507	429.5	78.5	8	2.14
PAB-EZ64Y30	557	479.5	53.5	10	2.27

Model	L	L1	L2	n	Mass(kg)
PAB-EZ64Z05	256	229.5	78	2	1.51
PAB-EZ64Z10	306	279.5	53	3	1.64
PAB-EZ64Z15	356	329.5	78	3	1.78
PAB-EZ64Z20	406	379.5	53	4	1.91
PAB-EZ64Z25	456	429.5	78	4	2.05
PAB-EZ64Z30	506	479.5	53	5	2.18

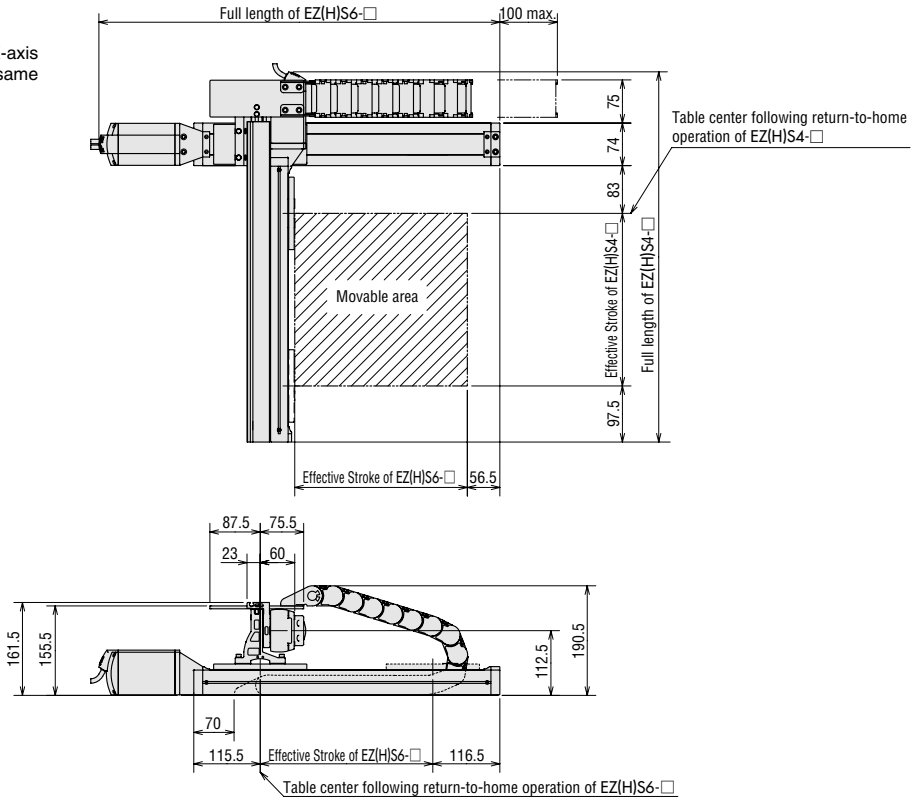
Common Can be used with all series.

EZS EZHS EZC EZHC EZHP Used only with the specified series.

◇Operating Range unit: mm

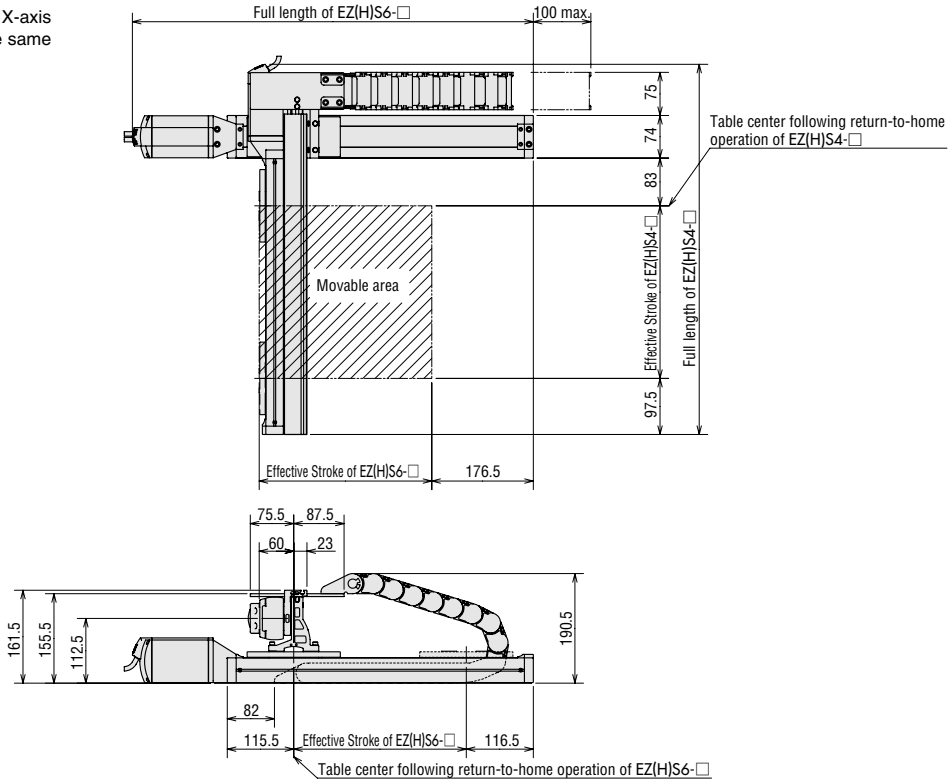
X-Y Configuration Pattern 1

*The Y-axis can be installed symmetrically to the X-axis either on its right or left. The moving range is the same on both sides.



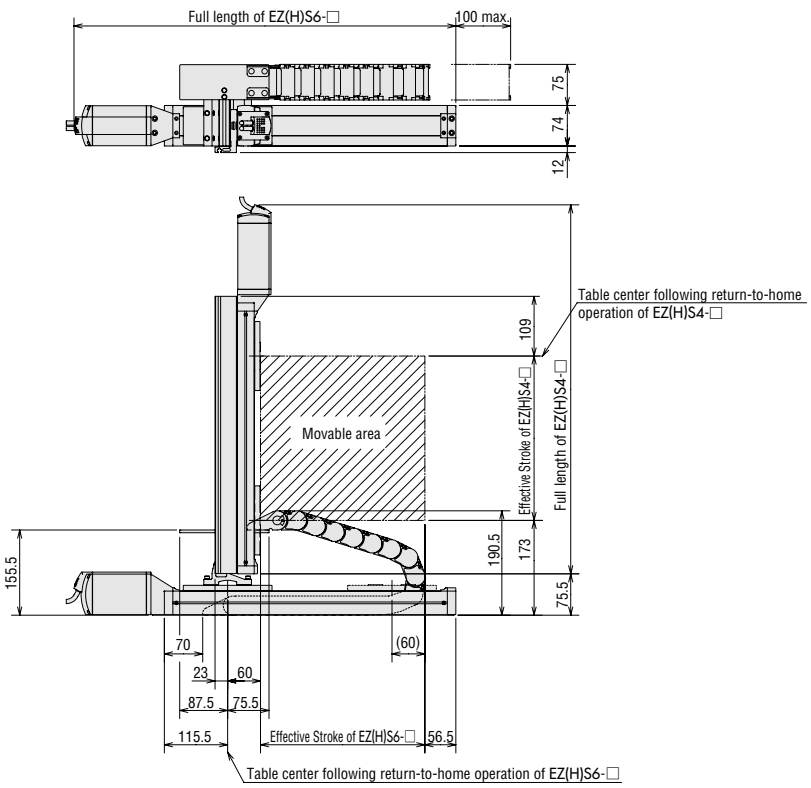
X-Y Configuration Pattern 2

*The Y-axis can be installed symmetrically to the X-axis either on its right or left. The moving range is the same on both sides.

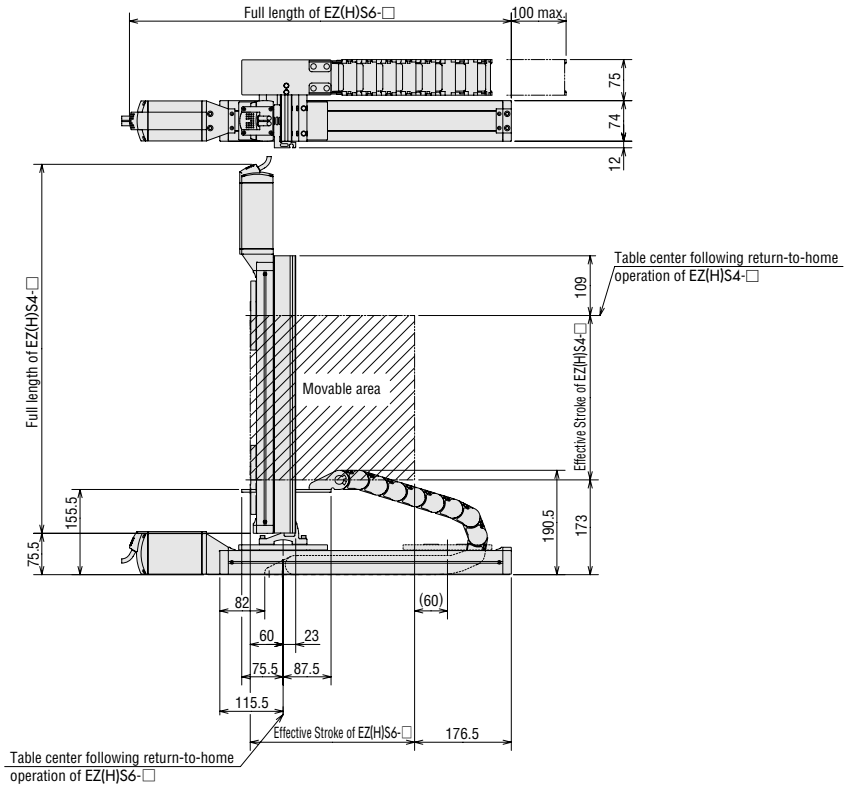


Optional Parts (sold separately)

X-Z Configuration Pattern 1



X-Z Configuration Pattern 2



Common Can be used with all series.

EZS EZHS EZC EZHC EZHP Used only with the specified series.

■ Cable Holder EZS EZHS

This low-noise cable holder protects and guides cables in multi-axis configurations. It can be easily installed on a dual axis mounting bracket using the supplied brackets.

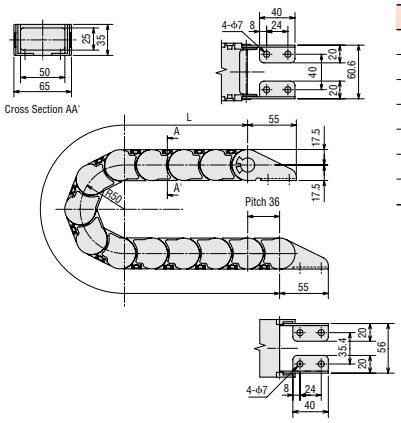
Stroke	Model
100mm	**PACH65-13**
150mm	**PACH65-14**
200mm	**PACH65-15**
250mm	**PACH65-17**
300mm	**PACH65-18**
400mm	**PACH65-21**
500mm	**PACH65-24**

●Specifications

Model		PACH65-□						
		13	14	15	17	18	21	24
Minimum Bending Radius	mm	50						
Maximum Cable Hose Diameter	mm	20						
Maximum Cable Hose Mass	kg/m	6.5						
Mass※	kg	0.70	0.74	0.77	0.83	0.86	0.96	1.06
Ambient Temperature Range		−10℃～+80℃						
Ambient Environment		Avoid use in an acid or alkaline ambience or in hot water.						

*The figures include the weight of brackets used for installation on the dual axis mounting bracket.

●Dimensions unit: mm



Model	L
PACH65-13	468
PACH65-14	504
PACH65-15	540
PACH65-17	612
PACH65-18	648
PACH65-21	756
PACH65-24	864

■ Cylinder Flange EZC EZHC EZHP

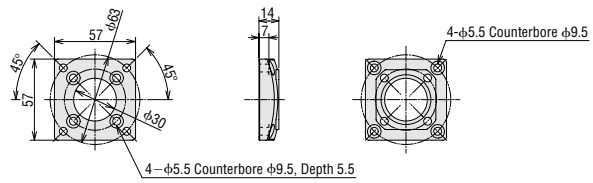
This special mounting bracket is used to install the cylinder from the body side. The flange comes with the mounting screws for affixing the cylinder to the flange.

(The mounting screws must be provided for affixing the flange to the equipment.)

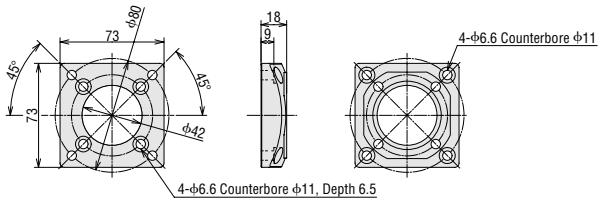
Model	Applicable Products
PAEZ4-F	**EZC4, EZHC4, EZHP4**
PAEZ6-F	**EZC6, EZHC6, EZHP6**

●Dimensions unit: mm

PAEZ4-F



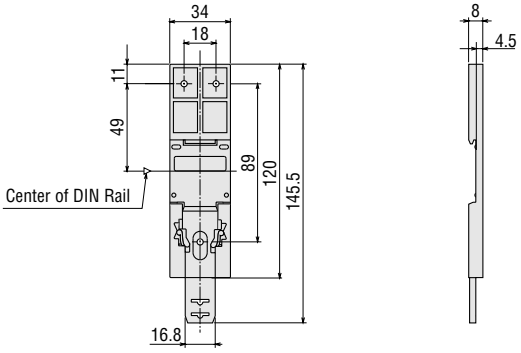
PAEZ6-F



■ DIN Rail Mounting Plate PADP01 EZS EZC

This plate is used to install the **EZ limo** controller to a DIN rail. The plate comes with the mounting screws.

●Dimensions unit: mm



The following spare parts are also available:

●Stainless Sheet for Slider EZS EZHS

Model	Stroke (mm)	Model	Stroke (mm)	Applicable Products
PAEZ3-05W	50	**PAEZ3-25W**	250	
PAEZ3-10W	100	**PAEZ3-30W**	300	**EZS3**
PAEZ3-15W	150	**PAEZ3-40W**	400	**EZHS3**
PAEZ3-20W	200	**PAEZ3-50W**	500	
PAEZ4-05W	50	**PAEZ4-25W**	250	
PAEZ4-10W	100	**PAEZ4-30W**	300	**EZS4**
PAEZ4-15W	150	**PAEZ4-40W**	400	**EZHS4**
PAEZ4-20W	200	**PAEZ4-50W**	500	
PAEZ6-10W	100	**PAEZ6-30W**	300	
PAEZ6-15W	150	**PAEZ6-40W**	400	**EZS6**
PAEZ6-20W	200	**PAEZ6-50W**	500	**EZHS6**
PAEZ6-25W	250	—	—	—

●Battery

Model	Applicable Products
PAEZ-BT	**EZS・EZC**Series
PAEZ-BT2	**EZHS・EZHC・EZHP**Series

*The spare battery does not come with a battery holder.

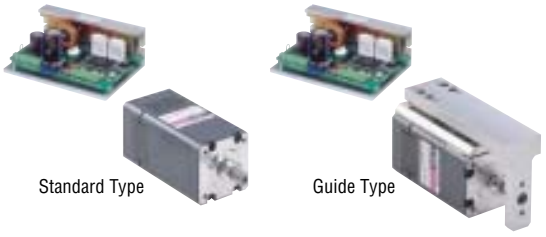
EZ limo absolute type uses Ni-Cd rechargeable batteries. Disposal of the used batteries is subject to each country's regulations on environmental control. Please contact Oriental Motor if you have any questions regarding disposal of the batteries.

Oriental Motor offers a full line of linear-motion products, including the **DRL** series and **LH** series.

We can help you design a more convenient and user-friendly operating environment that meets your various requirements. Please consult us for further details.

Compact Actuator
DRL Series

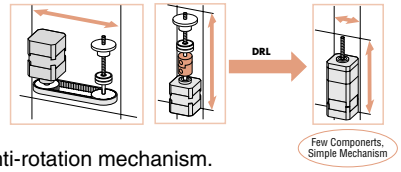
The **DRL** Series of compact linear motion actuators use a new 5-phase stepping motor which incorporates a ball screw. These are combined with 5-phase 24 VDC microstepping drivers with photocoupler inputs for extremely precise positioning.



● Compact Design

The compact design of the **DRL** actuator allows for the elimination of extra parts such as couplings, belts and pulleys.

The **DRL** actuator is a self-contained package consisting of a stepping motor with a hollow shaft rotor connected to a ball screw nut. Rotation of the nut initiates movement of the actual ball screw.



To enable linear motion of the screw on an actuator without a guide, provide an external anti-rotation mechanism.

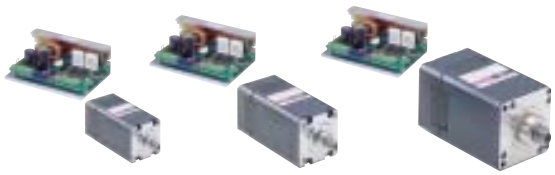
● Microstepping Drivers

The driver features a microstepping mechanism that electronically divides the basic step angle of the motor, thus enabling high resolution and low-vibration operation at low speeds.

● Reliable Design and Structure

The drive mechanism employs a 5-phase stepping motor with ball screw. The hollow rotor shaft incorporates large bore bearings for the direct handling of thrust loads. Minimizing the number of parts involved in linear conversion results in higher reliability.

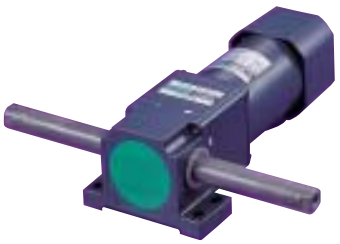
■ Product Line



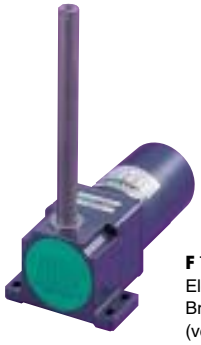
Rolled Ball Screw Repetitive Positioning Accuracy ±0.00079 inch (±0.02 mm)	**DRL28PA1-03D**	**DRL42PA2-04D**	**DRL60PA4-05D**	**DRL28PA1G-03D**	**DRL42PA2G-04D**	**DRL60PA4G-05D**
Ground Ball Screw Repetitive Positioning Accuracy ±0.00039 inch (±0.01 mm)	**DRL28PB1-03D**	**DRL42PB2-04D**	—	**DRL28PB1G-03D**	**DRL42PB2G-04D**	—
Motor Frame Size	28 mm sq.	42 mm sq.	60 mm sq.	28 mm sq.	42 mm sq.	60 mm sq.
Maximum Thrust Force	30 N	100 N	300 N	30 N	100 N	300 N
Type	**Standard Type**			**Guide Type**		

Linear Heads
LH Series

The **LH** Series of linear heads with a rack-and-pinion mechanism are coupled with standard AC compact motors. They easily produce linear motion for applications pressing and reversing.



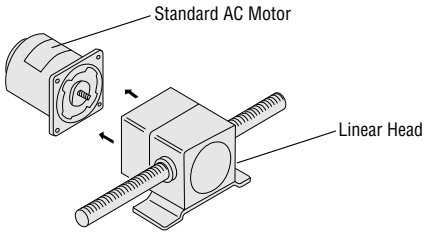
B Type
Reversible Motors (horizontal)
(The motor shown in the photograph is sold separately.)



F Type
Electromagnetic
Brake Motors
(vertical)

● Wide Variety

A wide variety of linear heads are available, depending on basic speed, length of rack, maximum transportable mass, direction of rack movement in respect to the mounting face etc.



■ Types of Linear Heads

Linear Head Type	Basic Speed (mm/s)*2				Max. Transportable Mass*3 kg	Rack Stroke (mm)						
	6	12	24	54		100	200	300	400	500	600	700
0L	●	●	●	—	10	●	●	—	—	—	—	—
2L*1	—	●	●	●	20	●	●	●	●	●	—	—
4L	—	●	●	●	70	●	●	●	●	●	●	●
5L-U	—	●	●	●	140	●	●	●	●	●	●	●

*1 The basic speed of **2L** type is 12 mm/s, 30 mm/s, 60 mm/s.
*2 Basic speed is based on the synchronous speed (1800 r/min at 60Hz). The actual speed varies with the load or power supply frequency.
*3 The maximum transportable mass is determined by the strength of the linear head. Just as when connecting a gearhead to a motor, increasing the gear ratio (reducing the speed) generates greater transportable mass, but the motor should always be operated below the maximum permissible transportable mass. The maximum transportable mass is the value when operating the rack in a horizontal direction. When operating in a vertical direction, subtract the mass of the rack from the value. The maximum transportable mass is the value when combined with a reversible motor. The value varies with basic speed.

This product is manufactured at a plant certified with the international standards **ISO 9001** (for quality assurance) and **ISO 14001** (for systems of environmental management).

Specifications are subject to change without notice.
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